

Grid Computing

introduction & illustration

T. Gautier
V. Danjean

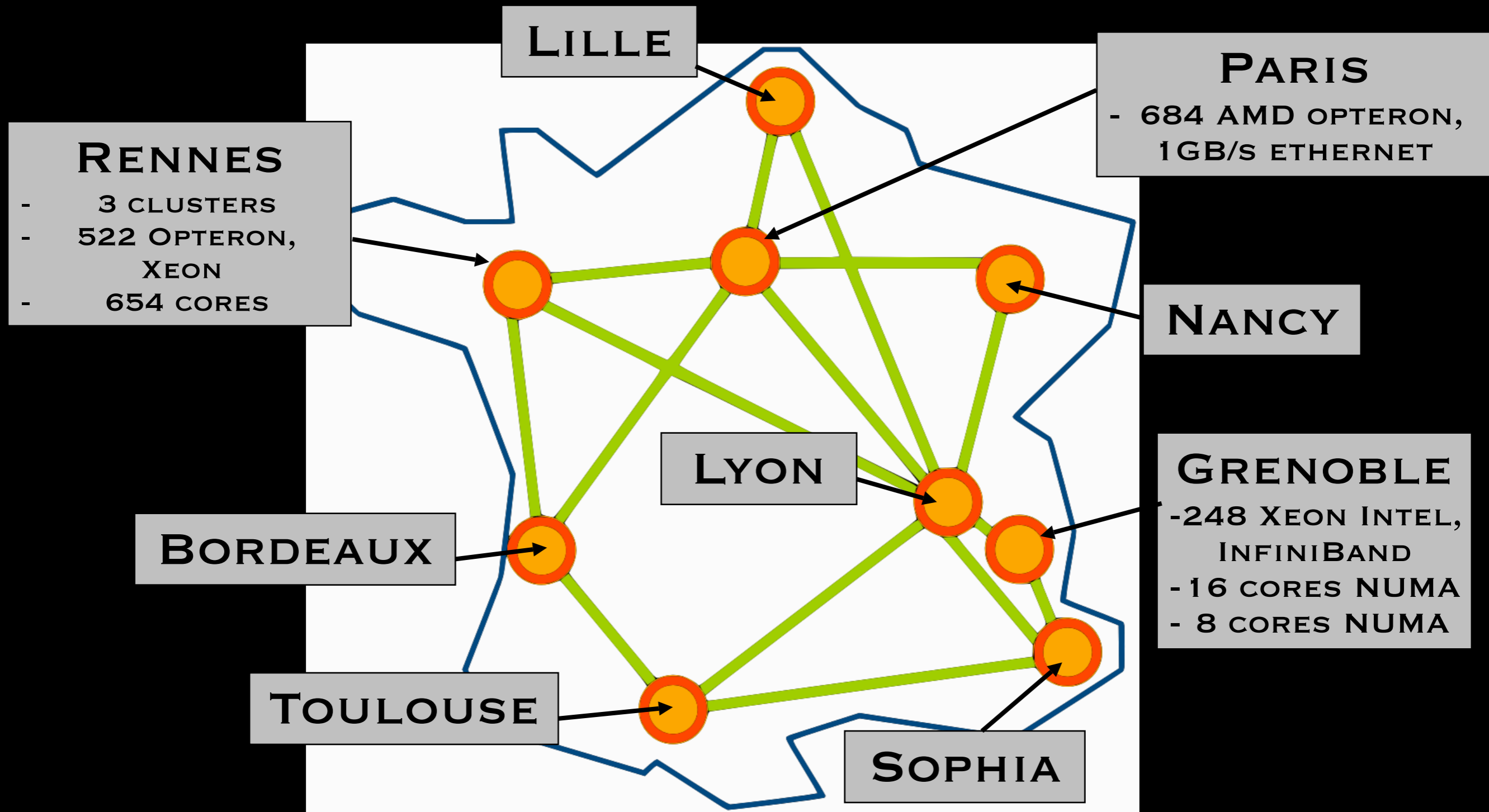
Facts

- No choice : parallelism is in any computer
 - MPSoC, Multicore, Manycore, **Cluster, Grid**
 - Exact Solution to the Quadratic Assignment Problem
 - Combinatorial Problem: NUG30, 7 days, 650 processors
 - Solving bigger CFD, CEM problems
 - 100GBytes of memory
- ➔ Cluster & Grid computing

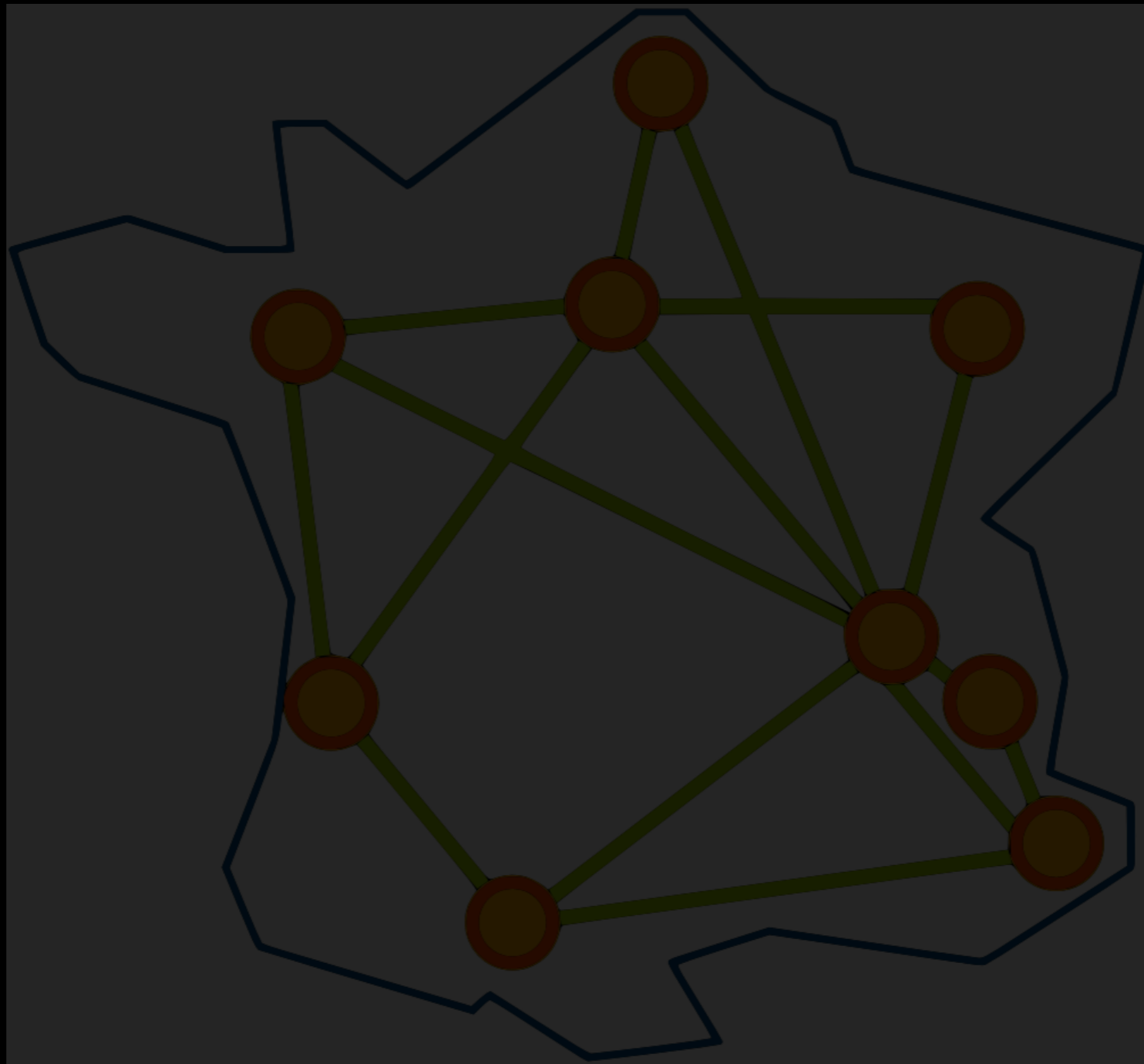
Outline

- **Context**
 - Parallel and distributed architecture
- **Programming Challenges**
 - Parallel algorithm
 - Scheduling & Communication
- **Illustration with domain decomposition method**
- **Conclusions**

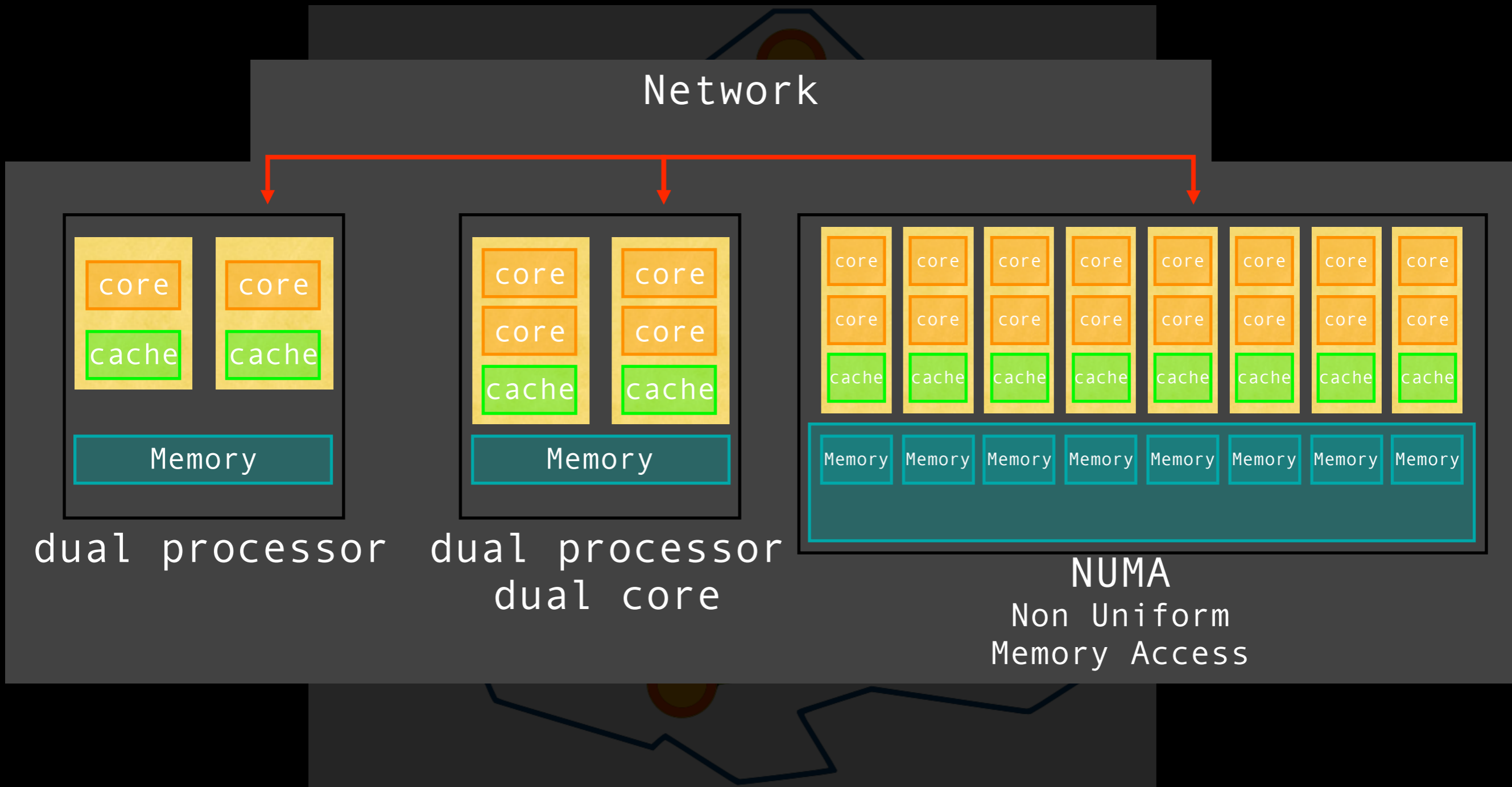
www.grid5000.fr



Grid5000



Grid5000



Characteristics

- **Cluster: set of homogeneous machines**
 - **homogeneous resources (memory, cpu)**
 - Dual, Quad, Octo cores cpu, GBytes / machine
 - **homogeneous & high performance network**
 - Ethernet, Myrinet, InfiniBand
 - **homogeneous administration domain**
 - 1 user = 1 account, home directory mounted using NFS

Characteristics

- **Grid: set of clusters**
 - **heterogeneous resources**
 - CPU, memory, network speed
 - Each cluster has different number of machines
 - **Network between clusters: high latency !**
 - **multiple administration domains**
 - 1 user = multiple account
 - access to cluster through firewall
 - **dependability problem**
 - huge number of basic components

Programming Challenges

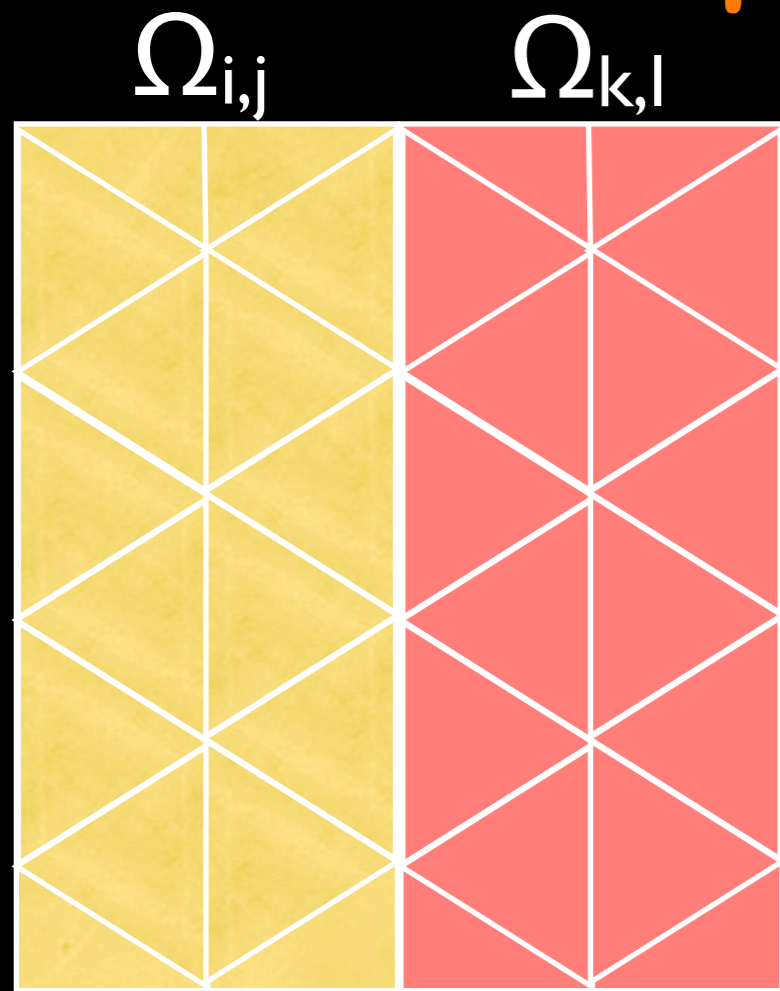
- Write once, run anywhere
 - heterogeneity !
- Keypoints
 - parallel algorithm
 - scheduling
 - implementation
 - [fault tolerance]

Parallel algorithm

- 30 years of theoretical studies & experiments of parallel architectures
- What's new ?
 - huge number of cores/CPU
 - fault tolerance
 - ABFT: Algorithm Based Fault Tolerant

Let's back to a problem

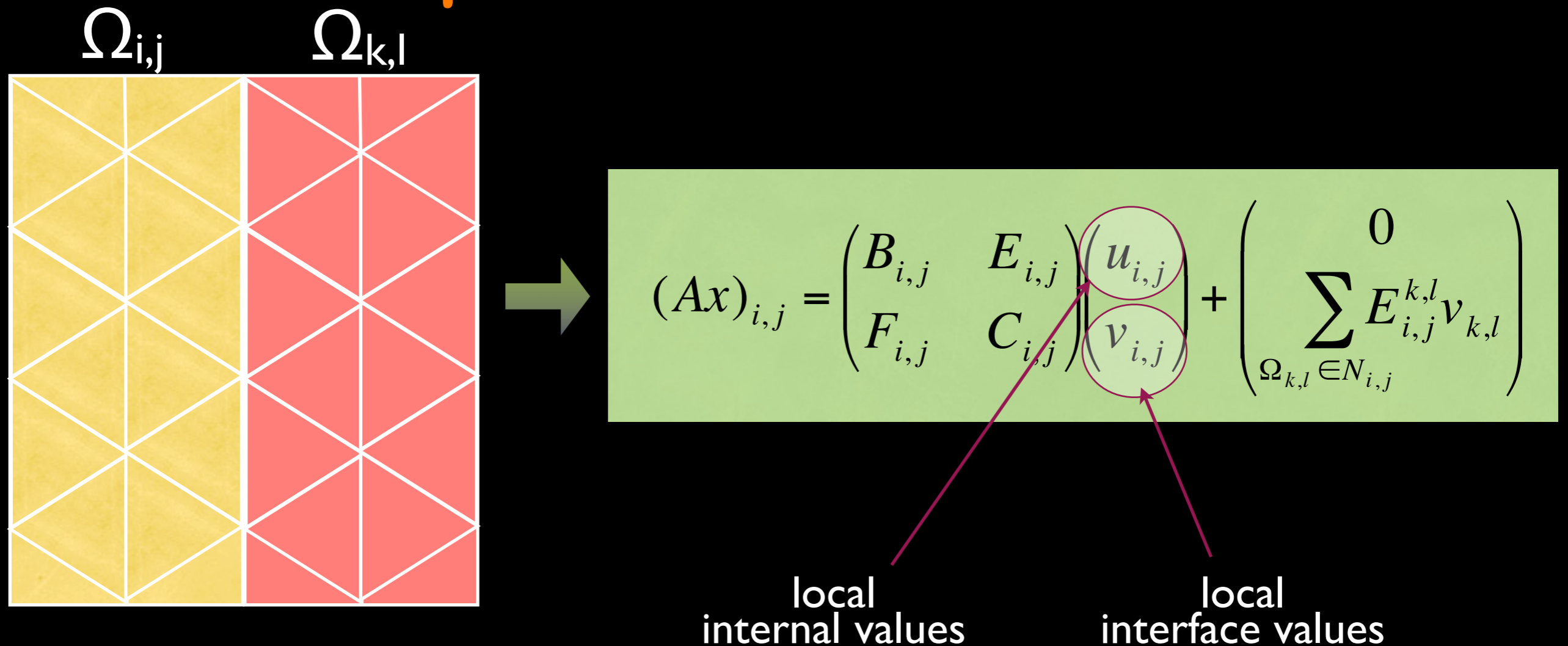
- Domain decomposition for matrix vector product



$$(Ax)_{i,j} = \begin{pmatrix} B_{i,j} & E_{i,j} \\ F_{i,j} & C_{i,j} \end{pmatrix} \begin{pmatrix} u_{i,j} \\ v_{i,j} \end{pmatrix} + \begin{pmatrix} 0 \\ \sum_{\Omega_{k,l} \in N_{i,j}} E_{i,j}^{k,l} v_{k,l} \end{pmatrix}$$

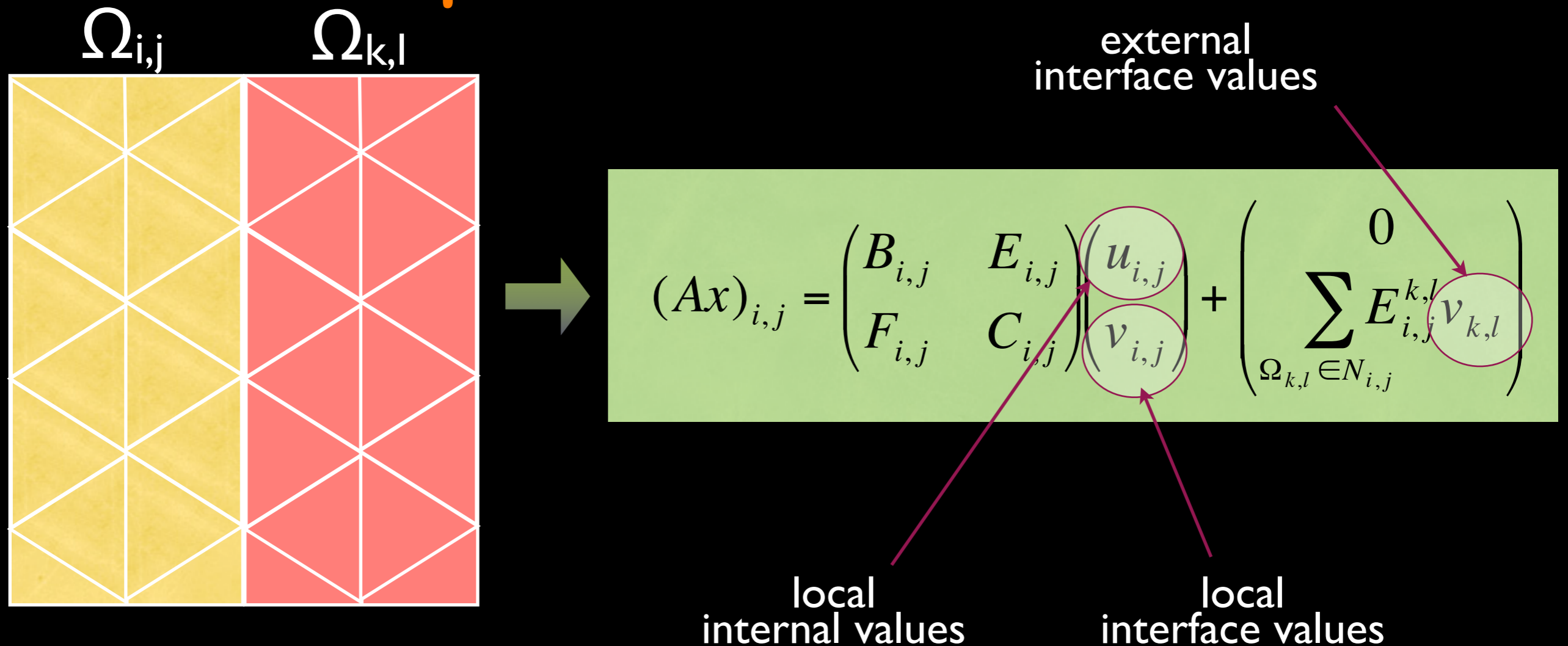
Let's back to a problem

- Domain decomposition for matrix vector product



Let's back to a problem

- Domain decomposition for matrix vector product



Scheduling

- Once tasks and data are described by a parallel algorithm then:
 - For each task, compute where to execute it
 - For each data, compute where to store it
- Such that:
 - Completion time is minimize, ...
- NP-hard problem
 - Use algorithms to approximate the problem
 - Use heuristics, application dependent

Strict multi-threaded computations

● Notations

- T_s : Sequential work, time of sequential execution
- D : Critical Path
- P : the P processors

● Properties

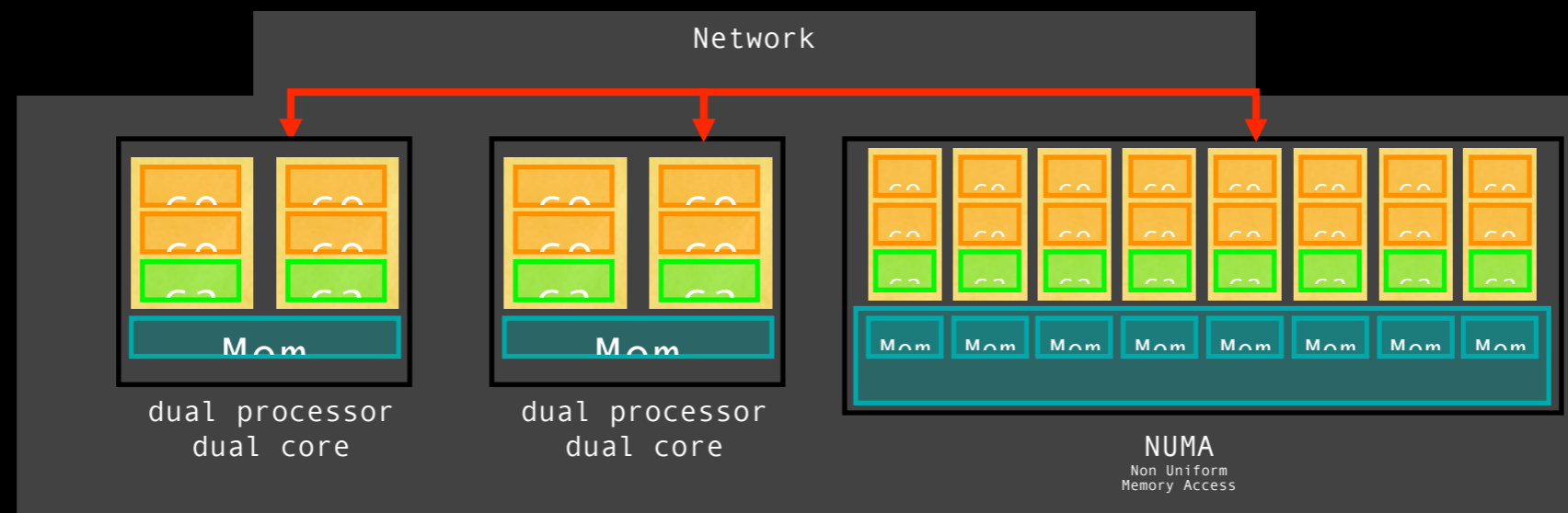
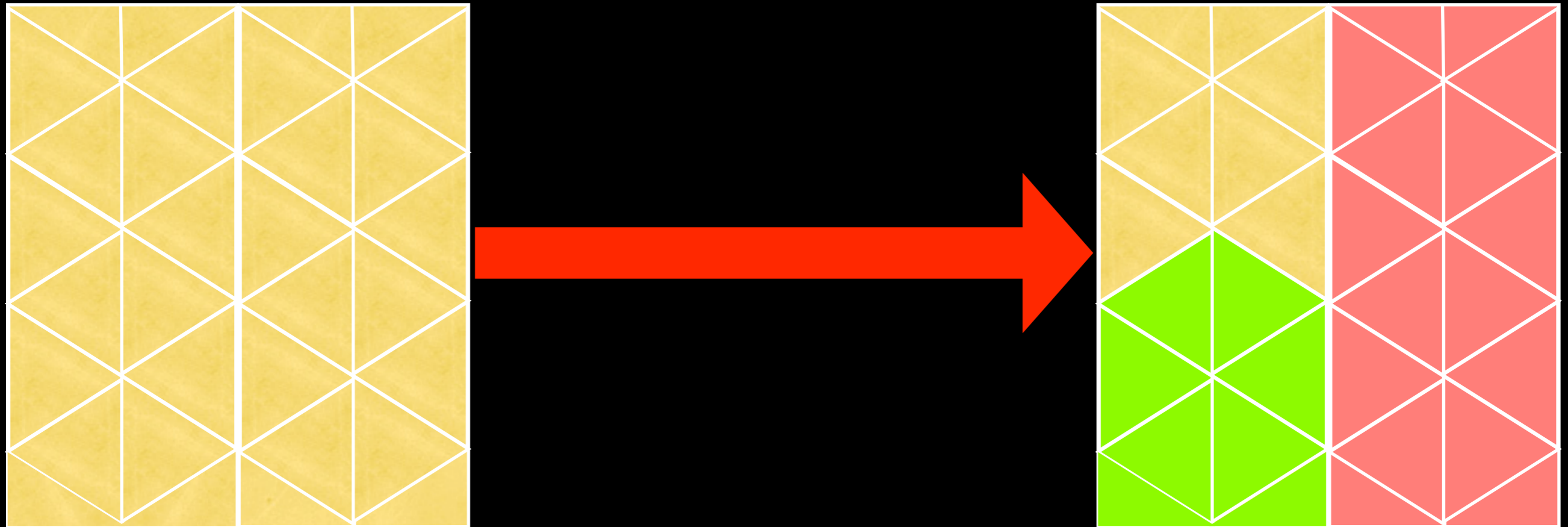
- with high probability, number of steals is

$$O(P \times D)$$

- with high probability, execution time is

$$T_p \leq T_1 / P + O(D)$$

Domain decomposition



That's all ?

- **Domain decomposition**
 - Data = sub domain, mapped onto machines
 - Task : mapped using “owner compute rule”
- **Program : one process per subdomain**

```
while (error < epsilon)
{
    exchange interface
    do computation inside subdomain
    compute error
}
```

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Communication
between neighbors



That's all ?

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  exchange interface
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  do computation inside subdomain
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```
  compute error
```

```
}
```

Communication
between neighbors

Global reduction
communication

Improvement

- Assume that emission & reception of message are concurrent with local computation

```
while (error < epsilon)
{
    begin send message to my neighbors
    do internal computation
    wait until all messages have been received
    update internal computation
    compute error
}
```

Improvement

- Assume that emission & reception of message are concurrent with local computation

```
while (error < epsilon)
```

```
{
```

```
  begin send message to my neighbors
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```
  do internal computation
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```
  wait until all messages have been received
```

```
  update internal computation
```

```
  compute error
```

```
}
```

may overlap
some delay of
communication



How to program

- **MPI, standard but low level API**
 - scheduling and mapping should be coded
 - bad overlapping of communication by **computation** (at least in public domain implementation)
 - bad support multi-threaded computations
 - bad support for inter-cluster communication
- **Research languages**
 - UPC, Titanium, X10, Fortress
 - Our language: Athapascan (API) with Kaapi
 - **AUTOMATIC SCHEDULING : <http://moais.imag.fr>**

Experiments

● Code

- Kaapi / C++ code versus Fortran MPI code

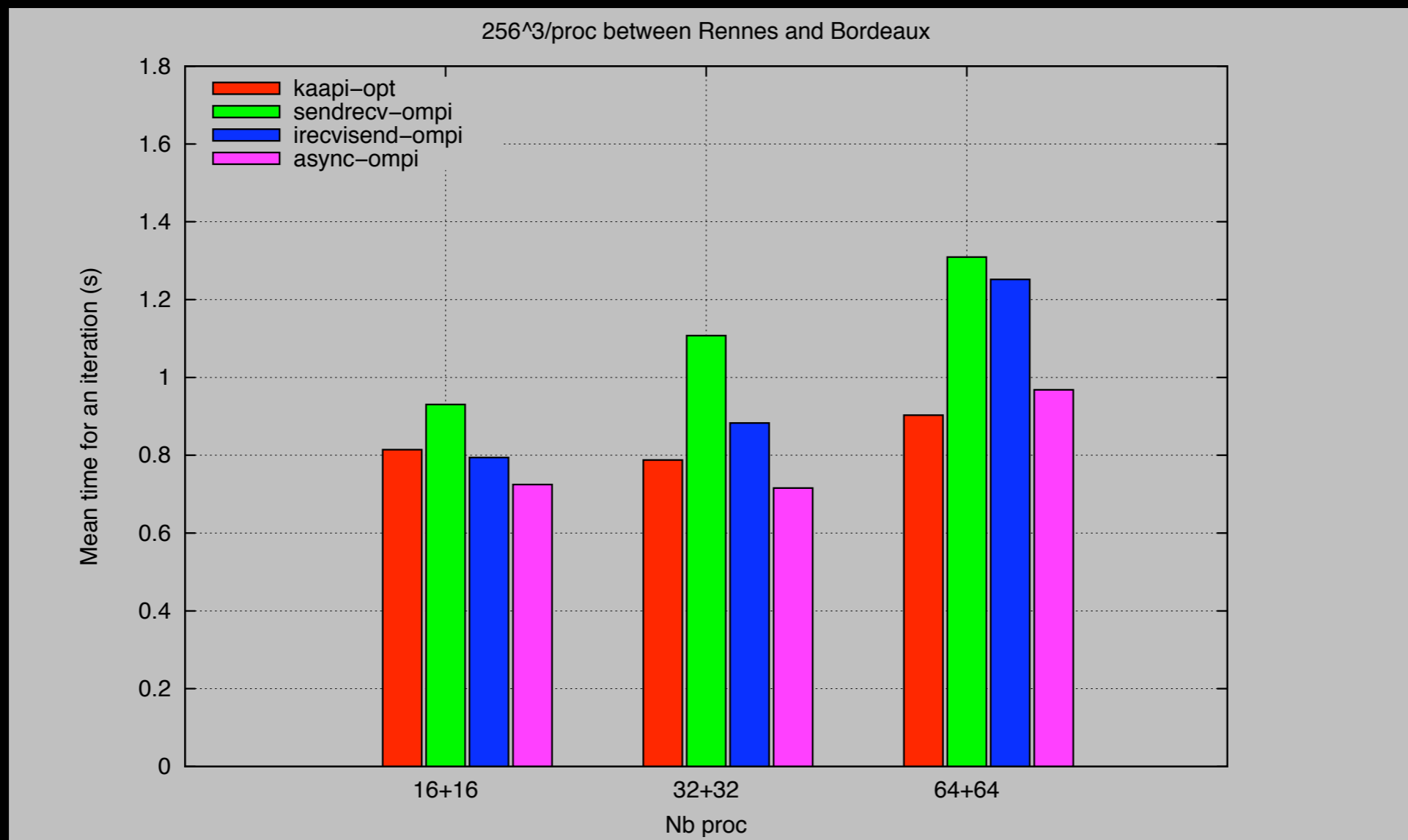
● Platform

- Cluster : N processors on a cluster
- Grid : N/4 processors per cluster, 4 clusters

D=256 ³	# processors	Cluster (s)	Grid (s)	Overhead
KAAPI	1	0.49	0.49	-
	64	0.55	0.84	0,53
	128	0.65	0.91	0,4
MPI	1	0.44	0.44	-
	64	0.66	2.02	2,06
	128	0.68	1.57	1,31

Optimized Poisson 3D

- **Fortran code with non-blocking IO**
 - MPI_IRecv, MPI_IRecv + MPI_Wait_all
 - Overlapping of communication by computation



Conclusion

● SCHEDULING

- but also compilation, grid-reservation, parallel launching, runtime environment, firewall management, ...

● More references

- Herlihy, M. and Shavit, N. The Art of Multiprocessor Programming, ISBN 0123705916. Morgan Kaufmann Publishing, 2008.
- Foster I., Kesselman C. The GRID 2: Blueprint for a New Computing Infrastructure, ISBN 1558609334. Morgan Kauffman Publishing, 2 edition, 1999.
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