

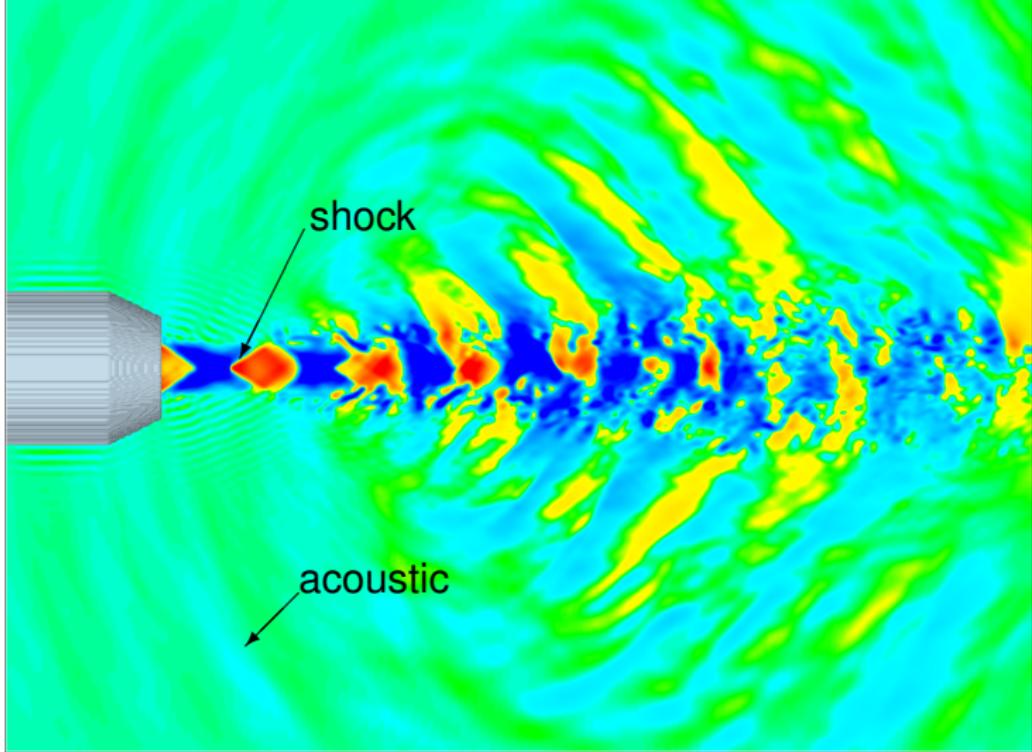
# Skew-Symmetric Schemes for compressible and incompressible flows

Julius Reiss

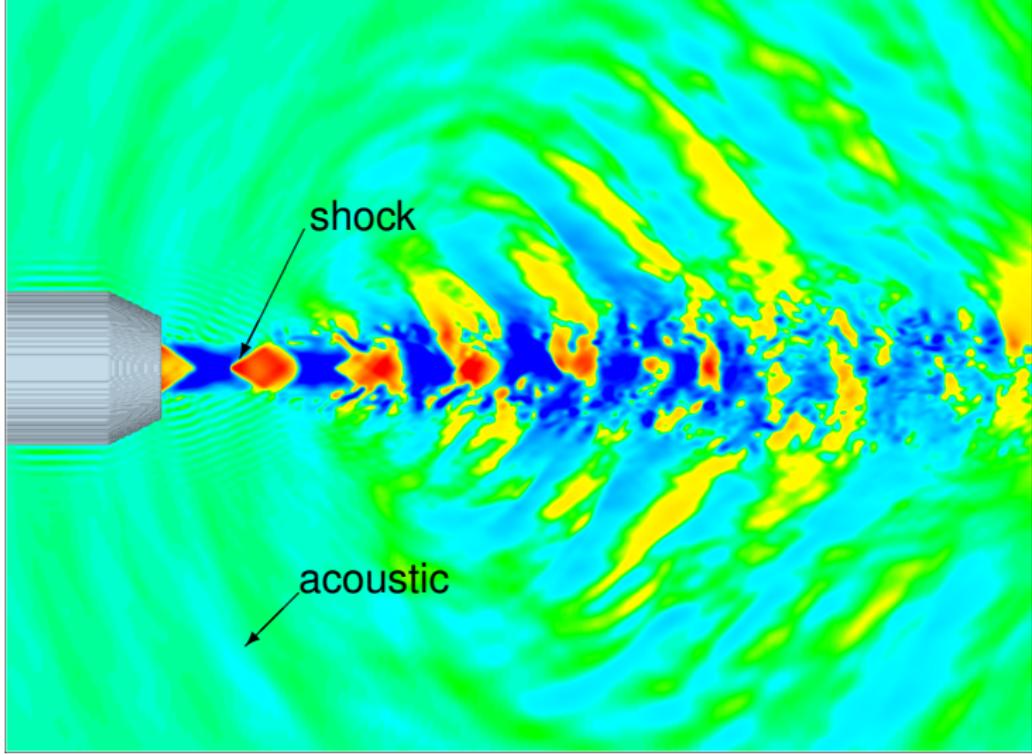
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**Use Finite Difference or use Finite Volume?**



**Use Finite Difference or use Finite Volume?  
→ skew symmetric, conservative FD**

# Overview

- 1 Burgers equation
- 2 Euler/Navier-Stokes Equations
- 3 Time discretization
- 4 Arbitrarily Transformed Grids
- 5 Fluxes & Boundary conditions
- 6 Incompressible flows

# The concept

$$\partial_t u + \partial_x f(u) = 0$$

Discretised:

$$\partial_t u + D^u u = 0$$

- $\partial_t \int u \, dx$

$$\mathbf{1}^T D^u = 0 \quad \text{telescoping sum}$$

- $\partial_t \int u^2 \, dx$

$$(D^u)^T = -D^u \quad \text{skew symmetry}$$

# The concept

$$\partial_t u + \partial_x f(u) = 0$$

Discretised:

$$\partial_t u + D^u u = 0$$

- $\partial_t \int u \, dx$

$$1^T D^u = 0 \quad \text{telescoping sum} \longrightarrow \text{Momentum Conservation}$$

- $\partial_t \int u^2 \, dx$

$$(D^u)^T = -D^u \quad \text{skew symmetry} \longrightarrow \text{Kin. Energy Conservation}$$

# Literature: Skew Symmetry

- Feiereisen W.C. Reynolds J.H. Ferziger, *Numerical simulation of a compressible homogeneous, turbulent shear flow*, NASA-CR-164953; SU-TF-13
- E. Tadmor, *Skew-Selfadjoint Form for Systems of Conservation Laws*, J. Math. Ana. Appl. 103, p428, (1984)
- Y. Morinishi and T. S. Lund and O. V. Vasilyev and P. Moin, *Fully conservative higher order finite difference schemes for incompressible flow* JCP 143, p 90, (1998)
- R. W. C. P. Verstappen, A. E. P. Veldman. *Symmetry-preserving discretization of turbulent flow*. JCP 187, p343 , (2003)
- J.C. Kok, *A high-order low-dispersion symmetry-preserving finite-volume method...* JCP 228, p 6811, (2009)
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- S. Pirozzoli, *Generalized conservative approximations of split convective derivative operators*, p7180 JCP 229, (2010)

# Skew-Symmetric discretisation

Simple example: Burgers' equation

divergence and convection form

$$\partial_t u + \partial_x \left( \frac{u^2}{2} \right) = 0 \quad (D)$$

$$\partial_t u + u \partial_x u = 0 \quad (C)$$

by  $(2 \cdot [D] + [C])/3$ :

skew-symmetric form

$$\partial_t u + \frac{1}{3} [\partial_x u \cdot + u \partial_x \cdot] u = 0 \quad (S)$$

# Skew-Symmetric discretisation

Burgers' in skew-symmetric form

$$\partial_t \mathbf{u} + \frac{1}{3} [\partial_x \mathbf{u} \cdot + \mathbf{u} \partial_x \cdot] \mathbf{u} = 0$$

Discrete

$$\partial_t \mathbf{u} + \underbrace{\frac{1}{3} (DU + UD)}_{D^u} \mathbf{u} = 0$$

$\mathbf{U} = \text{diag}(\mathbf{u})$ , derivative  $D$  with  $D^T = -D$

$$\partial_t \mathbf{u} + D^u \mathbf{u} = 0$$

# Skew Symmetric discretisation

Kinetic Energy Conservation

$$\frac{1}{2} \mathbf{u}^T \mathbf{u} = \frac{1}{2} \sum_i u_i^2$$

$$\begin{aligned}\partial_t \mathbf{u}^T \mathbf{u} &= (\partial_t \mathbf{u})^T \mathbf{u} + \mathbf{u}^T \partial_t \mathbf{u} \\ &= -(D^u \mathbf{u})^T \mathbf{u} - \mathbf{u}^T D^u \mathbf{u} \\ &= -\mathbf{u}^T [(D^u)^T + D^u] \mathbf{u}\end{aligned}$$

# Skew Symmetric discretisation

Kinetic Energy Conservation

$$\frac{1}{2} \mathbf{u}^T \mathbf{u} = \frac{1}{2} \sum_i u_i^2$$

$$\begin{aligned}\partial_t \mathbf{u}^T \mathbf{u} &= (\partial_t \mathbf{u})^T \mathbf{u} + \mathbf{u}^T \partial_t \mathbf{u} \\ &= -(D^u \mathbf{u})^T \mathbf{u} - \mathbf{u}^T D^u \mathbf{u} \\ &= -\mathbf{u}^T [(D^u)^T + D^u] \mathbf{u}\end{aligned}$$

Symmetry of transport term  $D^u$

$$(D^u)^T = \frac{1}{3}(DU + UD)^T = \frac{1}{3}(U^T D^T + D^T U^T) = -D^u$$

$$U = \text{diag}(u) = U^T, \quad D^T = -D$$

# Skew Symmetric discretisation

Kinetic Energy Conservation

$$\frac{1}{2} \mathbf{u}^T \mathbf{u} = \frac{1}{2} \sum_i u_i^2$$

$$\begin{aligned}\partial_t \mathbf{u}^T \mathbf{u} &= (\partial_t \mathbf{u})^T \mathbf{u} + \mathbf{u}^T \partial_t \mathbf{u} \\ &= -(D^u \mathbf{u})^T \mathbf{u} - \mathbf{u}^T D^u \mathbf{u} \\ &= -\mathbf{u}^T \underbrace{[(D^u)^T + D^u]}_{=0} \mathbf{u} = 0\end{aligned}$$

Symmetry of transport term  $D^u$

$$(D^u)^T = \frac{1}{3}(DU + UD)^T = \frac{1}{3}(U^T D^T + D^T U^T) = -D^u$$

Skew symmetry implies conservation of  $E_{kin}$

# Skew Symmetric discretisation

Momentum Conservation

$$\mathbf{1}^T \mathbf{u} = \sum_i \mathbf{1} \cdot u_i$$

$$\begin{aligned}\partial_t \mathbf{1}^T \mathbf{u} &= \mathbf{1}^T \partial_t \mathbf{u} \\ &= -\mathbf{1}^T D^u \mathbf{u}\end{aligned}$$

Telescoping

$$\mathbf{1}^T D^u \mathbf{u} = \frac{1}{3} (\underbrace{\mathbf{1}^T D U}_{=0} + \mathbf{1}^T U D) \mathbf{u} = \frac{1}{3} \underbrace{\mathbf{u}^T D \mathbf{u}}_{=0} = 0$$

with  $D^T = -D$

# Skew Symmetric discretisation

Momentum Conservation

$$\mathbf{1}^T \mathbf{u} = \sum_i \mathbf{1} \cdot u_i$$

$$\begin{aligned}\partial_t \mathbf{1}^T \mathbf{u} &= \mathbf{1}^T \partial_t \mathbf{u} \\ &= -\underbrace{\mathbf{1}^T D^u \mathbf{u}}_{=0} = 0\end{aligned}$$

Telescoping

$$\mathbf{1}^T D^u \mathbf{u} = \frac{1}{3} (\underbrace{\mathbf{1}^T D U}_{=0} + \mathbf{1}^T U D) \mathbf{u} = \frac{1}{3} \underbrace{\mathbf{u}^T D \mathbf{u}}_{=0} = 0$$

Telescoping sum property implies conservation of momentum

# Time Integration

Implicit midpoint rule<sup>1</sup>

Fully discrete

$$\frac{u^{n+1} - u^n}{\Delta t} + \frac{1}{3} D^{u^{n+1/2}} u^{n+1/2} = 0$$

with  $u^{n+1/2} = \frac{1}{2}(u^n + u^{n+1})$

<sup>1</sup>Verstappen, Veldman, J. Com. Phys 187, p. 343 (2003)

# Time Integration

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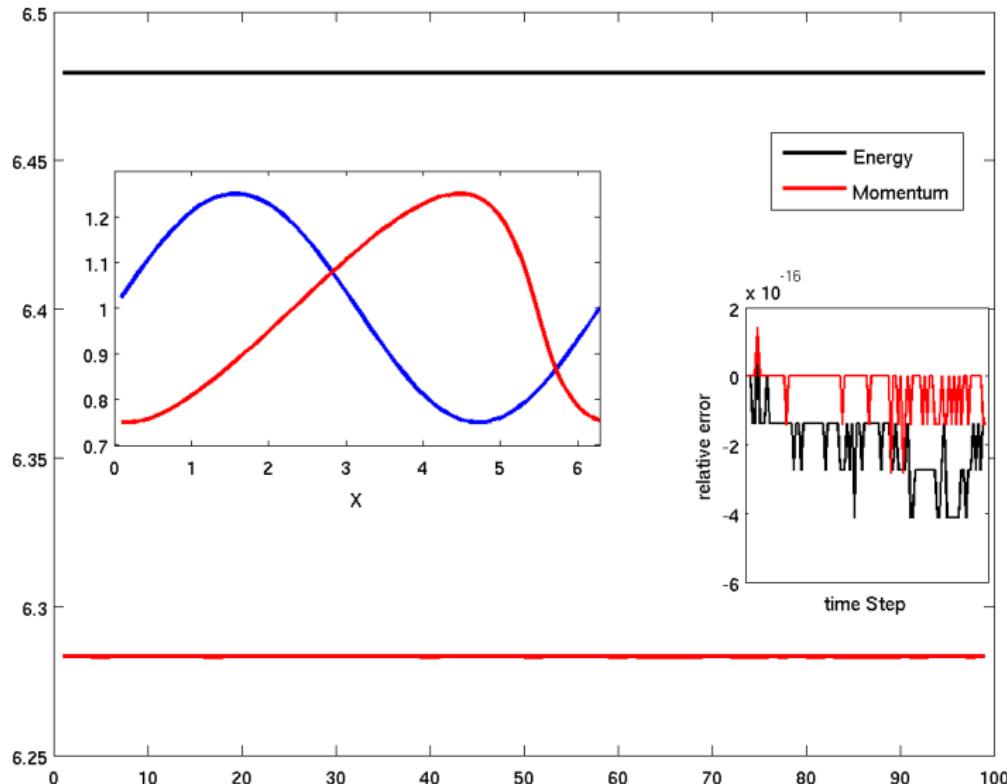
with  $u^{n+1/2} = \frac{1}{2}(u^n + u^{n+1})$

Multiplying by  $(u^{n+1/2})^T$

$$\begin{aligned} & (u^{n+1/2})^T (u^{n+1} - u^n) + \underbrace{\frac{1}{3} (u^{n+1/2})^T D^{u^{n+1/2}} u^{n+1/2}}_{=0} \\ &= \frac{1}{2} (u^n + u^{n+1})^T (u^{n+1} - u^n) \\ &= \frac{(u^{n+1})^2}{2} - \frac{(u^n)^2}{2} = 0 \end{aligned}$$

<sup>1</sup>Verstappen, Veldman, J. Com. Phys 187, p. 343 (2003)

# Numerical example: Burgers' Equation



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# Skew Symmetric discretisation

## Euler Momentum Equation

divergence and convection form

$$\partial_t(\varrho u) + \partial_x(\varrho u^2) + \partial_x p = 0 \quad (D)$$

$$\varrho \partial_t(u) + \varrho u \partial_x(u) + \partial_x p = 0 \quad (C)$$

by  $([D]+[C])/2$

Skew symmetric form

$$\frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p = 0 \quad (S)$$

# Skew Symmetric discretisation

## Euler Equations

$$\begin{aligned}\partial_t \varrho + \partial_x(u\varrho) &= 0 \\ \frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p &= 0\end{aligned}$$

# Skew Symmetric discretisation

## Euler Equations

$$\begin{aligned}\partial_t \varrho + \partial_x(u\varrho) &= 0 \\ \frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p &= 0 \\ \partial_t \left( \frac{p}{\gamma - 1} \right) + \partial_x \left( u \left( \frac{p}{\gamma - 1} + p \right) \right) &+ \\ \partial_t \left( \varrho u^2 / 2 \right) + \partial_x \left( u \left( \varrho u^2 / 2 \right) \right) &= 0\end{aligned}$$

# Skew Symmetric discretisation

## Skew symmetric Euler Equations

$$\begin{aligned}\partial_t \varrho + \partial_x(u\varrho) &= 0 \\ \frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p &= 0 \\ \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} \partial_x (up) - u \partial_x p &= 0\end{aligned}$$

# Skew Symmetric discretisation

## Skew symmetric Euler Equations

$$\begin{aligned}\partial_t \varrho + \partial_x(u\varrho) &= 0 \\ \frac{1}{2}(\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2}(\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p &= 0 \\ \frac{1}{\gamma-1} \partial_t p + \frac{\gamma}{\gamma-1} \partial_x (up) - u \partial_x p &= 0\end{aligned}$$

## Discretised

$$\begin{aligned}\partial_t \varrho + (DU)\varrho &= 0 \\ \frac{1}{2}(\partial_t \varrho + \varrho \partial_t) u + \frac{1}{2}(DUR + RUD)u + Dp &= 0 \\ \frac{1}{\gamma-1} \partial_t p + \frac{\gamma}{\gamma-1}(DU)p - (UD)p &= 0\end{aligned}$$

with  $U = \text{diag}(u)$ ,  $R = \text{diag}(\varrho)$ , Derivative  $D = -D^T$

# Skew Symmetric discretisation

## Skew symmetric Navier–Stokes Equations

$$\begin{aligned}\partial_t \varrho + \partial_x(u\varrho) &= 0 \\ \frac{1}{2}(\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2}(\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p &= \partial_x \tau \\ \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} \partial_x (up) - u \partial_x p &= -u \partial_x \tau + \partial_x \tau\end{aligned}$$

## Discretised

$$\begin{aligned}\partial_t \varrho + (DU)\varrho &= 0 \\ \frac{1}{2}(\partial_t \varrho + \varrho \partial_t) u + \frac{1}{2}(DUR + RUD)u + Dp &= D\tau \\ \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1}(DU)p - (UD)p &= -UD\tau + D\tau u\end{aligned}$$

with  $U = \text{diag}(u)$ ,  $R = \text{diag}(\varrho)$ , Derivative  $D = -D^T$ ,  $\tau = \mu \partial_x u$

## Conservation, time continuous

$$\begin{aligned}\partial_t \varrho + D\mathbf{U} \varrho &= 0 \\ \frac{1}{2}(\partial_t \varrho + \varrho \partial_t) \mathbf{u} + \frac{1}{2} \underbrace{(D\mathbf{U} \mathbf{R} + \mathbf{R} \mathbf{U} \mathbf{D})}_{D\mathbf{U} \mathbf{e}} \mathbf{u} + D\mathbf{p} &= 0 \\ \frac{1}{\gamma - 1} \partial_t \mathbf{p} + \frac{\gamma}{\gamma - 1} D\mathbf{U} \mathbf{p} - U \mathbf{D} \mathbf{p} &= 0\end{aligned}$$

$\mathbf{1}^T(\text{mass}) = 0 \rightarrow \text{mass Conservation}$

$\mathbf{1}^T(\text{mom}) + \mathbf{u}^T(\text{mass})/2 = 0 \rightarrow \text{Momentum Conservation}$

$\mathbf{1}^T(\text{innerE}) + \mathbf{u}^T(\text{mom}) = 0 \rightarrow \text{Energy Conservation}$

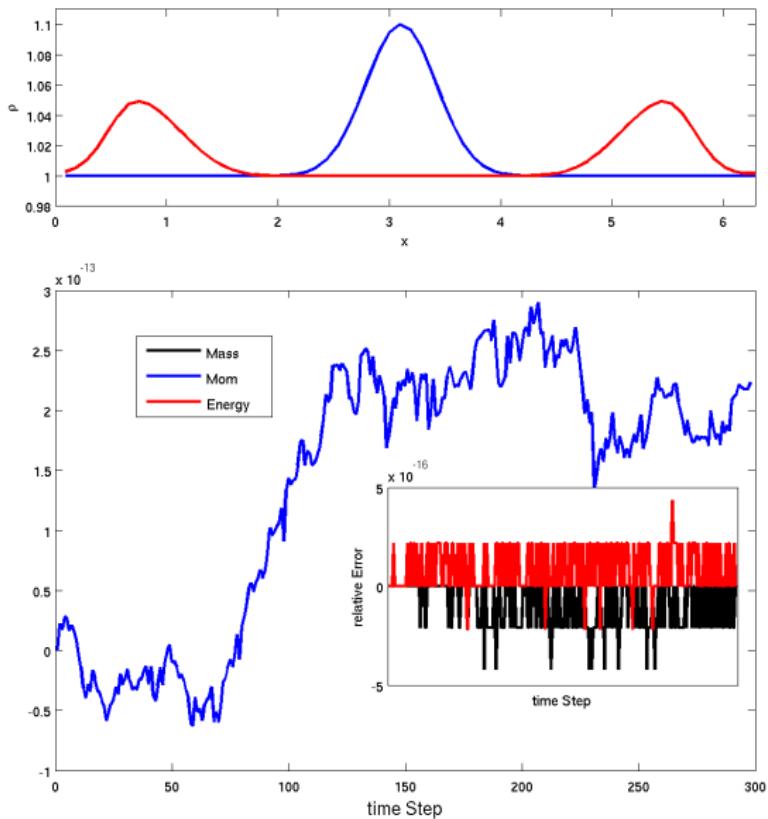
## Conservation, time continuous

$$\begin{aligned}\partial_t \varrho + D\mathbf{U} \varrho &= 0 \\ \frac{1}{2}(\partial_t \varrho + \varrho \partial_t) \mathbf{u} + \frac{1}{2} \underbrace{(DUR + RUD)}_{D\mathbf{u} \varrho} \mathbf{u} + Dp &= 0 \\ \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} DUP - UDP &= 0\end{aligned}$$

- $\mathbf{1}^T (\text{mass}) = 0 \rightarrow \text{mass Conservation}$   
 $\mathbf{1}^T (\text{mom}) + \mathbf{u}^T (\text{mass}) / 2 = 0 \rightarrow \text{Momentum Conservation}$   
 $\mathbf{1}^T (\text{innerE}) + \mathbf{u}^T (\text{mom}) = 0 \rightarrow \text{Energy Conservation}$

$$\begin{aligned}\frac{1}{\gamma - 1} \partial_t \mathbf{1}^T p + \frac{1}{2} \mathbf{u}^T (\partial_t \varrho + \varrho \partial_t) \mathbf{u} &= \partial_t \left( \frac{1}{\gamma - 1} \mathbf{1}^T p + \mathbf{u}^T (\varrho \mathbf{u}) / 2 \right) \\ + \frac{\gamma}{\gamma - 1} \mathbf{1}^T DUP + \frac{1}{2} \mathbf{u}^T D\mathbf{u} \varrho \mathbf{u} &= 0\end{aligned}$$

# Numerical example 1D



## Time Integration: Leapfrog-like

# Time discretization

$$\frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p = 0$$

One Step methods:

- Morinishi's rewriting  $\frac{1}{2} (\partial_t \rho \cdot + \rho \partial_t \cdot) u = \sqrt{\rho} \partial_t \sqrt{\rho} u$
- use adopted midpoint rule
- → similar to Morinishi , Subbareddy et. al., JCP 2009
- generalises to higher order

# Time discretization

$$\frac{1}{2} (\partial_t \varrho \cdot + \varrho \partial_t \cdot) u + \frac{1}{2} (\partial_x u \varrho \cdot + \varrho u \partial_x \cdot) u + \partial_x p = 0$$

One Step methods:

- Morinishi's rewriting  $\frac{1}{2} (\partial_t \rho \cdot + \rho \partial_t \cdot) u = \sqrt{\rho} \partial_t \sqrt{\rho} u$
- use adopted midpoint rule
- → similar to Morinishi , Subbareddy et. al., JCP 2009
- generalises to higher order

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u) + \frac{1}{2} D^{\mathbf{u}\rho} u + D_x p = 0$$

# Time discretization

$$\sqrt{\rho} \partial_t \sqrt{\rho} + \frac{1}{2} B^u \rho = 0$$

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u) + \frac{1}{2} D^{u\rho} u + D_x p = 0$$

$$\frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} B^u p - C^u p = 0$$

$$\sqrt{\rho}^{n+1/2} \frac{(\sqrt{\rho}^{n+1} - \sqrt{\rho}^n)}{\Delta t} + \frac{1}{2} B^{u^{n+a}} \rho^{n+b} = 0$$

$$\sqrt{\rho}^{n+1/2} \frac{(\sqrt{\rho} u)^{n+1} - (\sqrt{\rho} u)^n}{\Delta t} + \frac{1}{2} D^{u^{n+a} \rho^{n+b}} u^{n+1/2} + D_x p^{n+c} = 0$$

$$\sqrt{\rho}^{n+1/2} = \frac{1}{2} (\sqrt{\rho}^n + \sqrt{\rho}^{n+1})$$

# Time discretization

$$\sqrt{\rho} \partial_t \sqrt{\rho} + \frac{1}{2} B^u \rho = 0$$

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u) + \frac{1}{2} D^{u\rho} u + D_x p = 0$$

$$\frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} B^u p - C^u p = 0$$

$$\sqrt{\rho}^{n+1/2} \frac{(\sqrt{\rho}^{n+1} - \sqrt{\rho}^n)}{\Delta t} + \frac{1}{2} B^{u^{n+a}} \rho^{n+b} = 0$$

$$\sqrt{\rho}^{n+1/2} \frac{(\sqrt{\rho} u)^{n+1} - (\sqrt{\rho} u)^n}{\Delta t} + \frac{1}{2} D^{u^{n+a} \rho^{n+b}} u^{n+1/2} + D_x p^{n+c} = 0$$

$$\sqrt{\rho}^{n+1/2} = \frac{1}{2} (\sqrt{\rho}^n + \sqrt{\rho}^{n+1})$$

$$u^{n+1/2} = \frac{1}{2} \frac{(\sqrt{\rho} u)^{n+1} + (\sqrt{\rho} u)^n}{\sqrt{\rho}^{n+1/2}}$$

# Time discretization

## Higher Order

$$\sqrt{\rho} \partial_t \sqrt{\rho} + \frac{1}{2} B^u \rho = 0$$

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u) + \frac{1}{2} D^u \rho u + D_x p = 0$$

$$\frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} B^u p - C^u p = 0$$

- Implicit Midpoint rule is Gauss-collocation method
- All Gauss-collocation methods preserve skew-symme. & cons.<sup>†</sup>

Midpoint (2<sup>nd</sup> order)

$\frac{1}{2}$	$\frac{1}{2}$
1	

Midpoint (4<sup>th</sup> order)

$\frac{1}{2} - \frac{\sqrt{3}}{6}$	$\frac{1}{4}$	$\frac{1}{4} - \frac{\sqrt{3}}{6}$
$\frac{1}{2} + \frac{\sqrt{3}}{6}$	$\frac{1}{4} + \frac{\sqrt{3}}{6}$	$\frac{1}{4}$
	$\frac{1}{2}$	$\frac{1}{2}$

†Brouwer, Reiss, in prep.

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# Euler Equations, more dimensions

Skew-symmetric momentum equation

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u_\alpha) + \frac{1}{2} [\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot] u_\alpha + \partial_{x_\alpha} p = 0.$$

Main problem: Keep skew symmetric structure on distorted grids.<sup>a</sup>

Local base  $\mathbf{e}_\alpha = \partial_{\xi^\alpha} \mathbf{r}$ ,  $\mathbf{r} = \mathbf{r}(\xi, \eta, \zeta) = (x, y, z)^T$

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<sup>a</sup>Veldman, Rinzema, Playing with nonuniform grids, J. Engin. and Math. 26, p 119, (1992), VV2003

# Euler Equations, more dimensions

Skew-symmetric momentum equation

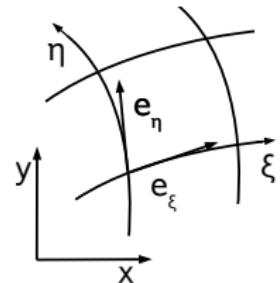
$$\sqrt{\rho} \partial_t (\sqrt{\rho} u_\alpha) + \frac{1}{2} [\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot] u_\alpha + \partial_{x_\alpha} p = 0.$$

Main problem: Keep skew symmetric structure on distorted grids.

Local base  $\mathbf{e}_\alpha = \partial_{\xi^\alpha} \mathbf{r}$ ,  $\mathbf{r} = \mathbf{r}(\xi, \eta, \zeta) = (x, y, z)^T$

Use divergence as

$$\begin{aligned}\frac{\partial u_\beta}{\partial x_\beta} &= \frac{1}{J} \sum_{\alpha, c\gamma} \partial_{\xi^\alpha} (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \mathbf{u} \\ &= \frac{1}{J} \sum_{\alpha, c\gamma} (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \partial_{\xi^\alpha} \mathbf{u}.\end{aligned}$$



# Euler Equations, more dimensions

Skew-symmetric momentum equation

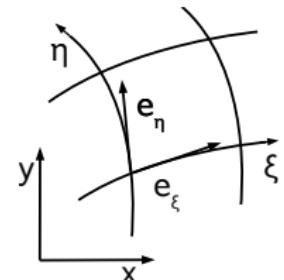
$$\sqrt{\rho} \partial_t (\sqrt{\rho} u_\alpha) + \frac{1}{2} [\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot] u_\alpha + \partial_{x_\alpha} p = 0.$$

Main problem: Keep skew symmetric structure on distorted grids.

Local base  $\mathbf{e}_\alpha = \partial_{\xi^\alpha} \mathbf{r}$ ,  $\mathbf{r} = \mathbf{r}(\xi, \eta, \zeta) = (x, y, z)^T$

Use divergence as

$$\begin{aligned}\frac{\partial u_\beta}{\partial x_\beta} &= \frac{1}{J} \sum_{\alpha, \text{cy}} \partial_{\xi^\alpha} (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \mathbf{u} \\ &= \frac{1}{J} \sum_{\alpha, \text{cy}} (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \partial_{\xi^\alpha} \mathbf{u}.\end{aligned}$$



$$[\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot] u_\alpha$$

$$\sim \sum_{\alpha, \text{cy}} [\partial_{\xi^\alpha} (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \mathbf{u} \varrho \cdot + \mathbf{u} \varrho (\mathbf{e}_\beta \times \mathbf{e}_\gamma) \partial_{\xi^\alpha} \cdot] u_\alpha$$

# Euler Equations in 2D

Semidiscrete

$$\begin{aligned} J\partial_t \rho + B^u \rho &= 0 \\ J\sqrt{\rho} \partial_t (\sqrt{\rho} u) + \frac{1}{2} D^{\mathbf{u}\rho} u + D_x p &= 0 \\ J\sqrt{\rho} \partial_t (\sqrt{\rho} v) + \frac{1}{2} D^{\mathbf{u}\rho} v + D_y p &= 0 \\ J \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} B^u p - C^u p &= 0 \end{aligned}$$

with

$$\begin{aligned} B^{\mathbf{u}} &= D_{\xi} \tilde{U} + D_{\eta} \tilde{V} \\ D^{\mathbf{u}\rho} &= (D_{\xi} \tilde{U} R + R \tilde{U} D_{\xi}) + (D_{\eta} \tilde{V} R + R \tilde{V} D_{\eta}) \\ C^{\mathbf{u}} &= U D_x + V D_y \end{aligned}$$

where  $\tilde{U} = (UY_{\eta} - VX_{\eta})$  and  $\tilde{V} = (VX_{\xi} - UY_{\xi})$   
and  $D_x = D_{\xi} Y_{\eta} - D_{\eta} Y_{\xi}$ ,  $D_y = \dots$

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## Boundary conditions

Flux vs. Value, 1D mass equation

$$\partial_t \rho + D_x u \rho = 0 \quad \longrightarrow \quad \partial_t \mathbf{1}^T \rho + \underbrace{\mathbf{1}^T D_x}_{b^T} u \rho = 0$$

$$b^T = \mathbf{1}^T \begin{pmatrix} -1 & 1 & & & \\ -\frac{1}{2} & 0 & \frac{1}{2} & & \\ & -\frac{1}{2} & 0 & \frac{1}{2} & \\ & & \ddots & \ddots & \ddots \\ & & & -1 & 1 \end{pmatrix} = \left( -\frac{3}{2}, \frac{1}{2}, 0, \dots, 0, -\frac{1}{2}, \frac{3}{2} \right)$$

mass flux over boundaries:

$$b^T u \rho = - \left( (\rho u)_1 \frac{3}{2} - (\rho u)_2 \frac{1}{2} \right) + \left( (\rho u)_N \frac{3}{2} - (\rho u)_{N-1} \frac{1}{2} \right) = -f_0 + f_N$$

Flux non-zero even for  $u_1 = 0$

## Boundary conditions

Would like  $u_1 = 0 \Leftrightarrow f_0 = 0$

$$Wu' = \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} & & & \\ -\frac{1}{2} & 0 & \frac{1}{2} & & \\ & -\frac{1}{2} & 0 & \frac{1}{2} & \\ & & \ddots & \ddots & \ddots \\ & & & -\frac{1}{2} & \frac{1}{2} \end{pmatrix} u.$$

$$\rightarrow b^T = (-1, 0, \dots, 0, 1).$$

weigh- matrix  $W$  (norm)

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$$\rightarrow b^T = (-1, 0, \dots, 0, 1).$$

weigh- matrix  $W$  (norm)

$$W_{jj} = \text{diag}\left(\frac{1}{2}, 1, 1, \dots, 1, \frac{1}{2}\right)$$

Summation By Parts (SBP)-Property

# Boundary conditions: SBP

For SBP derivatives there is a norm, such that<sup>2</sup>

- Telescoping sum is broken at boundary
- Skew Symmetry only broken at  $D_{1,1}$  and  $D_{N,N}$

Boundary flux of our scheme depends entirely

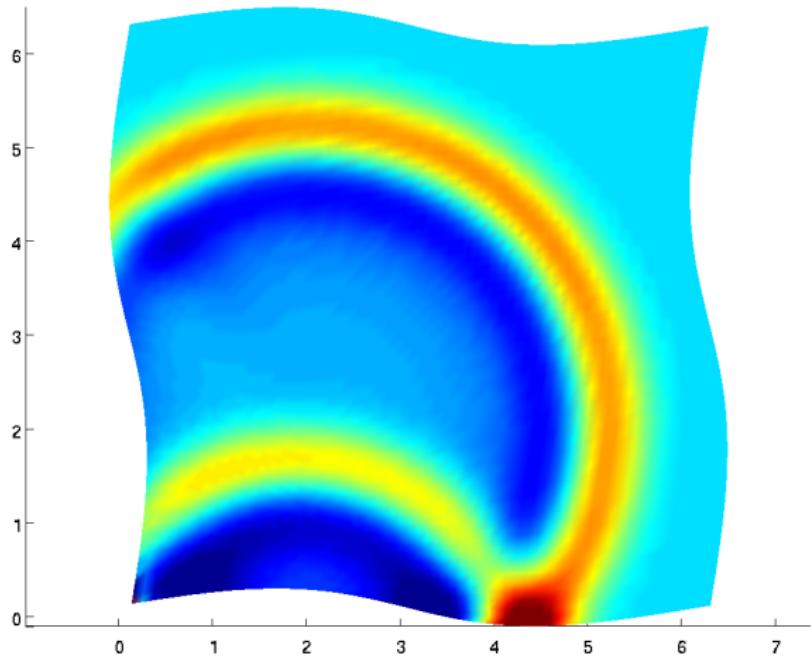
- on boundary values,
- addition flux to enforce BC

Enforcing BC e.g. in Carpenter<sup>3</sup> give global energy estimates.  
(Work in progress...)

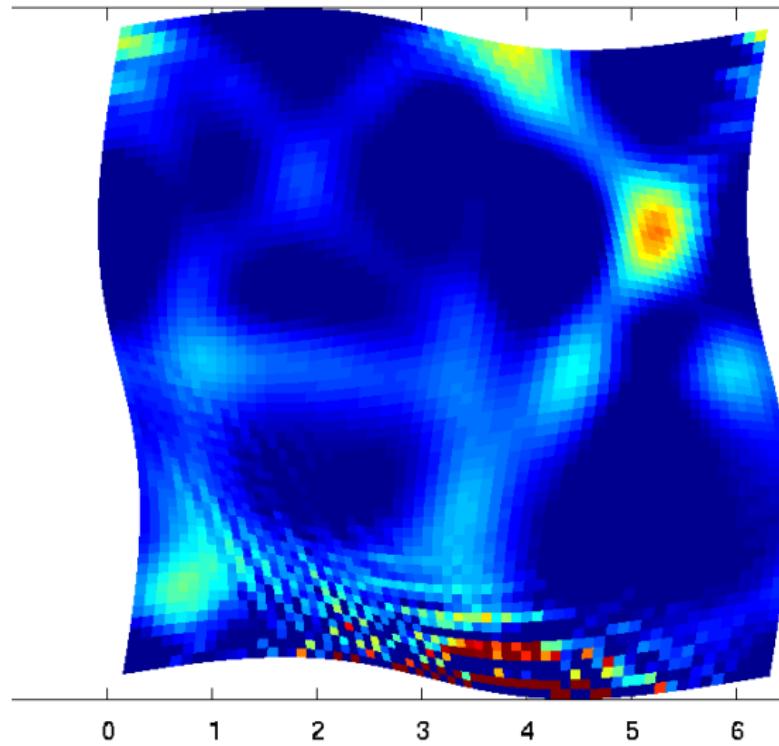
<sup>2</sup>Strand, JCP 110, p47, 1994

<sup>3</sup>Carpenter et al, JCP 108, p272, 1993

# Skew Symmetric discretisation

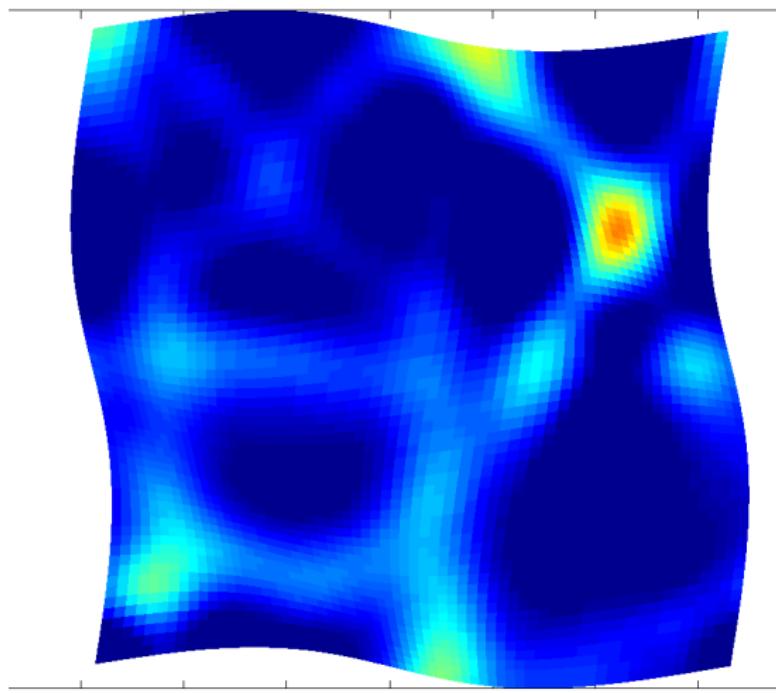


# Skew Symmetric discretisation



Without SBP

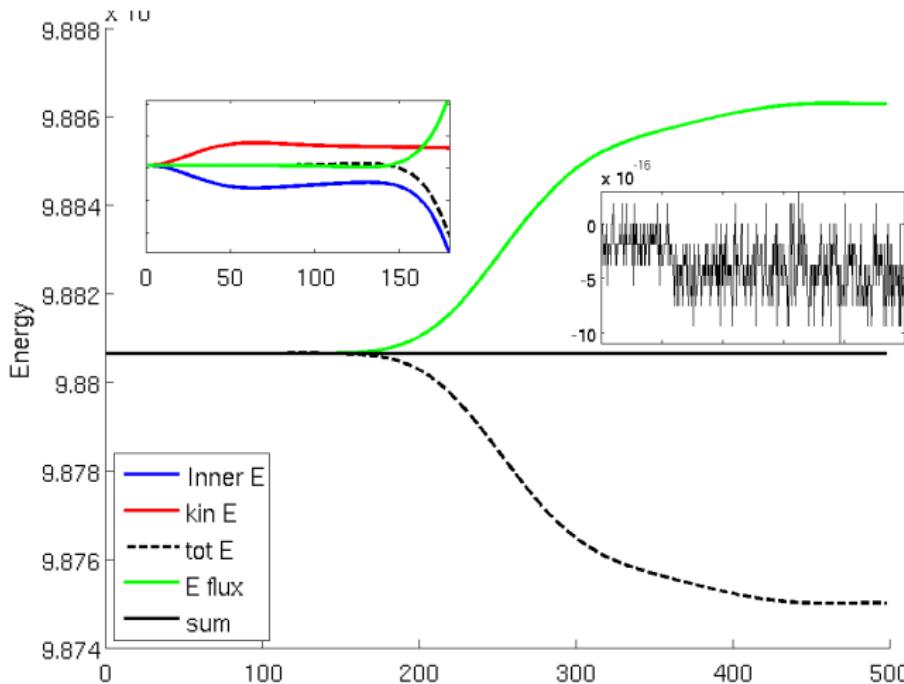
# Skew Symmetric discretisation



With SBP

# Skew Symmetric discretisation

Conservation with boundary



# Skew Symmetric discretisation

## First Conclusions

- Skew symmetry leads to kinetic energy conservation
- ... with telescoping sum property full conservation
- strict skew symmetry & perfect conservation on *transformed* grids
- Procedure easy to implement & numerically efficient
- Derivatives of any order in space
- Time stepping of any order

# Skew Symmetric discretisation

## First Conclusions

- Skew symmetry leads to kinetic energy conservation
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- Procedure easy to implement & numerically efficient
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## Outlook

- Implementation for shock acoustic simulations in progress
- Big DNS of turbulent flows

## Bonus Part

Schemes for the **incompressible** Navier-Stokes equation

## Bonus Part

Schemes for the **incompressible** Navier-Stokes equation

### How to avoid odd-even decoupling?

Idea:

- energy and momentum conserving, and **collocated**, by
  - ▶ use of skew symmetry  
  &
  - ▶ the **combination of non-symmetric derivatives**
- Grid transformations preserving these properties
  - ▶ general in 2D
  - ▶ restricted in 3D

# Incompressible Navier-Stokes

$$\partial_t \rho + \partial_{x_\alpha} \rho u_\alpha = 0$$

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u_\alpha) + \frac{1}{2} (\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot) u_\alpha + \partial_{x_\alpha} p = \partial_\beta \tau_{\alpha,\beta}$$

$$\frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} \partial_{x_\beta} (u_\beta p) - u_\beta \partial_{x_\beta} p = 0$$

$$\partial_t u_\alpha + \frac{1}{2} (\partial_{x_\beta} u_\beta \cdot + u_\beta \partial_{x_\beta} \cdot) u_\alpha + \partial_{x_\alpha} p = \nu \Delta u_\alpha$$

$$\partial_{x_\alpha} u_\alpha = 0 \quad \alpha, \beta = 1, 2, 3$$

Pressure Poisson Equation:

$$\partial_{x_\alpha} \partial_{x_\alpha} p = \partial_{x_\alpha} (-D^u u_\alpha + \nu \Delta u_\alpha)$$

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$$\partial_{x_\alpha} \partial_{x_\alpha} p = \partial_{x_\alpha} (-D^{\mathbf{u}} u_\alpha + \nu \Delta u_\alpha)$$

Discrete

$$\partial_{x_\alpha} \partial_{x_\alpha} p \sim D_\alpha G_\alpha p$$

$$\underbrace{(Gp)_i \sim (p_{i+1} - p_{i-1})}_{\text{ }} \quad \& \quad \underbrace{(Du)_i \sim (u_{i+1} - u_{i-1})}_{\text{ }}$$

$$DGp \sim (p_{i+2} - 2p_i + p_{i-2})$$

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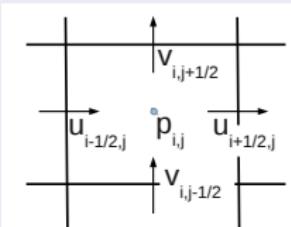
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Odd-even decoupling, nasty to solve!

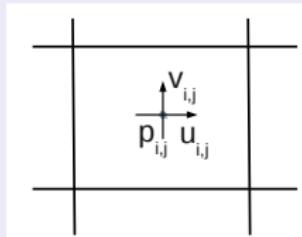
# Avoiding decoupling of $\Delta p$

## Staggered Grid



- + Simple
- + No extra damping
- Boundary non-simple
- Different geometry factors for  $p, u_\alpha$

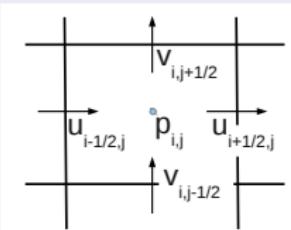
## Collocated Grid



- + Nice Boundary
- + Same geometry factors
- Upwind: Large damping
- Rhee-Chow: Smaller Damping

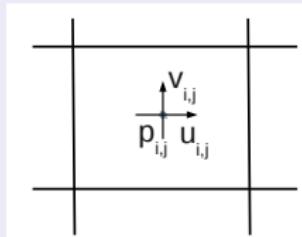
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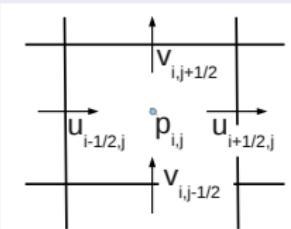


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## Skew Symmetric Schemes

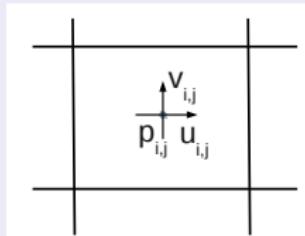
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## Skew Symmetric Schemes

— ??? —

# Discretisation

$$\partial_{x_\alpha} u_\alpha = 0$$

$$\partial_t u_\alpha + \frac{1}{2} (\partial_{x_\beta} u_\beta \cdot + u_\beta \partial_{x_\beta} \cdot) u_\alpha + \partial_{x_\alpha} p = \nu \Delta u_\alpha$$

$$D_\alpha u_\alpha = 0$$

$$\partial_t u_\alpha + \underbrace{\frac{1}{2} (D_\beta U_\beta + U_\beta G_\beta)}_{D^u} u_\alpha + G_\alpha p = \nu L u_\alpha$$

Transport term is skew symmetric

$$D^u{}^T = \frac{1}{2} (U_\beta D_\beta^T + G_\beta^T U_\beta) \equiv -D^u$$

**provided**

$$D_\beta = -G_\beta^T$$

**not necessary skew sym.!**

# Discrete Poisson Equation

$$D_\alpha u_\alpha = 0$$

$$\partial_t u_\alpha + D^{\mathbf{u}} u_\alpha + G_\alpha p = \nu L u_\alpha$$

$$D_\alpha G_\alpha p = D_\alpha (-D^{\mathbf{u}} u_\alpha + \nu L u_\alpha)$$

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$$D_\beta = -\underbrace{G_\beta^T}_{\rightarrow \text{Energy cons.}} = \frac{1}{\Delta h} \begin{pmatrix} \ddots & & \\ & -1 & 1 & 0 \\ & & \ddots & \ddots \end{pmatrix}$$

Not upwind!

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Not upwind!

# Discrete Poisson Equation

$$\begin{aligned} D_\alpha u_\alpha &= 0 \\ \partial_t u_\alpha + D^{\mathbf{u}} u_\alpha + G_\alpha p &= \nu L u_\alpha \end{aligned}$$

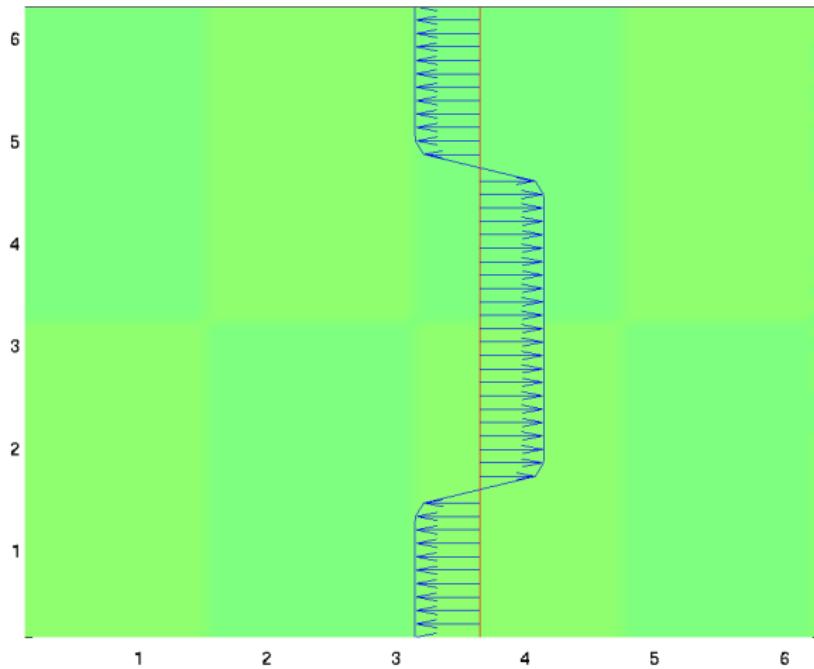
$$D_\alpha G_\alpha p = D_\alpha (-D^{\mathbf{u}} u_\alpha + \nu L u_\alpha)$$

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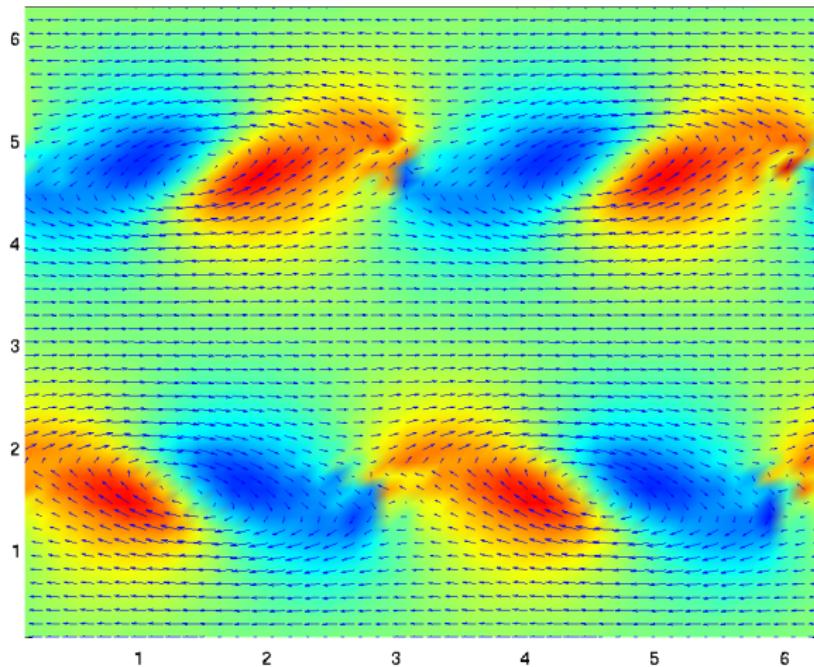
Not upwind!

$$D_\beta = \begin{pmatrix} & \ddots & & & \\ 1/6 & -1 & 1/2 & 1/3 & 0 \end{pmatrix}$$

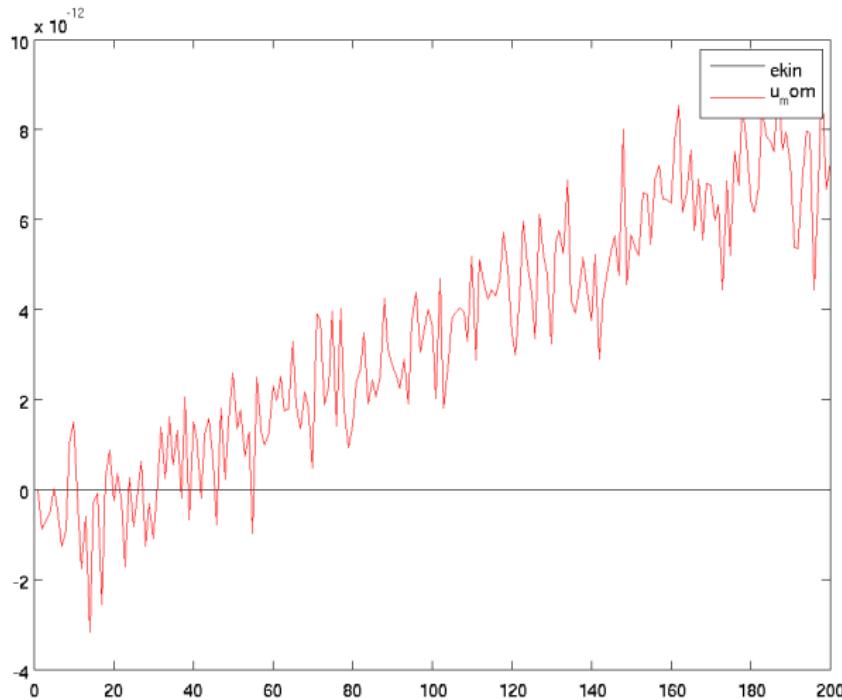
# Numerical example



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# Transformed Grids

$$D_\alpha u_\alpha = 0$$

$$\partial_t u_\alpha + \frac{1}{2} (D_\beta U_\beta + U_\beta G_\beta) u_\alpha + G_\alpha p = \nu L u_\alpha$$

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$$\partial_t u_\alpha + \frac{1}{2} (D_\beta U_\beta + U_\beta G_\beta) u_\alpha + G_\alpha p = \nu L u_\alpha$$

$$\bar{D}_\beta M_{\alpha,\beta} u_\alpha = 0$$

$$J \partial_t u_\alpha + \frac{1}{2} (\bar{D}_\gamma M_{\beta,\gamma} U_\beta + U_\beta M_{\beta,\gamma} \bar{G}_\gamma) u_\alpha + M_{\alpha,\gamma} \bar{G}_\gamma p = \nu L u_\alpha$$

$$\boxed{\bar{D}_\beta = -\bar{G}_\beta^T}$$

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$$\bar{D}_\beta = -\bar{G}_\beta^T$$

$$\Delta p \sim \bar{D}_\beta \frac{M_{\alpha,\beta} M_{\alpha,\gamma}}{J} \bar{G}_\gamma p = \dots$$

# Transformed Grids: Conservation?

$$\bar{D}_\beta M_{\alpha,\beta} u_\alpha = 0$$

$$J \partial_t u_\alpha + \frac{1}{2} (\bar{D}_\gamma M_{\beta,\gamma} U_\beta + U_\beta M_{\beta,\gamma} \bar{G}_\gamma) u_\alpha + \color{red} M_{\alpha,\gamma} \bar{G}_\gamma p = \nu L u_\alpha$$

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$$\boxed{\bar{D}_\beta = -\bar{G}_\beta^T}$$

## Energy conservation

$$\begin{aligned} & u_\alpha^T \color{red} M_{\alpha,\gamma} \bar{G}_\gamma p \\ = & p^T \bar{G}_\gamma^T M_{\alpha,\gamma} u_\alpha \\ = & -p^T \color{blue} \bar{D}_\gamma M_{\alpha,\gamma} u_\alpha \\ = & 0 \end{aligned}$$

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Energy conservation

$$\begin{aligned} & u_\alpha^T \textcolor{red}{M}_{\alpha,\gamma} \bar{G}_\gamma p \\ = & p^T \bar{G}_\gamma^T M_{\alpha,\gamma} u_\alpha \\ = & -p^T \bar{D}_\gamma M_{\alpha,\gamma} u_\alpha \\ = & 0 \end{aligned}$$

Momentum conservation

$$\begin{aligned} & \mathbf{1}^T \textcolor{red}{M}_{\alpha,\gamma} \bar{G}_\gamma p \\ = & p^T \bar{G}_\gamma^T m_{\alpha,\gamma} \\ = & -p^T \bar{D}_\gamma \textcolor{red}{m}_{\alpha,\gamma} \\ = & ? \end{aligned}$$

# Transformed Grids: Momentum Conservation

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2D

$$\bar{D}_\gamma m_{\alpha,\gamma} = \begin{pmatrix} \bar{D}_\xi y_\eta - \bar{D}_\eta y_\xi \\ \dots \end{pmatrix} = 0$$

**Provided**       $y_\xi = \bar{D}_\xi y$        $y_\eta = \bar{D}_\eta y$

# Transformed Grids: Momentum Conservation

2D

$$\bar{D}_\gamma m_{\alpha,\gamma} = \begin{pmatrix} \bar{D}_\xi y_\eta - \bar{D}_\eta y_\xi \\ \dots \end{pmatrix} = 0$$

**Provided**  $y_\xi = \bar{D}_\xi y$      $y_\eta = \bar{D}_\eta y$

3D

$$\bar{D}_\gamma^T m_{\alpha,\gamma} = \begin{pmatrix} \bar{D}_\xi(y_\eta z_\zeta - y_\zeta z_\eta) + \bar{D}_\eta(y_\zeta z_\xi - y_\xi z_\zeta) + \bar{D}_\zeta(y_\xi z_\eta - y_\eta z_\xi) \\ \dots \end{pmatrix}$$

Only zero for restricted transformations:

$$x(\xi, \eta), y(\xi, \eta), z(\zeta)$$

## Second Conclusions

We found

Schemes for the **incompressible** Navier-Stokes equation, which are

- collocated, energy and momentum conserving, by
  - ▶ use of skew symmetry  
&
  - ▶ the combination of non-symmetric derivatives
- Grid transformations preserving these properties
  - ▶ general in 2D
  - ▶ restricted in 3D
- Very simple to implement

# Conclusions

Skew symmetric Schemes are

- Skew symmetric schemes respect kinetic energy
- Avoid numerical damping
- Stable
- Simple to implement
- ... worth a try!

Thank you for your attention!

Question?

# Euler Equations, more dimensions

$$\sqrt{\rho} \partial_t (\sqrt{\rho} u_\alpha) + \frac{1}{2} [\partial_{x_\beta} \rho u_\beta \cdot + \rho u_\beta \partial_{x_\beta} \cdot] u_\alpha + \partial_{x_\alpha} p = 0.$$

Momentum equation in skew symmetric form, 2D,  $u_1 \equiv u$  component :

$$\begin{aligned} & \frac{J}{\sqrt{\rho}} \partial_t (\sqrt{\rho} u) \\ & + \frac{1}{2} \left[ (\partial_\xi \varrho (y_\eta u - x_\eta v) \cdot + \varrho (y_\eta u - x_\eta v) \partial_\xi \cdot) \right. \\ & \quad \left. + (\partial_\eta \varrho (-y_\xi u + x_\xi v) \cdot + \varrho (-y_\xi u + x_\xi v) \partial_\eta \cdot) \right] u \\ & + (\partial_\xi y_\eta - \partial_\eta y_\xi) p = 0 \end{aligned}$$

# Shock & Artificial Damping

$$\frac{1}{2}(\partial_t R + R \partial_t)u + \frac{1}{2}(DUR + RUD)u + Dp = D\tau$$

Friction Term  $\tau = \mu Du$

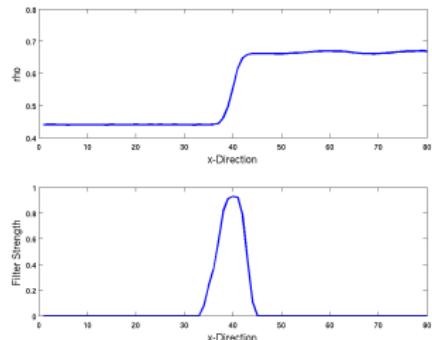
$$D\mu Du \rightarrow -F\sigma F^T u$$

with adaptive sigma:

$$\sigma = \frac{1}{2} \left( 1 - \frac{r_{th}}{r_i} + \left| 1 - \frac{r_{th}}{r_i} \right| \right)$$

with shock detector building on dilatation<sup>1</sup>

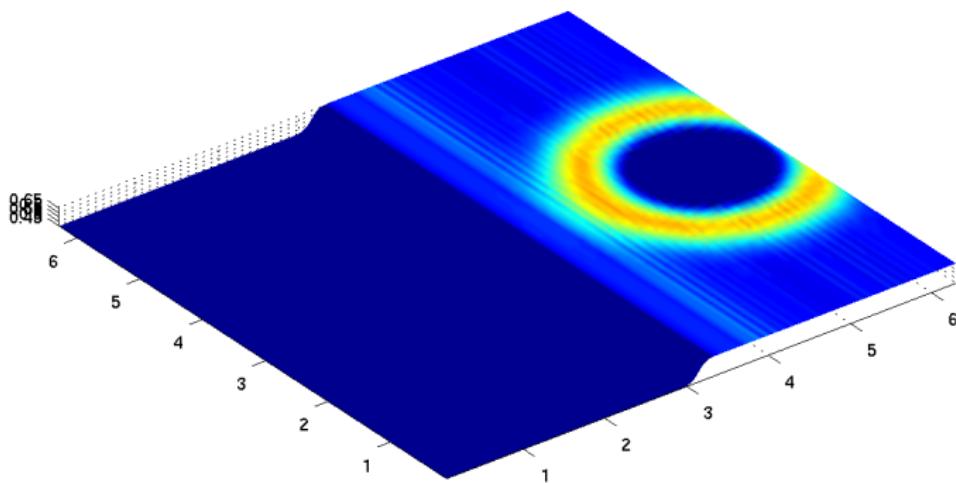
$$r_i = r_i(\nabla u)$$



<sup>4</sup>Bogey et al, JCP 228, 1447, 2009

# Where are we now?

Shock & Acoustic Pulse



$\varrho$

# Skew Symmetric discretisation

Euler Equations, time

$$\begin{aligned}\partial_t \varrho + B^u \varrho &= 0 \\ \frac{1}{2} [\partial_t R + R \partial_t] u + \frac{1}{2} D^{u\varrho} u + D_x p &= 0 \\ \frac{1}{\gamma - 1} \partial_t p + \frac{\gamma}{\gamma - 1} B^u p - C^u p &= 0\end{aligned}$$

Leap-Frog like scheme

$$\begin{aligned}\frac{1}{2\Delta t} (\varrho^{n+1} - \varrho^{n-1}) &\quad + B^{u^n} \varrho^n = 0 \\ \frac{1}{4\Delta t} ((R^{n+1} + R^n) u^{n+1} - (R^{n-1} + R^n) u^{n-1}) &\quad + \frac{1}{2} D^{u^n \varrho^n} u^n + D_x p^n = 0 \\ \frac{1}{\gamma - 1} \frac{1}{2\Delta t} (p^{n+1} - p^{n-1}) &\quad + \gamma \frac{B^{u^n} p^n}{\gamma - 1} - C^{u^n} p^n = 0\end{aligned}$$

# Skew Symmetric discretisation

Euler Equations, implicit time

mass

$$\frac{1}{2\Delta t} (\varrho^{n+1} - \varrho^{n-1}) + \frac{1}{8} D ((u\varrho)^{n-1} + 6(u\varrho)^n + (u\varrho)^{n+1}) = 0$$

velocity

$$\begin{aligned} & \frac{1}{4\Delta t} ((R^{n+1} + R^n)u^{n+1} - (R^{n-1} + R^n)u^{n-1}) + \\ & \frac{1}{2} \frac{1}{8} \left( D^{(u\varrho)^{n-1}} u^{n-1} + D^{(u\varrho)^n} (u^{n-1} + 4u^n + u^{n+1}) + D^{(u\varrho)^{n+1}} u^{n+1} \right) \\ & + \frac{1}{4} D_x (p^{n-1} + 2p^n + p^{n+1}) = 0 \end{aligned}$$

pressure

$$\begin{aligned} 0 &= \frac{1}{\gamma-1} \frac{1}{2\Delta t} (p^{n+1} - p^{n-1}) + \\ & \frac{\gamma}{4\gamma-1} D ((up)^{n-1} + 2(up)^n + (up)^{n+1}) - \frac{1}{4} u^n D (p^{n-1} + 2p^n + p^{n+1}) \end{aligned}$$

# Time Integration

Energy conservation

Time integration by midpoint rule produces energy conservation

$$\frac{u^{n+1} - u^n}{\Delta t} + \frac{1}{3} D^{u^{n+1/2}} u^{n+1/2} = 0$$

Multiplying by  $(u^{n+1/2})^T = \frac{1}{2}(u^n + u^{n+1})^T$

$$\frac{1}{2}(u^n + u^{n+1})^T \frac{u^{n+1} - u^n}{\Delta t} + \frac{1}{3} \underbrace{(u^{n+1/2})^T D^{u^{n+1/2}} u^{n+1/2}}_{=0} = 0$$

# Time Integration

Energy conservation

Time integration by midpoint rule produces energy conservation

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Multiplying by  $(u^{n+1/2})^T = \frac{1}{2}(u^n + u^{n+1})^T$

$$\frac{1}{2}(u^n + u^{n+1})^T \frac{u^{n+1} - u^n}{\Delta t} = 0$$

gives

$$\frac{1}{2} \left( (u^{n+1})^T u^{n+1} - (u^n)^T u^n \right) = 0$$

# Time Integration

## Momentum conservation

Time integration by midpoint rule produces momentum conservation

Multiplying by  $(\vec{1})^T = (1, 1, 1, 1, 1, \dots)$

$$(\vec{1})^T \frac{u^{n+1} - u^n}{\Delta t} + \frac{1}{3} (\vec{1})^T D^{u^{n+1/2}} u^{n+1/2} = 0$$

with

$$\begin{aligned} & (\vec{1})^T D^{u^{n+1/2}} u^{n+1/2} \\ = & (\vec{1})^T D U^{n+1/2} + (u^{n+1/2})^T D u^{n+1/2} = 0 \end{aligned}$$

gives

$$\frac{1}{2} \left( \sum_i u_i^{n+1} - \sum_i u_i^n \right) = 0$$

# Euler Equations, more dimensions

$$\frac{1}{2} (\partial_t \varrho + \varrho \partial_t) u_i + \frac{1}{2} [\nabla \varrho \vec{u} + \varrho \vec{u} \cdot \nabla] u_i + \nabla p = 0.$$

Use divergence as

$$\nabla \mathbf{u} = \frac{1}{J} \sum_{i,cy} \partial_{\xi^i} (\mathbf{e}_j \times \mathbf{e}_k) \mathbf{u} = \frac{1}{J} \sum_{i,cy} (\mathbf{e}_j \times \mathbf{e}_k) \partial_{\xi^i} \mathbf{u}.$$

Momentum equation in skew symmetric form

$$\begin{aligned} \frac{1}{2} (\partial_t \varrho + \varrho \partial_t) u_\alpha + \frac{1}{2} \frac{1}{J} \sum_{i,cy} & \left( \partial_{\xi^i} (\mathbf{e}_j \times \mathbf{e}_k) \varrho \mathbf{u} + (\mathbf{e}_j \times \mathbf{e}_k) \varrho \mathbf{u} \partial_{\xi^i} \right) u_\alpha \\ & + \left( \frac{1}{J} \sum_{i,cy} \partial_{\xi^i} (\mathbf{e}_j \times \mathbf{e}_k) p \right)_\alpha = 0 \end{aligned}$$

... is indeed skew symmetric!

# Time discretization

$$\begin{aligned}\partial_t \varrho + \quad & RHS_{\varrho} = 0 \\ \frac{1}{2} [\partial_t R + R \partial_t] u + \quad & RHS_u = 0 \\ \frac{1}{\gamma - 1} \partial_t p + \quad & RHS_p = 0\end{aligned}$$

Central scheme 3-step

$$\begin{aligned}\frac{1}{2\Delta t} (\varrho^{n+1} - \varrho^{n-1}) & + RHS_{\varrho} = 0 \\ \frac{1}{4\Delta t} ((R^{n+1} + R^n)u^{n+1} - (R^{n-1} + R^n)u^{n-1}) & + RHS_u = 0 \\ \frac{1}{\gamma-1} \frac{1}{2\Delta t} (p^{n+1} - p^{n-1}) & + RHS_p = 0\end{aligned}$$

# Skew Symmetric discretisation

Euler Equations, time

$$mass^{n+\frac{1}{2}} = \mathbf{1}^T \frac{(\varrho^n + \varrho^{n+1})}{2}$$

$$mom^{n+\frac{1}{2}} = \frac{(\varrho^n + \varrho^{n+1})^T}{2} \frac{(u^n + u^{n+1})}{2}$$

$$e_{tot}^{n+1/2} = \frac{\mathbf{1}^T}{\gamma - 1} (p^n + p^{n+1})/2 + \frac{(u^n)^T (\varrho^n + \varrho^{n+1}) u^{n+1}}{4}$$

E.g. momentum conservation

$$mom^{1/2} - mom^{N-1/2} = \sum_{n=1}^{N-1} f_{1/2} - \sum_{n=1}^{N-1} f_{N-1/2}$$

→ equivalent to FV for  $\Delta t \rightarrow 0$

End