Simulating Complex Flows with a Parallel Lattice Boltzmann Method U. Rüde (LSS Erlangen, ruede@cs.fau.de)

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### Overview

- Motivation: How fast are computers today (and tomorrow)
  - and what we might want to do with them
- How fast should our Solvers be
  - Scalable Parallel Multigrid Algorithms for PDE
  - Matrix-Free Multigrid FE solver: Hierarchical Hybrid Grids (HHG)
- A Multi-Scale & Multi-Physics Simulation (with grain size resolution)
  - Rigid Body Dynamics for Granular Media
  - Flow Simulation with Lattice Boltzmann Methods
    - free surface flows
  - Fluid-Structure Interaction with Moving Rigid Objects
    - particle ladden flows
- Towards a Systematic Perfomance Engineering
  - GPU performance comparison
- Conclusions



### **Motivation**









#### What can we do with Exa-Scale Computers (1)?

- The *recirculatory system* contains
  - ca. 0.006 m<sup>3</sup> volume
    - discretize with 10<sup>12</sup> finite volumes
    - mesh size of 0.02 mm
    - 10<sup>6</sup> operations per second and per volume.
  - ca. 2.5 ×10<sup>13</sup> red blood cells
    - $4 \times 10^4$  flops per second and blood cell
- The brain has
  - ca. 10<sup>11</sup> Neurons
    - 10<sup>7</sup> flops per sec and neuron
  - ca. 0.0015 m<sup>3</sup> volume
    - discretize with 10<sup>14</sup> finite elements
    - resolve the brain with a mesh size ~0.0025 mm
    - 10<sup>4</sup> operations per second and per element.



#### What can we do with Exa-Scale Computers(2)?

#### Fluidized Bed

Even if we want

- to simulate a billion (10<sup>9</sup>)
   objects (particles): we can do a billion (10<sup>9</sup>) operations for each of them in each second
- a trillion (10<sup>12</sup>) finite elements (finite volumes) to resolve the flow between particles: we can do a million (10<sup>6</sup>) operations for each of them in each second



Fluidized Bed (movie: thanks to K.E. Wirth, Erlangen)

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### An Example of High Performance Multi-Scale and Multi-Physics Simulation







### Rigid Body Dynamics (aka "physics engines")



- Newton's Laws of Motion
  - including rotations
- Contact Detection
  - in each time step

- **Collisions modelled by** 
  - cofficient of restitution: forces in normal direction
  - (Coulomb) friction laws: forces in tangential direction

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#### **Collisions & Contacts between Rigid Objects**





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### **Parallel Rigid Body Dynamics**



No point masses, but volumetric, geometrically defined objects

- objects may (geometrically) extend across several processors
- Objects overlapping with process boundaries must be synchronized
- Objects are assigned logically to exactly one process
- Unique identifier from rank of the process and local counter



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#### **Granular Media Simulations**









#### Hourglass Simulation (1)



1250000 spherical particles, 256 CPUs, 300300 time steps, runtime: 48h (including data output)

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How far can we go? Scaling Results!				
# Cores	# Particles	Partitioning	Runtime [s]	
128	2000000	8 x 4 x 4	727.096	
256	4 000 000	8 x 8 x 4	726.991	
512	8 000 000	8 x 8 x 8	727.150	
1024	16000000	16 x 8 x 8	727.756	
2048	32000000	16 x 16 x 8	727.893	
4 0 9 6	64 000 000	16 x 16 x 16	728.593	
8 1 9 2	128000000	32 x 16 x 16	728.666	
16384	256000000	32 x 32 x 16	728.921	
32768	512000000	32 x 32 x 32	729.094	
65 536	1024000000	64 x 32 x 32	728.674	
131072	2048000000	64 x 64 x 32	728.320	

\* Jugene simulation results of 1000 time steps of a dense granular gas contained in an evacuated box without external forces. Computational Fluid Dynamics with the Lattice Boltzmann Method

Falling Drop with Turbulence Model (slow motion) ATTENZIONE PERICOLO POSSIBILITÀ DI ONDE DI PIENA IMPROVVISE ANCHE PER MANOVRE SU OPERE IDRAULICHE DANGER POSSIBILITY OF SUDDEN FLOOD WAVES ALSO BECAUSE OF MANOEUVRES ON HYDRAULIC PLANTS ATTENTION DANGER POSSIBILITÉ DE CRUES SOUDAINES A LA SUITE AUSSI DE MANOEUVRES SUR OUVRAGES HYDRAULIQUES ACHTUNG GEFAHR MÖGLICHKEIT PLÖTZLICHER FLUTWELLEN AUCH ZUFOLGE VON BETÄTIGUNG DER STAUDAMMSCHÜTZE

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#### **Computational Fluid Dynamics**

The flow modelling is based on the Navier-Stokes equations (here incompressible form)

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla p + \nu \Delta \mathbf{v} + \mathbf{f}.$$
$$\nabla \cdot \mathbf{v} = 0.$$

More recently, the Lattice Boltzmann method (LBM) has been developed as an alternative

$$\partial_t f(\vec{x}, \vec{v}, t) + \vec{v} \nabla_{\vec{x}} f(\vec{x}, \vec{v}, t) + \frac{\vec{F}}{m} \nabla_{\vec{v}} f(\vec{x}, \vec{v}, t) = \mathbf{I}_{\mathbf{c}}(f),$$



#### The Lattice-Boltzmann-Method

- Discretization in squares or cubes (cells)
- 9 numbers per cell (or 19 in 3D)
  - = number of particles traveling towards neighboring cells
- Repeat (many times)
  - stream
  - collide









#### The stream step

Move particle (numbers) into neighboring cells



a single cell at timestep t after collision



a single cell at timestep t+1 after streaming



four cells at timestep t after collision



four cells at timestep t+1 after streaming







#### The collide step

# Compute new particle numbers according to the collisions



FAU







Discretizing the Boltzmann Equation
$$\frac{\partial f}{\partial t} + \langle u, \nabla f \rangle = -\frac{1}{\tau} \left( f - f^{(0)} \right)$$
finite set  $\{v_i\}, 0 \leq i \leq n$ , of velocities $f_i(x,t) = f(x,v_i,t)$ discrete Boltzmann equation $\frac{\partial f_i}{\partial t} + \langle v_i, \nabla f_i \rangle = -\frac{1}{\tau} \left( f_i - f_i^{(0)} \right)$  $F_i(x + c_i \Delta t, t + \Delta t) - F_i(x, t) = -\frac{1}{\tau} \left( F_i(x, t) - F_i^{(0)}(x, t) \right)$ EXECCES



Steam/Collide:  

$$f_i(x + c_i\Delta t, t + \Delta t) - f_i(x, t) = -\frac{1}{\tau} \left( f_i(x, t) - f_i^{(0)}(x, t) \right)$$
Steam/Collide:  

$$f_i^{(0)}(x, t) = \frac{1}{3}\rho(x, t) \left( 1 - \frac{3}{2} \frac{\langle u(x, t), u(x, t) \rangle}{c^2} \right) \qquad \text{for } i = C,$$

$$f_i^{(0)}(x, t) = \frac{1}{18}\rho(x, t) \left( 1 + 3 \frac{\langle c_i, u(x, t) \rangle}{c^2} + \frac{9}{2} \frac{\langle c_i, u(x, t) \rangle^2}{c^4} - \frac{3}{2} \frac{\langle u(x, t), u(x, t) \rangle}{c^2} \right)$$

$$f_i^{(0)}(x, t) = \frac{1}{36}\rho(x, t) \left( 1 + 3 \frac{\langle c_i, u(x, t) \rangle}{c^2} + \frac{9}{2} \frac{\langle c_i, u(x, t) \rangle^2}{c^4} - \frac{3}{2} \frac{\langle u(x, t), u(x, t) \rangle}{c^2} \right)$$

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$$f_i^{(0)}(x, t) = \frac{1}{36}\rho(x, t) \left( 1 + 3 \frac{\langle c_i, u(x, t) \rangle}{c^2} + \frac{9}{2} \frac{\langle c_i, u(x, t) \rangle^2}{c^4} - \frac{3}{2} \frac{\langle u(x, t), u(x, t) \rangle}{c^2} \right)$$



### The Interface Between Liquid and Gas

- Volume-of-Fluids like approach
- Flag field: Compute only in fluid
- Special "free surface" conditions in interface cells



#### Curvature calculation (version I)



- Alternative approaches:
  - Integrate normals over surface (weighted triangles)
  - Level set methods (track surface as implicit function)





#### Walberla Software Framework



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### Computational Fluid Dynamics Lattice Boltzmann Method



- 1000 Bubbles
  - 510x510x530 =
     1.4 · 10<sup>8</sup> lattice cells
  - 70,000 time steps
  - 77 GB
  - 64 processes
  - 72 hours
  - 4,608 core hours
- Visualization

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- 770 images
- Approx. 12,000 core hours for rendering

Best Paper Award for Stefan Donath (LSS Erlangen) at ParCFD, May 2009 (Moffett Field, USA)





### Simulation of Metal Foams

- Example application:
  - Engineering: metal foam simulations
- **Based on LBM:** 
  - Free surfaces
  - Surface tension
  - Disjoining pressure to stabilize thin liquid films
  - Parallelization with MPI and load Balancing
- Collaboration with C. Körner (Dept. of Material Sciences, Erlangen)
- Other applications:
  - Food processing
  - Fuel cells









### Computational Fluid Dynamics Wetting Effects/Contact Angles



Department of Computer Science Chair for System Simulation University of Erlangen-Nürnberg



Stefan Donath and Ulrich Rüde Microdrops on hydrophobic surface between two hydrophilic stripes

December 2010

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#### Computational Fluid Dynamics for Fuel Cells Water Transport through Hydrophobic Fibers



### Fluid-Structure Interaction for particle ladden flows







#### Mapping Moving Obstacles into the LBM Fluid Grid

#### An Example



#### Mapping Moving Obstacles into the LBM Fluid Grid

#### An Example (2)



#### Cell change from didition

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#### Virtual Fluidized Bed



#### 512 processors

Simulation Domain Size: 180x198x360 cells of LBM

900 capsules and 1008 spheres = 1908 objects

Number time steps: 252,000

Run Time: 07h 12 min

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### Fluid-Structure Interaction with Free Surface and Moving Objects











#### Weak Scaling





### **Performance Engineering**

#### LBM on Clusters with GPUs









#### **Domain Partitioning and Parallelization**









### Pure LBM Performance on Tsubame 2

- MLUPS: Mega Lattice Updates per Seconds
- Pure LBM performance is limited by bandwidth
- Implementation in CUDA
- Scenario: Lid Driven Cavity

	NVIDIA Tesla M2050	Xeon X5670 "Westmere"	Factor
		2 sockets 12 cores	
Flops [ TFlop/s ]	1.0 / 0.5	0.25/0.13	x 4
Theoretical Peak Bandwidth [GB/s]	148	64	x 2-3
Stream Copy Bandwidth [GB/s]	100(+ECC)/ 115(-ECC)	43	x 2-3



#### Tsubame 2

- 1408 compute nodes equipped with GPUs
- 3 NVIDIA Tesla M2050 per node
- Peak performance:
  - 2.2 PFlop/s
  - 633 TB/s memory bandwidth
- Total performance: 2.4 PFlops/s
- 14<sup>th</sup> in the TOP500 list



- Located at Tokyo Institute of Technology, Japan
- Collaboration with Prof. Takayuki Aoki







### Single GPU and CPU Node Performance

- Performance estimates based in Stream bandwidth:
  - CPU: 142 MLUPS (ECC, DP, -BC)
  - GPU: 330 MLUPS (ECC, DP, -BC)
- Resulting performance 75 % of estimate (+BC)
- CPU Kernel:
  - **SSE** Intrinsics
  - Non-temporal stores
  - Padding
- GPU Kernel:
  - Register usage optimized
  - Memory layout: SoA
  - Padding



Kernels implemented by Johannes Habich







#### Weak Scaling Performance







#### Weak Scaling Performance







### Heterogeneous (GPU+CPU) LBM

- **Requirements:** 
  - Different data structures
  - Different kernels
  - Common communication interface
  - Load balancing
  - Node Setup:
    - I MPI Process per Core
    - I MPI Process per Socket
    - I MPI Process per Node







### **CPU vs GPU: LBM Implementation Effort**

- Subjective evaluation
- Valid for the pure LBM implementation
- Partly for stencil based methods

Difficulty	CPU	GPU
Kernel	**	*/***
Intra Node	*	**
Inter Node	**	***







#### Fluidization Heterogenous CPU-GPU Simulation



Particles: 31250 Domain: 400x400x200 Timesteps: 400 000 Devices: 2 x M2070 + 1 Intel "Westmere" Runtime: 17.5 h

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#### Fluidization: Weak Scaling on CPUs





#### Conclusions







#### Simulations with Fluid Control









# The Two Principles of Science Three

#### Theory

Mathematical Models, Differential Equations, Newton

### **Experiments**

Observation and prototypes

empirical Sciences

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#### **Computational Science**

Simulation, Optimization

(quantitative) virtual Reality

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## Thank you for your attention!



Slides, reports, thesis, animations available for download at: www10.informatik.uni-erlangen.de

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