



Firedrake: automating the finite element method by composing abstractions

Lawrence Mitchell¹

26th January 2017

¹Departments of Computing and Mathematics, Imperial College London



IC Thomas Gibson, David A. Ham, Miklós Homolya, Fabio
Luporini, Tianjiao Sun, Paul H. J. Kelly

Bath Andrew T. T. McRae

ECMWF Florian Rathgeber

IBM Gheorghe-Teodor Bercea

www.firedrakeproject.org

Rathgeber et al. 2016 arXiv: 1501.01809 [cs.MS]



www.firedrakeproject.org/contact.html

Methods

- Slack: firedrakeproject.slack.com
- Mail: firedrake@imperial.ac.uk (subscribe first)
- Github: github.com/firedrakeproject/firedrake



[...] *an automated system for the portable solution of partial differential equations using the finite element method.*

- Written in Python.
- Finite element problems specified with *embedded* domain specific language.
- *Runtime* compilation to low-level (C) code.
- Expressly *data parallel*: don't worry about MPI.



Find $u \in V \times Q \subset H(\text{div}) \times L^2$ s.t.

$$\langle u, v \rangle + \langle \text{div} v, p \rangle = 0 \quad \forall v \in V$$

$$\langle \text{div} u, q \rangle = -\langle 1, q \rangle \quad \forall q \in Q.$$

```
from firedrake import *
mesh = UnitSquareMesh(100, 100)
V = FunctionSpace(mesh, "RT", 2)
Q = FunctionSpace(mesh, "DG", 1)
W = V*Q
u, p = TrialFunctions(W)
v, q = TestFunctions(W)

a = dot(u, v)*dx + div(v)*p*dx + div(u)*q*dx
L = -Constant(1)*v*dx
u = Function(W)
solve(a == L, u, solver_parameters={
    "ksp_type": "gmres",
    "ksp_rtol": 1e-8,
    "pc_type": "fieldsplit",
    "pc_fieldsplit_type": "schur",
    "pc_fieldsplit_schur_fact_type": "full",
    "pc_fieldsplit_schur_precondition": "selfp",
    "fieldsplit_0_ksp_type": "preonly",
    "fieldsplit_0_pc_type": "ilu",
    "fieldsplit_1_ksp_type": "preonly",
    "fieldsplit_1_pc_type": "hypre"
})
```



Weave together

- *symbolic* problem description

```
W = V*Q
u, p = TrialFunctions(W)
v, q = TestFunctions(W)
a = dot(u, v)*dx + div(v)*p*dx + div(u)*q*dx
L = -Constant(1)*v*dx
```

- with problem-specific data (which mesh, what solver?)

```
mesh = UnitSquareMesh(100, 100)
V = FunctionSpace(mesh, "RT", 2)
Q = FunctionSpace(mesh, "DG", 1)
...
solve(a == L, u, solver_parameters=...)
```

and *synthesise* efficient implementation from the symbolic problem description.



Library usability

- High-level language enables rapid model development
- Ease of experimentation
- Small model code base

Library development

- Automation of complex optimisations
- Exploit expertise across disciplines
- Small library code base



www.dolfin-adjoint.org

Automated derivation of the discrete adjoint from forward models written using FEniCS *and Firedrake*.

```
$ cloc dolfin-adjoint/  
Language  files  blank  comment  code  
Python    54    2322    937    7294  
$ cloc dolfin-adjoint/compatibility.py  
Python    1     38     11     140
```

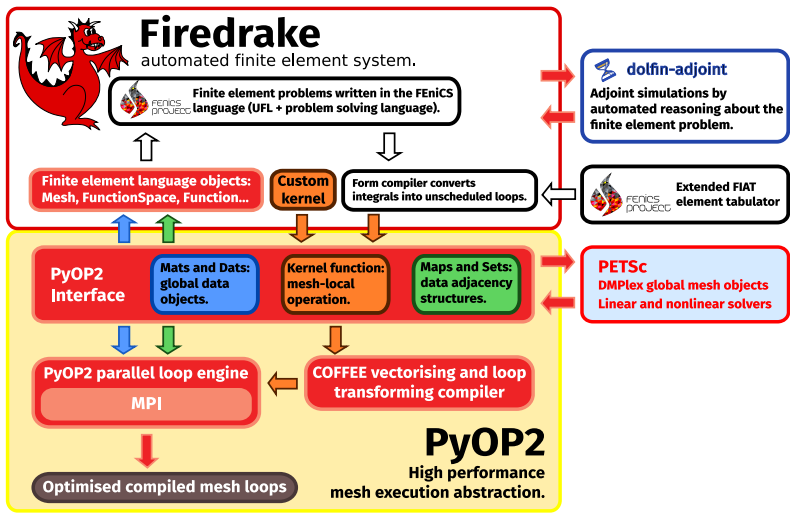



How much code do you need to change to

- Change preconditioner (e.g. ILU to AMG)?
- Drop terms in the preconditioning operator?
- Use a completely different operator to precondition?
- Do quasi-Newton with an approximate Jacobian?
- Apply operators matrix-free?

Same “easy to use” code must run fast at scale.

Say *what*, not *how*.



Local kernels



- “In-person” case-by-case optimisation *does not scale*
- Code generation allows us to package expertise and provide it to everyone
- Done by a special-purpose kernel compiler



No single optimal schedule for evaluation of every finite element kernel. Variability in

- polynomial degree,
- number of fields,
- kernel complexity,
- working set size,
- structure in the basis functions,
- structure in the quadrature points,
- ...



Vectorisation

Align and pad data structures, then use intrinsics or rely on compiler.

Luporini, Varbanescu, et al. 2015 doi: 10.1145/2687415

Flop reduction

Exploit *linearity* in test functions to perform factorisation, code motion and CSE.

Luporini, Ham, and Kelly 2016 arXiv: 1604.05872 [cs.MS]

github.com/coneoproject/COFFEE

Global iteration



Performance

- Keep data in cache as long as possible.
- Manually fuse kernels.
- Loop tiling for latency hiding.
- ...
- Individual components hard to test
- Space of optimisations suffers from combinatorial explosion.



Maintainability

- Keep kernels separate
- “Straight-line” code
- ...
- Testable
- Even if performance of individual kernels is good, can lose *a lot*



A library for expressing data parallel iterations

Sets iterable entities

Dats abstract managed arrays (data defined on a set)

Maps relationships between elements of sets

Kernels local computation

par_loop Data parallel iteration over a set

Arguments to parallel loop indicate how to gather/scatter global data using *access descriptors*

```
par_loop(kernel, iterset, data1(map1, READ), data2(map2, WRITE))
```



Local computation

Kernels do not know about global data layout.

- Kernel defines contract on local, packed, ordering.
- Global-to-local reordering/packing appears in map.

“Implicit” iteration

Application code does not specify explicit iteration order.

- Define data structures, then just “iterate”
- Lazy evaluation

Did we succeed?



With model set up, experimentation is easy

- Change preconditioner: c. 1 line
- Drop terms: c. 1-4 lines
- Different operator: c. 1-10 lines
- quasi-Newton: c. 1-10 lines
- Matrix-free: c. 1-10 lines (+ c. 30 lines for preconditioner).



Core Firedrake

Component	LOC
Firedrake	11000
PyOP2	5000
TSFC	3500
COFFEE	4500
Total	24000

Shared with FEniCS

Component	LOC
FIAT	4000
UFL	13000
Total	17000



Kernel performance

- COFFEE produces kernels that are better (operation count) than existing automated form compilers
- Provably optimal in some cases
- Good vectorised performance, problem dependent, but up to 70% peak for in-cache computation.



- Firedrake provides a layered set of abstractions for finite element
- Enables automated provision of expertise to model developers
- Computational performance is good, often $> 50\%$ achievable peak.



- Luporini, F., D. A. Ham, and P. H. J. Kelly (2016). *An algorithm for the optimization of finite element integration loops*. Submitted. arXiv: 1604.05872 [cs.MS].
- Luporini, F., A. L. Varbanescu, et al. (2015). “Cross-Loop Optimization of Arithmetic Intensity for Finite Element Local Assembly”. *ACM Trans. Archit. Code Optim.* 11. doi:10.1145/2687415.
- Rathgeber, F. et al. (2016). “Firedrake: automating the finite element method by composing abstractions”. *ACM Transactions on Mathematical Software* 43. doi:10.1145/2998441. arXiv: 1501.01809 [cs.MS].