Some numerical strategies to be improved for controlled fusion designed.

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Inertial Confinement Fusion : Compression Ignition



- Interfaces flow
- Large ratio computational domain change.

Needs : Lagrangian Hydrodynamics Scheme...

• Ignition by X-rays compression



Needs : Compute Focusing Beams interactions...

Inertial Confinement Fusion : Fast laser ignition



Need : Nonlinear laser/plasmas model, non-local Transport...

Tokamak Plasma : Avoid large scale instabilities.



Tomographic reconstruction of X-ray emission. JET SXR cameras (1998).

Tokamak Plasma : Kink instability (MHD, Jorek).



Laser focusing (ICF): Huygens-Fresnel Theorem.



Focusing Laser : Approximations and Computations.

$$E(\mathbf{x},t) = \sum_{\ell=1}^{N_{\ell}} \sum_{n=1}^{N_{w}} \sum_{i=1}^{N_{k_{x}}} \sum_{j=1}^{N_{k_{x}}} \mathcal{E}_{\ell,i,j,m} \mathcal{G}_{\ell,h}(t,\mathbf{x},\omega_{m},\boldsymbol{\theta}_{ij}) e^{i\Phi_{l,i,j,m}} e^{i\omega_{m}\left(t-\frac{n_{\ell}(\mathbf{x})}{c}\right)}$$
where $\Phi_{l,i,j,m} = \boldsymbol{\beta}_{\ell}(\mathbf{x}) \cdot \mathbf{k}_{\ell}(\boldsymbol{\theta}_{ij},\omega_{m}) + \frac{\omega_{m}n_{\ell}(\mathbf{x})}{c}$
 $\mathbf{k}_{\ell}(\boldsymbol{\theta},\omega) = k_{0,\ell}(\boldsymbol{\theta},\omega)\mathbf{n}_{0,\ell} + \theta_{1,\ell}\mathbf{n}_{1,\ell} + \theta_{2,\ell}\mathbf{n}_{2,\ell}$
 $\boldsymbol{\beta}_{\ell}(\mathbf{x}) = \mathbf{x} - \mathbf{x}_{\ell} = n_{\ell}(\mathbf{x})\mathbf{n}_{0,\ell} + \xi_{1,\ell}(\mathbf{x})\mathbf{n}_{1,\ell} + \xi_{2,\ell}(\mathbf{x})\mathbf{n}_{2,\ell}$
Given $\mathcal{E}_{\ell,i,j,m}$
 $N_{l} = 30$ quads
 $\mathbf{Q}_{1,2m} \times 1.2m$
 $\mathbf{x}_{l} = \mathbf{x}_{l} + \mathbf{x}_{l} +$

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Numerics for Controled Fusion

Mega Joule Laser (Bordeaux) : Input and Operations

 $N_w \simeq 10^3$, $Nk_x \simeq Nk_y \simeq 10^3$ $N_\ell \simeq 30$ quads

Total of Floating Operations = Flop $\simeq 3 \times 10^{10} \times \mathcal{R}_f$

 $\mathcal{R}_f = N f_x imes N f_y imes N f_t$ is the focal spot resolution

CPU Time for $\mathcal{R}_f = 2048 \times 2048 \times 1000 \simeq 4 \times 10^9$

 $\mathsf{Flop} \simeq 10^{20} = 10^8 \mathsf{Tera} \Longrightarrow 28 \times 10^3 \mathsf{ H}$ with a Tera computer \equiv 3 years

Parallel Computing unavoidable ! Need of mathematical approximations! Stationary phase approximation : asymptotic of oscillatory integrals

Focusing Laser Beams : Parallel strategy (simple)

• Scatter the Flop:

$$\boldsymbol{E}(\boldsymbol{x},t,\mathtt{me}) = \sum_{\ell} \sum_{m_1(\mathtt{me})}^{m_N(\mathtt{me})} \sum_{i_1(\mathtt{me})}^{i_N(\mathtt{me})} \sum_{j_1(\mathtt{me})}^{j_N(\mathtt{me})} \boldsymbol{\mathcal{E}}_{\ell,i,j,m} \mathcal{G}_{\ell,h} e^{\imath \Phi_{l,i,j,m}} e^{\imath \omega_m \tau}$$

• Gather the solution :

$$\boldsymbol{E}(\boldsymbol{x},t) = \sum_{\text{me}=0}^{N_p-1} \boldsymbol{E}(\boldsymbol{x},t,\text{me})$$

FFTW + MPI

Focusing Laser Beams : Computed focal spot and zoom.



21H CPU with 1936 cores : 30 quads = 120 (40cm x 40cm) Nodes : 4 Intel®Itanium® II, Dual-Core, 1.6 Ghz, 128 Go $N_w = Nf_t = 1$, $Nk_x = Nk_y = 2048$ and $Nf_x = Nf_y = 2048$

From the focal spot to Lagrangian Hydrodynamics



Weak formulation of Conservation Law

Integral form of in arbitrary coordinates

$$\begin{cases} \frac{d}{dt} \int_{\mathcal{C}(t)}^{\rho} d\boldsymbol{x} + \int_{\partial \mathcal{C}(t)}^{\rho} (\boldsymbol{u} - \boldsymbol{\kappa}) \cdot \boldsymbol{n} \, dS = 0, \\ \frac{d}{dt} \int_{\mathcal{C}(t)}^{\rho} \boldsymbol{u} \, d\boldsymbol{x} + \int_{\partial \mathcal{C}(t)}^{\rho} \boldsymbol{u} \, (\boldsymbol{u} - \boldsymbol{\kappa}) \cdot \boldsymbol{n} \, dS = -\int_{\partial \mathcal{C}(t)}^{\rho} \boldsymbol{n} \, dS, \\ \frac{d}{dt} \int_{\mathcal{C}(t)}^{\rho} \mathbf{e} \, d\boldsymbol{x} + \int_{\partial \mathcal{C}(t)}^{\rho} \mathbf{e} \, (\boldsymbol{u} - \boldsymbol{\kappa}) \cdot \boldsymbol{n} \, dS = -\int_{\partial \mathcal{C}(t)}^{\rho} \boldsymbol{u} \cdot \boldsymbol{n} \, dS. \end{cases}$$

Lagrangian controle volume : $\boldsymbol{\kappa} = \boldsymbol{u}$ on $\partial C(t)$

•
$$\tilde{m}_C \frac{d}{dt} \tilde{\boldsymbol{u}}_C = -\int_{\partial \mathcal{C}_C(t)} p\boldsymbol{n} \, dS,$$

• $\tilde{m}_C \frac{d}{dt} \tilde{\boldsymbol{e}}_C = -\int_{\partial \mathcal{C}_C(t)} p\boldsymbol{\kappa} \cdot \boldsymbol{n} \, dS.$ where • $\frac{d}{dt} \tilde{m}_C = 0,$

Coupling between averaged (mesh scale) and subscale states.

Multiscale formulation and approximation

Mesh scale equations

•
$$\tilde{m}_C \frac{d}{dt} \tilde{\boldsymbol{u}}_C = -\int_{\partial \mathcal{C}_C(t)} p\boldsymbol{n} \, dS,$$

• $\tilde{m}_C \frac{d}{dt} \tilde{e}_C = -\int_{\partial \mathcal{C}_C(t)} p\boldsymbol{\kappa} \cdot \boldsymbol{n} \, dS.$ where • $\frac{d}{dt} \tilde{m}_C = 0,$

sub-scale $\mathcal{K}_{j,C}^{\epsilon} \subset \mathcal{C}_C$ and $\mathcal{K}_{j,C}^{\epsilon} \subset \mathcal{K}_j^{\epsilon} :: \epsilon \mapsto 0$

$$\begin{split} \frac{d}{dt} \int_{\mathcal{K}_{j}^{\epsilon}(t)} &\rho \boldsymbol{\kappa} \; d\boldsymbol{x} &= -\int_{\partial \mathcal{K}_{j}^{\epsilon}(t)} \boldsymbol{p} \boldsymbol{n} \; dS, \qquad |\mathcal{K}_{j}^{\epsilon}| \simeq O(\epsilon) \\ \frac{d}{dt} \int_{\mathcal{K}_{j,C}^{\epsilon}(t)} &\rho \boldsymbol{\kappa} \; d\boldsymbol{x} &= -\int_{\partial \mathcal{K}_{j,C}^{\epsilon}(t)} \boldsymbol{p} \boldsymbol{n} \; dS, \qquad |\mathcal{K}_{j,C}^{\epsilon}| \simeq O(\epsilon) \end{split}$$

Subscale Riemann Problem to compute $p^*_{C,\ell,j}$ and $oldsymbol{\kappa}_j$



Half Riemann Solver for κ_j fixed: Godunov-type method

$$p_{C,\ell,j}^* = p_{\ell}^* \left(\tilde{\omega}_C, \boldsymbol{\kappa}_j \right) = p_C + Z_{C,j} \left(\tilde{\boldsymbol{u}}_C - \boldsymbol{\kappa}_j \right) \cdot \frac{m_{C,\ell,j}}{\|\boldsymbol{m}_{C,\ell,j}\|}$$

Subscale compatibility: The local system can be nonlinear: $\hookrightarrow \kappa_j$

$$\sum_{\ell \in \vartheta(j)} r_{\ell} (p_{C_1,\ell,j}^* - p_{C_2,\ell,j}^*) \boldsymbol{n}_{C_1,\ell} = 0$$

Subscale Riemann Problem to compute $p^*_{C,\ell,j}$ and $oldsymbol{\kappa}_j$



Half Riemann Solver for $\boldsymbol{\kappa}_{j}$ fixed: Godunov-type method $p_{C,\ell,j}^{*} = p_{\ell}^{*} \left(\tilde{\omega}_{C}, \boldsymbol{\kappa}_{j} \right) = p_{C} + Z_{C,j} \left(\tilde{\boldsymbol{u}}_{C} - \boldsymbol{\kappa}_{j} \right) \cdot \frac{\boldsymbol{m}_{C,\ell,j}}{\|\boldsymbol{m}_{C}|_{\ell,j}\|}$

Subscale compatibility: The local system can be nonlinear: $\hookrightarrow \kappa_j$

$$\sum_{\ell \in \vartheta(j)} r_{\ell} (p_{C_1,\ell,j}^* - p_{C_2,\ell,j}^*) \boldsymbol{n}_{C_1,\ell} = 0$$

Numerical Scheme : Linear mapping for $\psi_{\ell,j}(\xi)$

$$p_{\ell}^{*}(\tilde{\omega}_{C},\boldsymbol{\kappa}_{j}) = p_{C} + Z_{C,j}(\tilde{\boldsymbol{u}}_{C} - \boldsymbol{\kappa}_{j}) \cdot \boldsymbol{m}_{C,\ell,j}$$

Explicit scheme :
$$\left[\mathcal{A}_{j} \left(\tilde{\omega}_{*}^{n}, \, \boldsymbol{\kappa}_{*}^{n} \right) \right] \boldsymbol{\kappa}_{j}^{*} = \boldsymbol{g}_{j} \left(\tilde{\omega}_{*}^{n}, \, \boldsymbol{\kappa}_{*}^{n} \right) \longrightarrow \boldsymbol{x}^{n+\theta}$$

 $\boldsymbol{\kappa}_{\ell}(\boldsymbol{x}) = \sum \varphi_{\ell,j}(\mathbf{x}) \boldsymbol{\kappa}_{j}^{*}, \qquad p_{C,\ell}(\boldsymbol{x}) = \sum \psi_{\ell,j}(\mathbf{x}) p_{\ell}^{*} \left(\tilde{\omega}_{C}^{n}, \boldsymbol{\kappa}_{j}^{*} \right)$

$$\tilde{m}_{C} \frac{d}{dt} \tilde{\boldsymbol{u}}_{C} = -\sum_{\ell \in \partial C} \int_{\ell} p_{C,\ell}(\boldsymbol{x}) \boldsymbol{n}(\boldsymbol{\kappa}_{*}^{n}) \, d\ell,$$
$$\tilde{m}_{C} \frac{d}{dt} \tilde{e}_{C} = -\sum_{\ell \in \partial C} \int_{\ell} p_{C,\ell}(\boldsymbol{x}) \boldsymbol{\kappa}_{\ell}(\boldsymbol{x}) \cdot \boldsymbol{n}(\boldsymbol{\kappa}_{*}^{n}) \, d\ell.$$

Orthogonality constraint for interpolation gives

$$\begin{split} \psi_{\ell,j}(\xi) &= (d+1)\varphi_{\ell,j}(\xi) - 1\\ \text{and}\\ \int_{\ell} \psi_{\ell,i}\varphi_{\ell,j}d\ell &= \frac{\|\ell\|}{d}\delta_{i,j} \end{split}$$

Therefore we have analitical formula for the right hand side to compute $\hookrightarrow \mathbf{u}^{n+\theta}, e^{n+\theta}, p^{n+\theta}, p^{n+\theta} \hookrightarrow \tilde{\omega}^{n+\theta}$

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Computational domain $(x,y) \in [0,1] \times [0,0.1]$ with $(n_x,n_y) = (100,10)$ skewed by the map

$$x_{sk} = x + (0.1 - y)\sin(\pi x), \quad y_{sk} = y.$$



Initial conditions: $(\rho^0, P^0, U^0) = (1, 10^{-6}, 0)$ Materials: gamma law gas with $(\gamma = 5/3)$ Boundary conditions: inflow velocity $U^* = 1$ at x = 0.

Saltzman problem : Density at t = 0.6



Cylindrical Noh Problem: non-conformal, 2250 cells



Sedov-Taylor blast wave: 31×31 Cartesian grid



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Sedov-Taylor blast wave: 3D hexahedra mesh



- Initial high pressure in only one cell.
- Symmetry boundary conditions

Multifluid Hydrodynamic 3D : 8×10^6 unknowns

$$\omega = (\alpha, \rho_1, \rho_2, \rho \boldsymbol{u}, E)^T$$

 $\begin{array}{ll} \mbox{Implicit Low mach scheme, Surface tension, Gravity.} \\ 1.3\times10^6 \mbox{ Cells,} & \mbox{Time Steps}=14\ 610, & \mbox{Final Physical Time}=3.59 \mbox{s}, \\ \mbox{RAM used}=1.35 \mbox{Go/Core}\simeq11\ \mbox{Go}, & \mbox{CPU}=12\ \mbox{days}\times\ 8 \mbox{Pe} \end{array}$



Pe : 2x3GHz Quad-core Intel Xeon RAM: 16 Go 667MHz DDR2 FB-DIMM

Multifluid Hydrodynamic 3D : 8×10^6 unknowns

Explicit scheme : CFL 0.9

$$rac{T_{phys}}{T_{cpu}} \simeq 1.7 imes 10^{-4}$$

RAM used = 0.45Go/Core \simeq 3.6Go

Implicit scheme : CFL 40 (GS Relaxations \leq 25, $\varepsilon = 10^{-5}$)

$$\frac{T_{phys}}{T_{cpu}} \simeq 15 \times 10^{-4}$$
RAM used = 1.35Go/Core $\simeq 11$ Go
$$\mathcal{E}_{cpu} = \frac{15}{1.7} \simeq 9 \qquad \mathcal{E}_{ram} = \frac{11}{3.6} \simeq 3$$

From Lagrangian Hydrodynamics to Nonlinear Laser/plasmas interaction



Laser/plasma interaction : Physical Model

• Paraxial approximation:

$$\begin{split} \frac{2\imath\omega_0}{c^2}\partial_t\mathbf{E} + 2\imath k_0\partial_z\mathbf{E} + \left(\imath\partial_z k_0 - \frac{\omega_0^2}{c^2}\frac{n_e - n_{e0}}{n_c} + \imath\frac{\nu_{ei}\omega_0}{c^2}\frac{n_{e0}}{n_c}\right)\mathbf{E} \\ + \left(\frac{2\nabla^2}{1 + \sqrt{1 + \nabla^2/k_0^2}}\right)\mathbf{E} = 0. \end{split}$$

Nonlinear nonlocal laser/plasma interaction

$$\begin{array}{lll} \partial_t \rho + \mathbf{u} \cdot \nabla \rho &=& -\rho \nabla \cdot \mathbf{u} &, \\ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} &=& -\frac{1}{\rho} \nabla p & -\frac{Z \nabla \left(\|\mathbf{E}\|^2 \right)}{2 c n_e m_i} & +\frac{1}{\rho} \nabla \cdot \left(\eta \nabla \mathbf{u} \right), \\ \partial_t T_e + \mathbf{u} \cdot \nabla T_e &=& -\frac{p_e}{\rho} \nabla \cdot \mathbf{u} & +\frac{\nu_{ei} \Gamma_e}{n_c c} \|\mathbf{E}\|^2 & +\frac{\Gamma_e}{n_e} \nabla \cdot \left(\kappa_e \nabla T_e \right), \\ \partial_t T_i + \mathbf{u} \cdot \nabla T_i &=& -\frac{p_i}{\rho} \nabla \cdot \mathbf{u} & +\frac{\Gamma_i}{n_i} \nabla \cdot \left(\kappa_i \nabla T_i \right). \\ \beta_z \partial_z \mathbf{E} &=& -\beta_t \partial_t \mathbf{E} & -\mathcal{S}(\rho) \mathbf{E} & -\mathcal{L} \left(\nabla \right) \mathbf{E} \end{array}$$

Numerical Approximation : $\mathbf{W} = (\rho, \mathbf{u}, T_e, T_i)^T$

$$\begin{cases} \partial_t \mathbf{W} + \mathcal{A}(\mathbf{W}) \nabla_{x,y} \mathbf{W} &= \mathcal{P}(\mathbf{W}, \mathbf{E}) + \mathcal{N}(\mathbf{W}), \\ \beta_z \partial_z \mathbf{E} &= -\mathcal{S}(\mathbf{W}) \mathbf{E} - \mathcal{L}(\nabla_{x,y}) \mathbf{E} \\ \text{Given } \underline{\mathbf{E}^n(z=0), \mathbf{W}^{n-\frac{1}{2}}\left(z + \frac{\delta z}{2}\right)} \text{ and set } \mathcal{M}_{z+\frac{\delta z}{2}}^{n-\frac{1}{2}} = \mathcal{S}_{z+\frac{\delta z}{2}}^{n-\frac{1}{2}} + \mathcal{L}(\nabla_{x,y}) \end{cases}$$

• FFTW & θ -scheme + MPI $\Longrightarrow \mathbf{E}^n(z+\delta z)$

$$\left[\beta_z + \delta z \theta \mathcal{M}_{z+\frac{\delta z}{2}}^{n-\frac{1}{2}}\right] \mathbf{E}^n(z+\delta z) = \left[\beta_z - \delta z(1-\theta) \mathcal{M}_{z+\frac{\delta z}{2}}^{n-\frac{1}{2}}\right] \mathbf{E}^n(z)$$

 $\textbf{W}_{i,j}^{(1)} = \textbf{W}_{i,j}^{n-\frac{1}{2}} + \frac{\delta t}{a_{i,j}} \left[-\Phi_{i,j}^{n-\frac{1}{2}} + a_{i,j} \mathcal{P}_{i,j}^{n-\frac{1}{2}} \left(\frac{\textbf{E}^n(z+\delta z) + \textbf{E}^n(z)}{2} \right) \right]$

③ FFTW & θ -scheme + MPI \Longrightarrow $\mathbf{W}^{n+\frac{1}{2}} \left(z + \frac{\delta z}{2} \right)$ $\mathbf{W}_{i,j}^{n+\frac{1}{2}} - \delta t \theta \mathcal{N}_{i,j} \left(\mathbf{W}^{n+\frac{1}{2}} \right) = \mathbf{W}_{i,j}^{(1)} + \delta t (1-\theta) \mathcal{N}_{i,j} \left(\mathbf{W}^{(1)} \right)$

Validation by a proton diagnostic.

• Incoming Electric field : $I(t, \mathbf{r}) = I_{max} \exp\left(-\frac{2\mathbf{r}}{W_c^2} - \frac{t^2}{t_c^2}\right)$.

 $I_{max} = 3.7 \ 10^{14} W.cm^2$, $W_0 = 60 \mu m$, $t_0 = 400 ps$. $\lambda_0 = 1.053 \mu m$.

• Initial plasma (Helium: Z = 2) :

$$n_0 = 0.014n_c, \ T_{e0} = 100eV, \ T_{i0} = 30eV.$$

- Electron heat flux model:
 - Spitzer-Härm Conductivity, marginally valid for ICF : (non maxwellian electrons density functions.)
 - Brantov (98) nonlocal Conductivity.
 Based on a linearised theory of Fokker-Planck Valid for an "arbitrary" collisionality.
- Braginskii viscosity & ion Landau damping
 - --> ion heat conductivity. .

Energy distribution (on a cut plane) at 550ps





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Numerics for Controled Fusion

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From ICF to Magnetized confinement Fusion (Tokamaks)

Tokamak plasmas : KINETIC or/and FLUID ?

- What is the range of applicability of fluids modelizations for large Tokamaks plasmas ?
- Can we accurately take into account unresolved kinetic and/or particles orbits effects on large macroscopic scaled?
- What are characteristic behaviors of "Fluid like" modelizations, their stiffness and asymptotic?
- Can we design appropriate, stable, accurate, efficient and scalable numerical approximations that are able to simulate long time MHD instabilities for ITER and DEMO?

Ballooning instability : Reduced MHD (Jorek)



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- **1** Refinable cubic-Bezier FEM (O. Czarny, G. Huysmans).
- Oirect/iterative parallel sparse matrix solver (P. Ramet, P. Henon, ...)
- Optimized time-stepping algorithm (G. Huysmans, B. Nkonga, ...)
- Stabilised FEM, RD schemes (R. Abgrall, R. Huart, B. Nkonga,...)
- Sextended MHD model (E. van der Plas, G. Huysmans, B. Nkonga,...)
- Boundary conditions (M. Becoulet, G. Huysmans, ...)
- ANR program Intensive Computing and Simulation (ANR-CIS.2006) http://aster.gforge.inria.fr/index.html

Numerical schemes

- Dynamic mesh aligned with magnetic flux surfaces.
- High, i.e. realistic, (magnetic) Reynolds numbers
- Resolution of boundary layers (open field line and curved boundary)
- Long time integration: complete (internal disruption) ELM cycle (different ELM types).
- In Non-linear evolution of MHD models
 - Trigger of neoclassical transport (low collisionality, tearing modes).
 - Extended MHD (Ti-Te + Generalized Ohm's law).
 - Interaction with micromagnetic turbulence (anomalous transport).
- Seast particles interaction with MHD modes (nonlocal transport).
- Charge exchange neutrals, radiation, local heating, ...