

Fast techniques for the incompressible variable density Navier-Stokes equations

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Acknowledgments

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Texas A&M University



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1 Introduction



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2 Pressure-correction schemes for constant density



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5 Conclusion



Navier-Stokes equations



Claude L. M. H. Navier



George G. Stokes



Navier-Stokes equations



Claude L. M. H. Navier

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 & \text{in } \Omega \times [0, T], \\ \rho(\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u}) - \mu \nabla^2 \mathbf{u} + \nabla p = \mathbf{f} & \text{in } \Omega \times [0, T], \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \times [0, T], \\ \mathbf{u}|_{\Gamma} = 0 & \text{in } [0, T], \quad \text{and } \mathbf{u}|_{t=0} = \mathbf{u}_0 \quad \text{in } \Omega, \end{cases}$$



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George G. Stokes

- Ω fluid domain
- T some time
- f smooth source term
- u_0 smooth solenoidal data



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Hyp: $\Omega \subset \mathbb{R}^2$ or 3 is a bounded and smooth domain, and all compatibility conditions are satisfied for a smooth solution to exist.



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Strategy: Fractional time-stepping, Chorin–Temam idea (1968-1969).



Non-incremental pressure-correction schemes

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$$p^{k+1} = \phi^{k+1}$$



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- Step 2 amounts to

$$\tilde{u}^{k+1} = u^{k+1} + \nabla\left(\frac{\Delta t}{\rho}\phi^{k+1}\right), \quad u^{k+1} \in H, \quad \phi^{k+1} \in H^1(\Omega)$$



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- Implementation:

$$(i) \quad \nabla^2\phi^{k+1} = \frac{\rho}{\Delta t}\nabla \cdot \tilde{u}^{k+1}; \quad \partial_n\phi^{k+1}|_{\Gamma} = 0$$

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- Very simple algorithm** \Rightarrow **Very popular**



Non-incremental pressure-correction schemes

Theorem (Rannacher (1991), Shen (1992))

$$\|u_{\Delta t} - u_{\Delta t}\|_{\ell^\infty([L^2(\Omega)]^d)} + \|u_{\Delta t} - \tilde{u}_{\Delta t}\|_{\ell^\infty([L^2(\Omega)]^d)} \leq c(u, p, T) \Delta t,$$

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- Observe that $\nabla p^{k+1} \cdot n|_\Gamma = 0$ is enforced on the pressure.
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- Irreducible** splitting error of order $\mathcal{O}(\Delta t)$ \Rightarrow using higher-order time stepping does not improve the overall accuracy.



Incremental pressure-correction schemes

- **Simple idea:** use the old pressure p^k in the viscous step and correct the pressure appropriately afterwards (Goda (1979) Van Kan (1986)).



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- Again artificial bc: $\nabla p^{k+1} \cdot n|_\Gamma = \nabla p^k \cdot n|_\Gamma = \dots \nabla p^0 \cdot n|_\Gamma$.
- Time stepping can be replaced by any 2nd order A-stable stepping.



Rotational incremental pressure-correction schemes

- A new simple idea: use $\nabla^2 u = \nabla \nabla \cdot u - \nabla \times \nabla \times u$
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Sum viscous prediction + projection + use pressure correction:

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- This implies **consistent** equations for the pressure:

$$\nabla^2 p^{k+1} = f(t^{k+1}); \quad \partial_n p^{k+1}|_{\Gamma} = (f(t^{k+1}) - \nu \nabla \times \nabla \times u^{k+1}) \cdot n|_{\Gamma},$$



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The tangent component of u^{k+1} is still not correct! \Rightarrow
sub-optimality



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Theorem (Guermond-Shen (2006))

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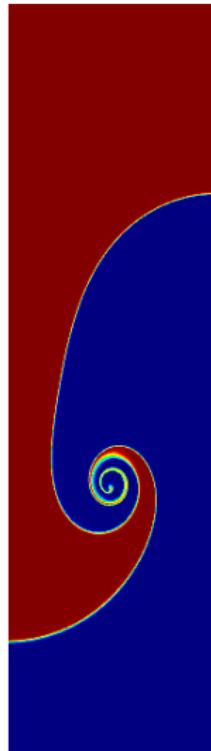
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- Brown, Cortez, Minion (2001) proved similar result in a periodic channel (Fourier analysis, 1D result).
- **OPEN QUESTION:** can we regain the missing $\Delta t^{\frac{1}{2}}$?



Variable density flows



The naive approach for variable density

- Use the same strategy as for constant density.
Viscous prediction + projection + pressure correction.



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- **All** The current splitting algorithms are based on this model!
- Only two proofs of stability available (Guermond-Quartapelle (2000), Pyo-Shen (2007)).



A new (old) idea

- Projection methods can also be interpreted as penalty techniques



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- Ex 1: Non-incremental pressure-correction equivalent to

$$\begin{cases} \rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) + \nabla p - \mu \nabla^2 \mathbf{u} = \mathbf{f}, & \mathbf{u}|_{\Gamma} = 0, \\ \nabla \cdot \mathbf{u} - \epsilon \nabla^2 \phi = 0, & \partial_n \phi|_{\Gamma} = 0, \quad p = \phi \end{cases}$$



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- Ex 2:** Incremental pressure-correction equivalent to

$$\begin{cases} \rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) + \nabla p - \mu \nabla^2 \mathbf{u} = \mathbf{f}, & \mathbf{u}|_{\Gamma} = 0, \\ \nabla \cdot \mathbf{u} - \epsilon \nabla^2 \phi = 0, & \partial_n \phi|_{\Gamma} = 0, \quad \epsilon p_t = \phi. \end{cases}$$



A new (old) idea

- Ex 3: Incremental rotational pressure-correction equivalent to

$$\begin{cases} \rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) + \nabla p - \mu \nabla^2 \mathbf{u} = \mathbf{f}, & \mathbf{u}|_{\Gamma} = 0, \\ \nabla \cdot \mathbf{u} - \epsilon \nabla^2 \phi = 0, & \partial_n \phi|_{\Gamma} = 0, \quad \epsilon p_t = \phi - \mu \nabla \cdot \mathbf{u}. \end{cases}$$



A new (old) idea

- **Ex 3:** Incremental rotational pressure-correction equivalent to

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- **The new idea:** Adopt the penalty point of view instead of the Helmholtz decomposition.



Non-incremental version

- Define $\rho_{\min} := \min_{x \in \Omega} \rho_0(x)$



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Non-incremental version

- Define $\rho_{\min} := \min_{x \in \Omega} \rho_0(x)$
- Choose parameter $\chi \in (0, \rho_{\min}]$.
- Initialize: Set $\rho^0 = \rho_0$, $\mathbf{u}^0 = \mathbf{u}_0$, $p^0 = 0$,



Non-incremental version

- Density

$$\frac{\rho^{n+1} - \rho^n}{\Delta t} + \nabla \cdot (\rho^{n+1} \mathbf{u}^n) - \frac{\rho^{n+1}}{2} \nabla \cdot \mathbf{u}^n = 0.$$



Non-incremental version

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- Velocity

$$\rho^n \frac{\mathbf{u}^{n+1} - \mathbf{u}^n}{\Delta t} + \rho^{n+1} (\mathbf{u}^n \cdot \nabla) \mathbf{u}^{n+1} - \mu \nabla^2 \mathbf{u}^{n+1} + \frac{\rho^{n+1}}{4} (\nabla \cdot \mathbf{u}^n) \mathbf{u}^{n+1} + \nabla p^n = \mathbf{f}^{n+1},$$



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- Pressure correction: $p^{n+1} = \phi^{n+1}$



Incremental version

Proposition

The algorithm is stable provided $\chi \leq \inf_{\mathbf{x} \in \Omega} \rho^0(\mathbf{x})$, for all $n \in \overline{0, N}$.



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- Velocity

$$\begin{aligned} & \frac{\rho^* \mathbf{u}^{n+1} - \rho^n \mathbf{u}^n}{\Delta t} + (\rho^{n+1} \mathbf{u}^n \cdot \nabla) \mathbf{u}^{n+1} - \mu \nabla^2 \mathbf{u}^{n+1} \\ & + \nabla \cdot \left(\frac{1}{2} \rho^* \mathbf{u}^n \right) \mathbf{u}^{n+1} + \nabla p^* = \mathbf{f}^{n+1}, \quad \tilde{\mathbf{u}}^{n+1}|_{\Gamma} = 0, \end{aligned}$$



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The fully discrete algorithm is stable provided $\chi \leq \inf_{\mathbf{x} \in \Omega} \rho^n(\mathbf{x})$, for all $n \in \overline{0, N}$, and the velocity space is conforming in \mathbf{H}_0^1 and the pressure space is conforming in H^1 .



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- Requires only to solve a **Poisson** problem!
- Error $\mathcal{O}(\Delta t)$ on velocity in \mathbf{H}^1 -norm and pressure in L^2 -norm.
- $p^n + \phi = 2p^n - p^{n-1}$: second-order extrapolation on pressure
 \Rightarrow second-order accuracy reachable.



Rotational incremental version + BDF2

- Velocity extrapolation $\mathbf{u}^* = 2\mathbf{u}^n - \mathbf{u}^{n-1}$.



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- Velocity

$$\begin{aligned} & \frac{3\rho^*\mathbf{u}^{n+1} - 4\rho^{n+1}\mathbf{u}^n + \rho^{n+1}\mathbf{u}^{n-1}}{2\Delta t} + \rho^{n+1}(\mathbf{u}^* \cdot \nabla) \mathbf{u}^{n+1} - \mu \nabla^2 \mathbf{u}^{n+1} \\ & + \left(\nabla \cdot \frac{\rho^*}{2} \mathbf{u}^* \right) \mathbf{u}^{n+1} + \nabla p^* = \mathbf{f}^{n+1}. \end{aligned}$$



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- Requires only to solve a **Poisson** problem!
- Algorithm formally $\mathcal{O}(\Delta t^2)$.



Numerical illustrations



Convergence tests

- Velocity \mathbb{P}_2 , pressure \mathbb{P}_1 , density \mathbb{P}_2

| Δt | Vel. L^2 | rate | Vel. H^1 | rate | Pre. L^2 | rate | Den. L^2 | rate |
|------------|------------|------|------------|------|------------|------|------------|------|
| 0.100000 | 3.90E-3 | | 1.63E-2 | | 1.25E-2 | | 1.25E-2 | |
| 0.050000 | 1.18E-3 | 1.73 | 5.03E-3 | 1.70 | 3.61E-3 | 1.79 | 2.93E-3 | 2.09 |
| 0.025000 | 3.35E-4 | 1.82 | 1.47E-3 | 1.77 | 1.00E-3 | 1.85 | 7.60E-4 | 1.95 |
| 0.012500 | 9.04E-5 | 1.89 | 4.13E-4 | 1.83 | 2.70E-4 | 1.89 | 2.08E-4 | 1.87 |
| 0.006250 | 2.37E-5 | 1.93 | 1.15E-4 | 1.84 | 7.10E-5 | 1.93 | 5.85E-5 | 1.83 |
| 0.003125 | 6.12E-6 | 1.95 | 3.17E-5 | 1.86 | 1.87E-5 | 1.93 | 1.67E-5 | 1.81 |

- Rotational incremental version + BDF2; *Smooth domains*: $(\mathcal{O}(\Delta t)^2)$ on velocity in \mathbf{L}^2 -norm, a little less in \mathbf{H}^1 -norm and pressure in L^2 -norm.

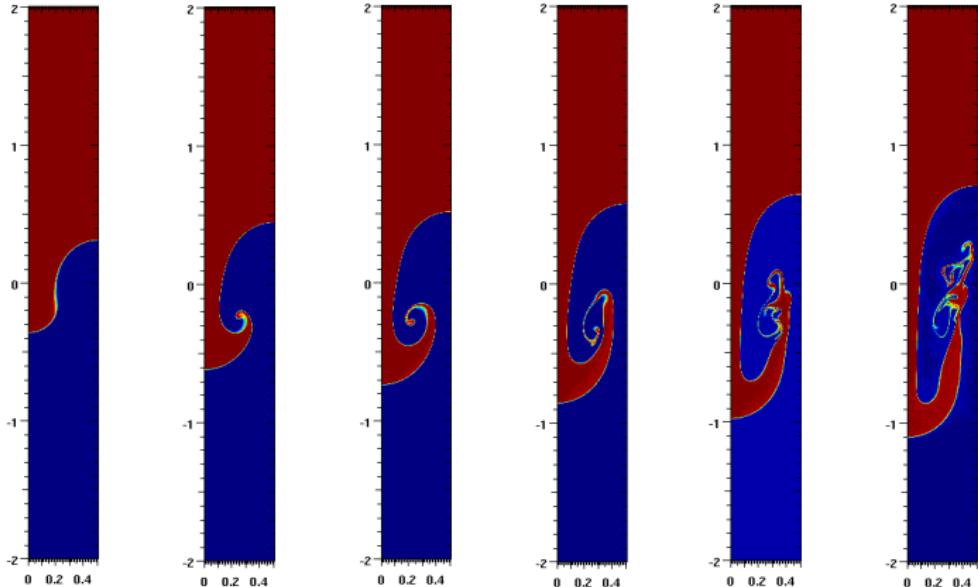


Convergence tests

- Rotational incremental version + BDF2; Non-smooth domains:
 $(\mathcal{O}(\Delta t)^2)$ on velocity in L^2 -norm, $(\mathcal{O}(\Delta t)^{\frac{3}{2}})$ on velocity in H^1 -norm and pressure in L^2 -norm.



Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 1000$

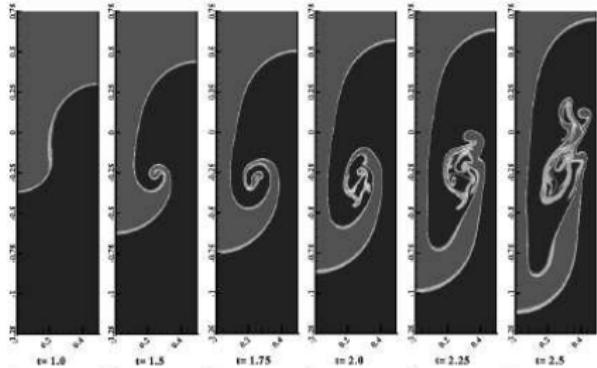


• $t = 1$ $t = 1.5$ $t = 1.75$ $t = 2$ $t = 2.25$ $t = 2.5$

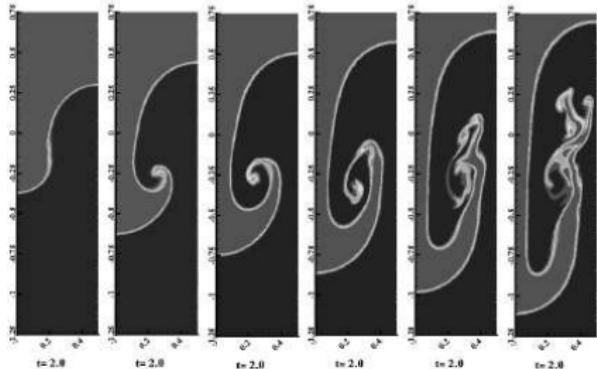
[movie](#)



Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 1000$



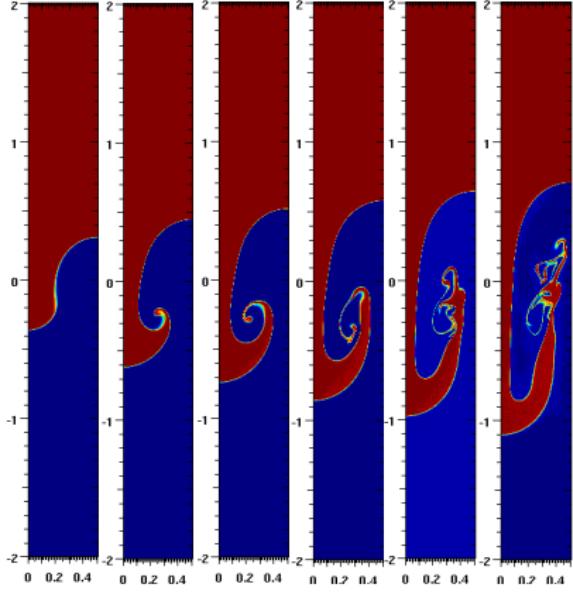
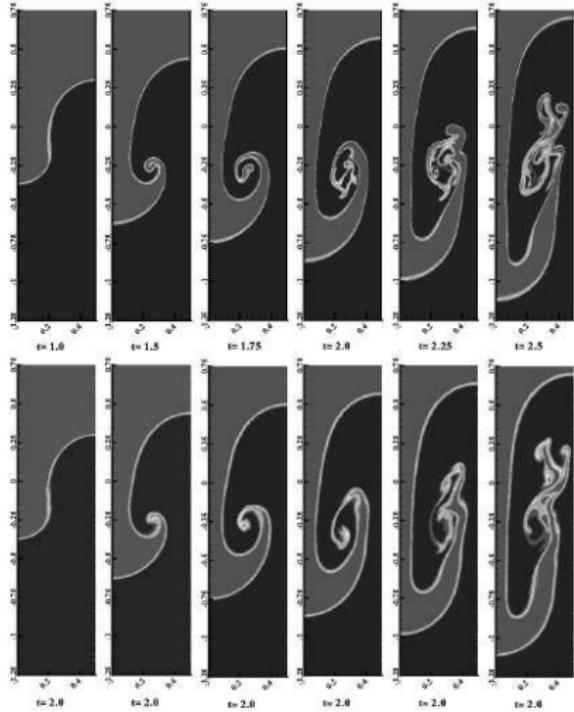
- Guermond, Fraigneau (2001)
Standard algorithm
Finite volume 256×512



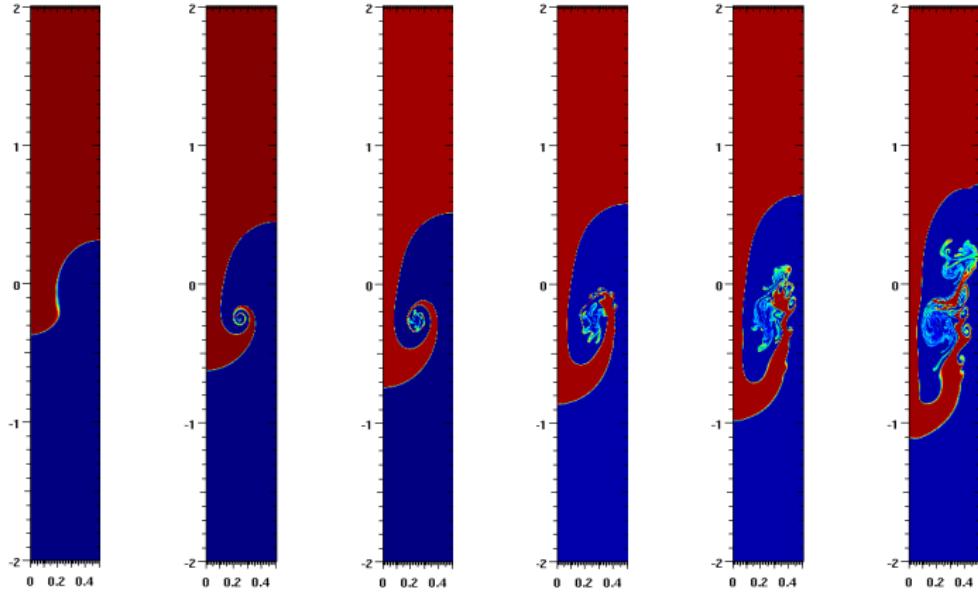
- Guermond, Fraigneau (2001)
Standard algorithm
Finite elements 30189
 \mathbb{P}_2 nodes



Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 1000$



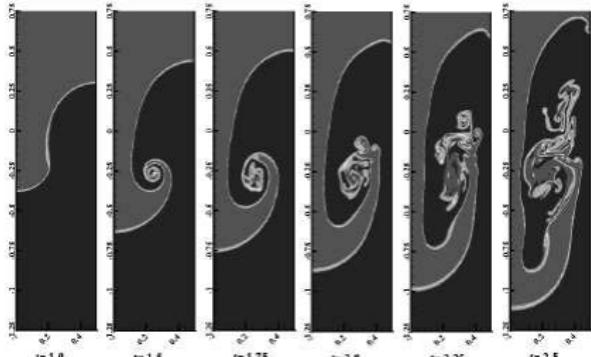
Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 5000$

 $t = 1$ $t = 1.5$ $t = 1.75$ $t = 2$ $t = 2.25$ $t = 2.5$

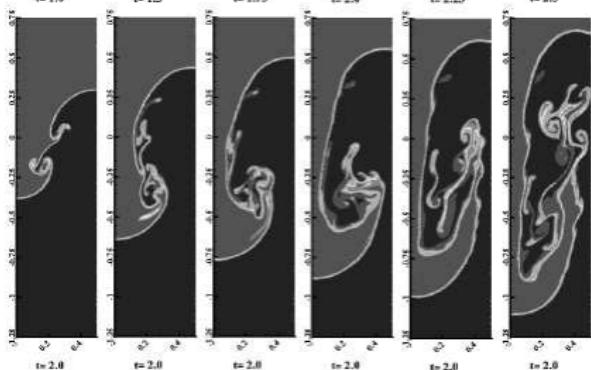
movie



Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 5000$



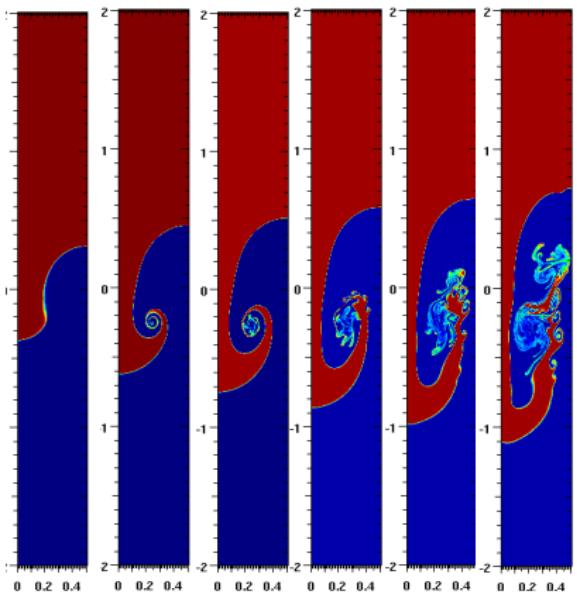
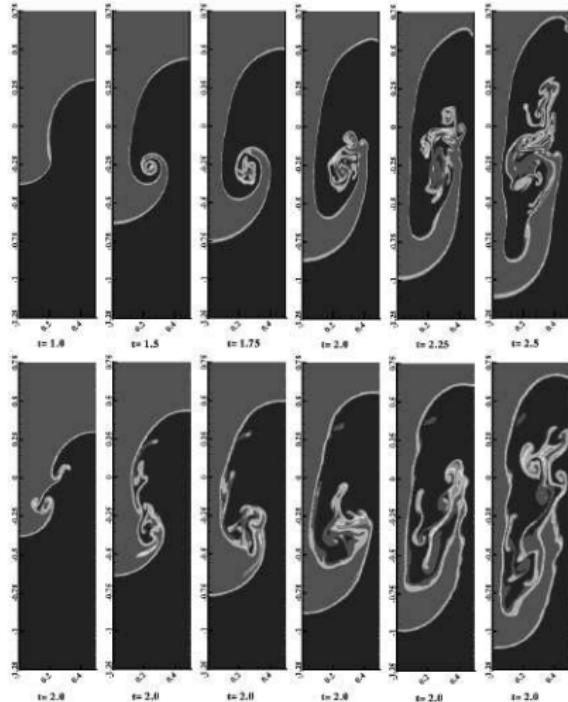
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Standard algorithm
Finite volume 256×512



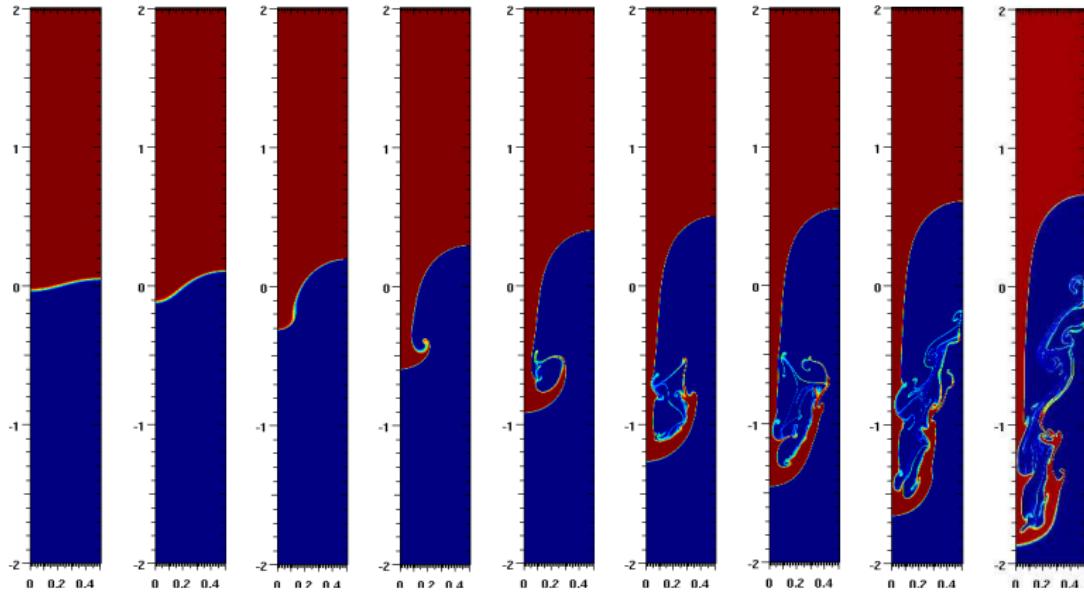
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 \mathbb{P}_2 nodes



Numerical illustrations. RT, $\rho_{\max}/\rho_{\min} = 3$, $R_e = 5000$



Numerical illustration. RT, $\rho_{\max}/\rho_{\min} = 7$, $R_e = 1000$

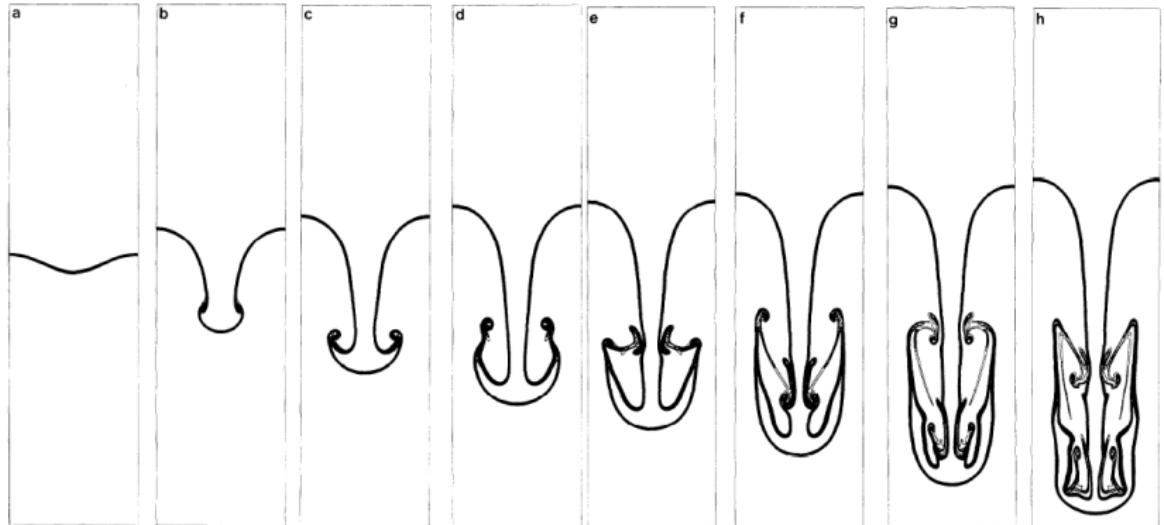


$t = 1, 1.5, 2, 2.5, 3, 3.5, 3.75, 4, 4.25$

movie



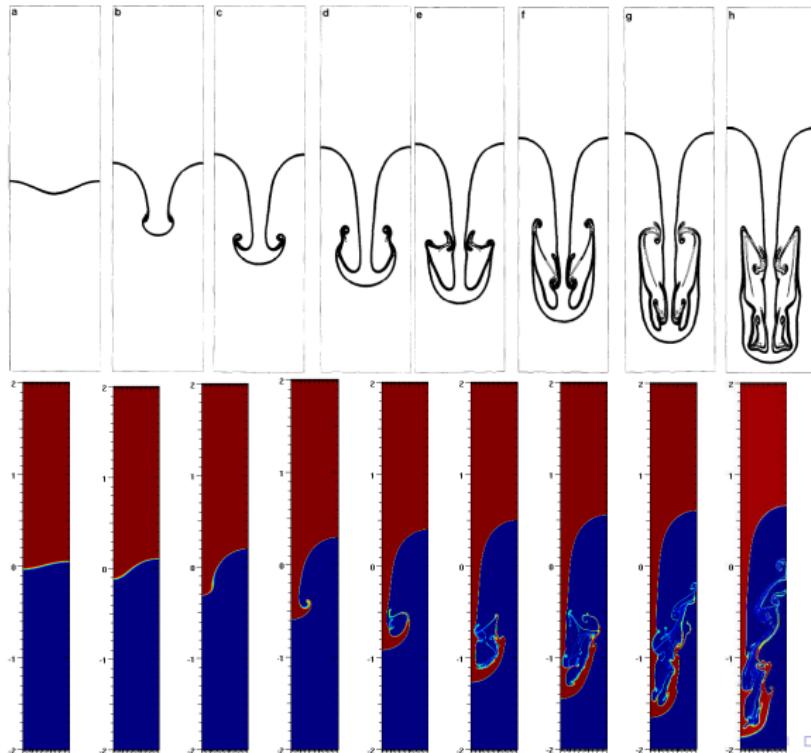
Numerical illustration. RT, $\rho_{\max}/\rho_{\min} = 7$, $R_e = 1000$



- $t = 1.5 \ t = 2 \ t = 2.5 \ t = 3 \ t = 3.5 \ t = 3.75 \ t = 4 \ t = 4.25$
- Bell, Marcus (1992), Standard algorithm, Finite volume
 200×800



Numerical illustration. RT, $\rho_{\max}/\rho_{\min} = 7$, $R_e = 1000$



Concluding remarks

- Splitting algorithms are **fast and easy** to implement.



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- Splitting algorithms are **fast and easy** to implement.
- **New fast splitting algorithm for solving variable density flows:**
solve $\nabla^2 \phi = \psi$ instead of $\nabla \cdot (\frac{1}{\rho} \nabla \phi) = \psi$.
- Stability proven up to second-order time stepping.
Convergence analysis coming soon.



Open issues

- Can splitting schemes do well with open BCs?



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Open issues

- Can splitting schemes do well with open BCs?
- Does there exist a splitting scheme that is fully $\mathcal{O}(\Delta t^2)$ in non-smooth domains?
- Be **suspicious** about any splitting method that claims convergence order (in H^1 -norm) $> \mathcal{O}(\Delta t^{\frac{3}{2}})$.

