



Discontinuous Galerkin methods for aerodynamic flows

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Aerodynamic

Navier-Stokes equations

- ▶ viscous compressible Navier-Stokes equations

$$\begin{cases} \partial_t \rho + \operatorname{div}_x(\rho \mathbf{u}) = 0 \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}_x(\rho \mathbf{u} \otimes \mathbf{u} + P \mathbf{I}) = \operatorname{div}_x \boldsymbol{\tau} \\ \partial_t(\rho E) + \operatorname{div}_x((\rho E + P) \mathbf{u}) = \operatorname{div}_x(\boldsymbol{\tau} \cdot \mathbf{u}) + \operatorname{div}_x(\lambda \nabla T) \end{cases}$$

$$\boldsymbol{\tau} = \mu \left(\nabla \otimes \mathbf{u} + (\nabla \otimes \mathbf{u})^T \right) - \frac{2\mu}{3} (\operatorname{div}_x \mathbf{u}) \mathbf{I}$$

- ▶ Closure conditions

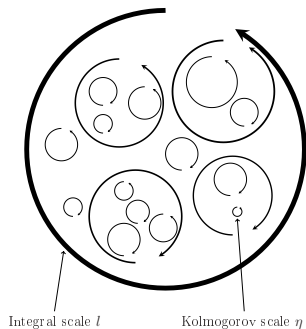
$$E = \frac{|\mathbf{u}|^2}{2} + \varepsilon \quad P = P(\varepsilon, \rho) \quad T = T(\varepsilon, \rho)$$

- ▶ Difficulties

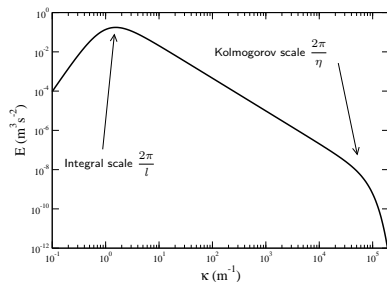
- ▶ Nonlinear system
- ▶ hyperbolic terms
- ▶ parabolic terms

Aerodynamic

Turbulent flows



Physical space



Fourier space

- ▶ Integral scale l
- ▶ Kolmogorov scale η

Aerodynamic

Turbulent flows

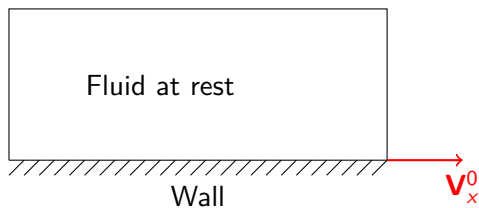
- ▶ Different flow configurations

$$\partial_t(\rho \mathbf{u}) + \operatorname{div}_{\mathbf{x}}(\rho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{Ma} \nabla P = \frac{1}{Re} \operatorname{div}_{\mathbf{x}} \tau$$

- ▶ **Re** Reynolds number
- ▶ **Ma** Mach number
- ▶ **Computational cost**
 - ▶ Resolution scale (size of the cells) is driven by the **smallest scales** η .
 - ▶ $\frac{l}{\eta} \sim Re^{3/4}$
 - ▶ Mesh size increases as $Re^{9/4}$.

Aerodynamic

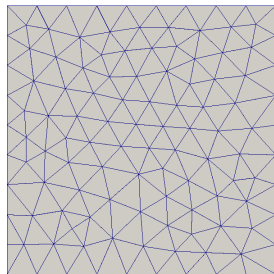
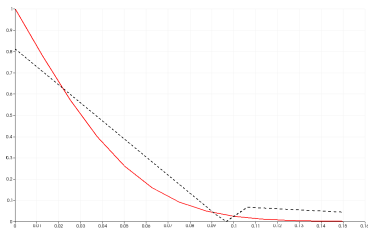
Boundary layer



$$\mathbf{v}_x(t, x) = \mathbf{v}_x^0 \left(1 - \operatorname{erf} \left(\frac{y}{\sqrt{4\nu t}} \right) \right)$$

Aerodynamic

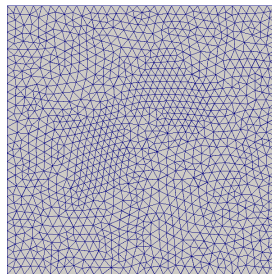
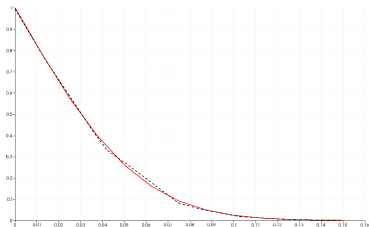
Boundary layer


 $N = 200$

$$\mathbf{v}_x(t, x) = \mathbf{v}_x^0 \left(1 - \operatorname{erf} \left(\frac{y}{\sqrt{4\nu t}} \right) \right)$$

Aerodynamic

Boundary layer

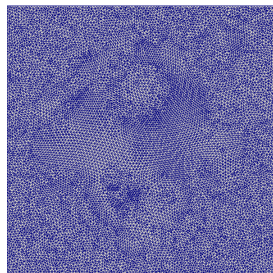
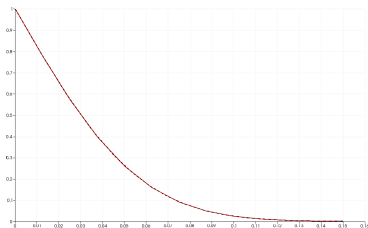


$$N = 2326$$

$$\mathbf{v}_x(t, x) = \mathbf{v}_x^0 \left(1 - \operatorname{erf} \left(\frac{y}{\sqrt{4\nu t}} \right) \right)$$

Aerodynamic

Boundary layer

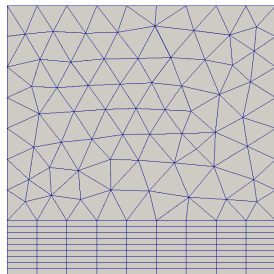
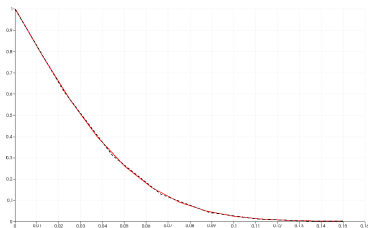


$$N = 22804$$

$$\mathbf{v}_x(t, x) = \mathbf{v}_x^0 \left(1 - \operatorname{erf} \left(\frac{y}{\sqrt{4\nu t}} \right) \right)$$

Aerodynamic

Boundary layer



$$N = 223$$

$$\mathbf{v}_x(t, x) = \mathbf{v}_x^0 \left(1 - \operatorname{erf} \left(\frac{y}{\sqrt{4\nu t}} \right) \right)$$

Use hybrid meshes

Aerodynamic

Turbulence modelling

- ▶ Direct Numerical Simulation
 - ▶ mesh size scales as $Re^{9/4}$; Re^3 in boundary layers
 - ▶ timestep scales as $Re^{-3/4}$
 - ▶ might be available in 2080 (Spalart, Boeing).
- ▶ Use turbulence models
 - ▶ Reynolds Averaged Navier Stokes (RANS)
 - ▶ fully time filtered (stationary)
 - ▶ Mesh loop adaptation
 - ▶ Standard in industry
 - ▶ Large Eddy Simulation: partially time filtered
 - ▶ Reliable if the mesh is fine enough
 - ▶ Mesh adaptation at each time step?
 - ▶ Beware of diffusion ▶ Example Vortex
 - ▶ Hybrid RANS/LES

Aerodynamic

Turbulence modelling

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 - ▶ Hybrid RANS/LES

Need for high order schemes

Aerodynamic

Which scheme?

We want

- ▶ Work on unstructured hybrid meshes.
 - ▶ Discretize convection problems (upwinding of the fluxes).
 - ▶ Have a compact scheme.
-
- ▶ Punctual approximations
 - ▶ **Finite differences**: structured meshes, filters for stability
 - ▶ Weak approximations
 - ▶ High order **Finite volumes**: uncompact stencil
 - ▶ **Continuous Galerkin**: difficulties for upwinding, non diagonal mass matrix.

⇒ Discontinuous Galerkin

Outline

Numerical scheme for compressible Navier-Stokes equations

- Advection terms

- Diffusion terms

- Efficient implementation

Discontinuous Galerkin methods for low (but not zero) Mach flow

- Review of the steady case

- Problem in the unsteady case

- A new scheme stable for both steady and unsteady flow

Application

Outline

Numerical scheme for compressible Navier-Stokes equations

- Advection terms

- Diffusion terms

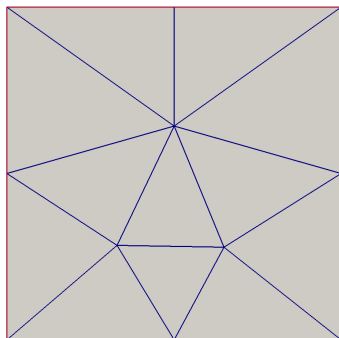
- Efficient implementation

Discontinuous Galerkin methods for low (but not zero) Mach flow

Application

Notations

- ▶ We consider a mesh \mathcal{T}_h



- ▶ S_b boundary faces
- ▶ S_i interior faces
- ▶ \mathbf{n}^S outward normal of the face S
- ▶ \mathbf{n}^{out} outward normal from an element

$$\varphi^R(\mathbf{x}) = \lim_{\varepsilon \rightarrow 0, \varepsilon > 0} \varphi(\mathbf{x} + \varepsilon \mathbf{n}^S) \quad \text{et} \quad \varphi^L(\mathbf{x}) = \lim_{\varepsilon \rightarrow 0, \varepsilon > 0} \varphi(\mathbf{x} - \varepsilon \mathbf{n}^S)$$

$$\llbracket \varphi \rrbracket(\mathbf{x}) = \varphi^R(\mathbf{x}) - \varphi^L(\mathbf{x}) \quad \text{and} \quad \{\!\!\{ \varphi \}\!\!\}(\mathbf{x}) = \frac{\varphi^R(\mathbf{x}) + \varphi^L(\mathbf{x})}{2}.$$

- ▶ Integrate the equation $\varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(\mathbf{u}) = 0$
- ▶ \mathbf{u} and φ are continuous in the cells, discontinuous on the faces

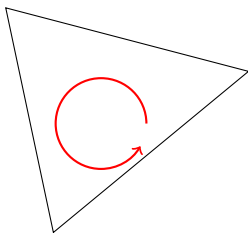
$$\int_{\Omega} \varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(u) = \sum_{T \in \mathcal{T}_h} \int_T \varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(u) + \sum_{S \in \mathcal{S}_i} \int_S \hat{\varphi} [\mathbf{f}(u)] \cdot \mathbf{n}^S$$

where $\hat{\varphi}$ is the **test function numerical flux**

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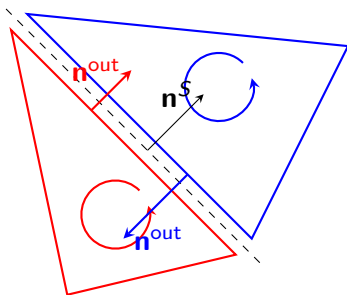
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where $\hat{\varphi}$ is the **test function numerical flux**

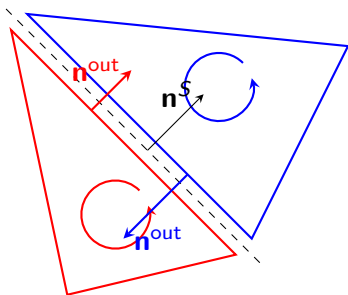


- ▶ Stokes formula

$$\begin{aligned} &= \int_T \operatorname{div}_{\mathbf{x}} (\varphi \mathbf{f}(\mathbf{u})) - \int_T \mathbf{f}(\mathbf{u}) \nabla \varphi \\ &= \int_{\partial T} \varphi \mathbf{f}(\mathbf{u}) \cdot \mathbf{n}^{\text{out}} - \int_T \mathbf{f}(\mathbf{u}) \nabla \varphi \\ &= \sum_{S \in \partial T} \int_S \varphi \mathbf{f}(\mathbf{u}) \cdot \mathbf{n}^{\text{out}} - \int_T \mathbf{f}(\mathbf{u}) \nabla \varphi \end{aligned}$$

Face integrals and numerical flux $\hat{\varphi}$ 

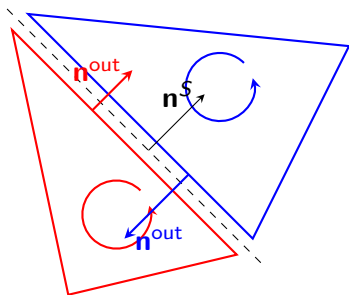
$$\begin{aligned}
 & \sum_{T \in \mathcal{T}_h} \sum_{S \in \partial T} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}} \\
 &= - \sum_{S \in \mathcal{S}_i} \int_S \llbracket \varphi \mathbf{f}(u) \rrbracket \cdot \mathbf{n}^S \\
 & \quad + \sum_{S \in \mathcal{S}_b} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}}
 \end{aligned}$$

Face integrals and numerical flux $\hat{\varphi}$ 

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$$\llbracket ab \rrbracket = \{ \{ a \} \} \llbracket b \rrbracket + \llbracket a \rrbracket \{ \{ b \} \}$$

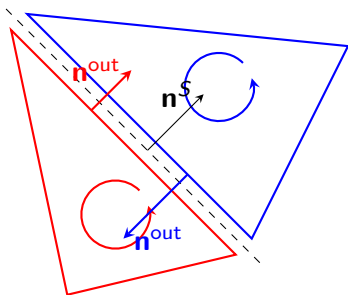
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$$[[ab]] = \{\{a\}\} [[b]] + [[a]] \{\{b\}\}$$

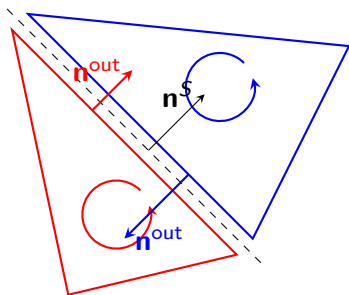
$$\begin{aligned} \int_{\Omega} \varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(u) &= - \sum_{T \in \mathcal{T}_h} \int_T \mathbf{f}(u) \nabla \varphi - \sum_{S \in \mathcal{S}_i} \int_S [[\varphi]] \{\{ \mathbf{f}(u) \} \} \cdot \mathbf{n}^S \\ & \quad - \sum_{S \in \mathcal{S}_i} \int_S \{\{ \varphi \} \} [[\mathbf{f}(u)]] \cdot \mathbf{n}^S + \sum_{S \in \mathcal{S}_b} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}} \\ & \quad + \sum_{S \in \mathcal{S}_i} \int_S \hat{\varphi} [[\mathbf{f}(u)]] \cdot \mathbf{n}^S \end{aligned}$$

Face integrals and numerical flux $\hat{\varphi}$ 

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$$\begin{aligned} \int_{\Omega} \varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(u) &= - \sum_{T \in \mathcal{T}_h} \int_T \mathbf{f}(u) \nabla \varphi - \sum_{S \in \mathcal{S}_i} \int_S \llbracket \varphi \rrbracket \{\{ \mathbf{f}(u) \} \} \cdot \mathbf{n}^S \\ & \quad - \sum_{S \in \mathcal{S}_i} \int_S \{\{ \varphi \} \} \llbracket \mathbf{f}(u) \rrbracket \cdot \mathbf{n}^S + \sum_{S \in \mathcal{S}_b} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}} \\ & \quad + \sum_{S \in \mathcal{S}_i} \int_S \hat{\varphi} \llbracket \mathbf{f}(u) \rrbracket \cdot \mathbf{n}^S \end{aligned}$$

Face integrals and numerical flux $\hat{\varphi}$ 

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$$[[ab]] = \{\{a\}\} [b] + [a] \{\{b\}\}$$

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Numerical flux

$$\int_{\Omega} \varphi \operatorname{div}_{\mathbf{x}} \mathbf{f}(u) = - \sum_{T \in \mathcal{T}_h} \int_T \mathbf{f}(u) \nabla \varphi - \sum_{S \in \mathcal{S}_i} \int_S [\![\varphi]\!] \{ \{ \mathbf{f}(u) \} \} \cdot \mathbf{n}^S + \sum_{S \in \mathcal{S}_b} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}}$$

- ▶ For stabilizing, use a **numerical flux** ▶ Riemann solver example

$$\{ \{ \mathbf{f}(u) \} \} \approx \tilde{\mathbf{f}}(\mathbf{u}^L, \mathbf{u}^R)$$

- ▶ Lax-Friedrich scheme

$$\tilde{\mathbf{f}}(\mathbf{u}^L, \mathbf{u}^R) = \frac{\mathbf{f}(\mathbf{u}^L) + \mathbf{f}(\mathbf{u}^R)}{2} - \frac{\lambda}{2} (\mathbf{u}^R - \mathbf{u}^L)$$

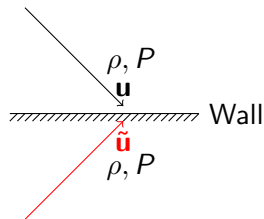
- ▶ Similar to penalization terms, **right physical scaling**

Boundary conditions

$$\sum_{S \in S_b} \int_S \varphi \mathbf{f}(u) \cdot \mathbf{n}^{\text{out}}$$

- ▶ **Inlet/outlet** boundary conditions: use characteristic decomposition
- ▶ **Slipping wall** boundary condition: normal velocity vanishes, no flux on mass nor energy
- ▶ $\tilde{\mathbf{u}} = \mathbf{u} - 2(\mathbf{u} \cdot \mathbf{n})\mathbf{n}$
- ▶ Use the **Lax Friedrich** scheme

$$\left(\begin{array}{c} 0 \\ [P + (\lambda + \mathbf{u} \cdot \mathbf{n})(\mathbf{u} \cdot \mathbf{n} - 0)] \cdot \mathbf{n} \\ 0 \end{array} \right)$$



Diffusive part

- ▶ Original system

$$\begin{cases} \operatorname{div}_{\mathbf{x}}(A\nabla\mathbf{U}) = 0 & \text{on } \Omega \\ A\frac{\partial\mathbf{U}}{\partial\mathbf{n}} = f_n & \text{on } \Gamma_n \\ \mathbf{U} = \mathbf{U}^b & \text{on } \Gamma_d \end{cases}$$

- ▶ Mixed formulation

$$\begin{cases} \operatorname{div}_{\mathbf{x}}(A\mathbf{z}) = 0 & \text{on } \Omega \\ \nabla\mathbf{U} = \mathbf{z} & \text{on } \Omega \\ A\mathbf{z} \cdot \mathbf{n} = f_n & \text{on } \Gamma_n \\ \mathbf{U} = \mathbf{U}^b & \text{on } \Gamma_d \end{cases}$$

- ▶ Perform advection scheme on both equations.

Diffusive part

- ▶ Equivalent to **lifting** the gradient: the gradient is the sum of a **cell contribution** and **face jumps contribution**

$$z = \nabla U + R(\llbracket \mathbf{U} \rrbracket)$$

- ▶ BR1 formulation: global lifting

$$\forall \mathbf{g} \quad \int_{\Omega} \mathbf{g} \cdot R(\llbracket \mathbf{U} \rrbracket) = - \sum_{S \in \mathcal{S}_i} \int_{S_i} \{\{\mathbf{g}\}\} \cdot \llbracket \mathbf{U} \rrbracket$$

- ▶ BR2 formulation: local lifting

$$\forall S_i \quad \forall \mathbf{g} \quad \int_{T \ni S_i} \mathbf{g} \cdot R^{S_i}(\llbracket \mathbf{U} \rrbracket) = - \int_{S_i} \{\{\mathbf{g}\}\} \cdot \llbracket \mathbf{U} \rrbracket$$

Diffusive part

Final scheme

$$\begin{aligned}
 & - \sum_{T \in \mathcal{T}_h} \int_T \nabla \varphi \cdot A \nabla \mathbf{U} \\
 & + \sum_{S \in \mathcal{S}_i} \int_{S_i} [\{ \{ A^T \nabla \varphi \} \} \cdot [\mathbf{U}] + \{ \{ A \nabla \mathbf{U} \} \} \cdot [\varphi]] \\
 & + \sum_{S \in \mathcal{S}_i} \int_{S_i} \eta \{ \{ A R^{S_i}([\mathbf{U}]) \} \} [\varphi] \\
 & + \sum_{S \in \mathcal{S}_b} \dots = 0
 \end{aligned}$$

- ▶ η = the number of faces

Practical implementation of the BR2 scheme

Symmetry term

- ▶ Compute

$$\int_{S_i} \left\{ \left\{ A^T \nabla \varphi \right\} \right\} \cdot [\mathbf{U}]$$

- ▶ Transformed as

$$\frac{1}{2} (\nabla \varphi_L A(\mathbf{U}_L) [\mathbf{U}] \otimes \mathbf{n} + \nabla \varphi_R A(\mathbf{U}_R) [\mathbf{U}] \otimes \mathbf{n})$$

Practical implementation of the BR2 scheme

Gradient lifting

- ▶ Compute

$$\int_{T \ni S} \mathbf{g} \cdot R^S([\mathbf{U}]) = - \int_{S_i} \{\{\mathbf{g}\}\} \cdot [\mathbf{U}]$$

- ▶ Project R^{S_i} on the finite element basis

$$R^S = \sum_{\varphi_{i_L} \in T_L} R_{i_L}^S \varphi_{i_L}^L + \sum_{\varphi_{i_R} \in T_R} R_{i_R}^S \varphi_{i_R}^R$$

- ▶ Test with $g = \varphi_i^R$ and $g = \varphi_i^L$

$$\text{for } K = L \text{ or } R \quad M_K R^{S,K} = M_S^{K,R} \mathbf{U}^R - M_S^{K,L} \mathbf{U}^L$$

$$\text{with} \quad M_K = \left(\int_K \varphi_i^K \varphi_j^K \right) \quad \text{and} \quad M_S^{K,R} = \frac{1}{2} \left(\int_S \varphi_i^R \varphi_j^K \right)$$

Practical implementation of the BR2 scheme

Factorization

- ▶ We want to compute

$$\{A \nabla \mathbf{U}\} \cdot [\varphi] + \eta \left\{ AR^{S_i}([\mathbf{U}]) \right\} [\varphi]$$

- ▶ Develop

$$\begin{aligned} & \frac{1}{2} A(\mathbf{U}_L) \nabla \mathbf{U}_L + \frac{1}{2} A(\mathbf{U}_R) \nabla \mathbf{U}_R + \frac{\eta}{2} (A(\mathbf{U}_L) R_L^S([\mathbf{U}]) + A(\mathbf{U}_R) R_L^S([\mathbf{U}])) \\ = & \frac{1}{2} A(\mathbf{U}_L) \nabla \mathbf{U}_L + \frac{1}{2} A(\mathbf{U}_R) \nabla \mathbf{U}_R + \frac{\eta}{2} \left(A(\mathbf{U}_L) \left(M_L^{-1} M_S^{L,R} \mathbf{U}^R - M_L^{-1} M_S^{L,L} \mathbf{U}_L \right) \right. \\ & \left. + A(\mathbf{U}_R) \left(M_R^{-1} M_S^{R,R} \mathbf{U}^R - M_R^{-1} M_S^{R,L} \mathbf{U}_L \right) \right) \end{aligned}$$

- ▶ Factorize

$$\begin{aligned} & \frac{1}{2} A(\mathbf{U}_L) \left(\nabla \mathbf{U}_L - \eta M_L^{-1} M_S^{L,L} \mathbf{U}_L + \eta M_L^{-1} M_S^{L,R} \mathbf{U}^R \right) \\ & + \frac{1}{2} A(\mathbf{U}_R) \left(\nabla \mathbf{U}_R + \eta M_R^{-1} M_S^{R,R} \mathbf{U}^R - \eta M_R^{-1} M_S^{R,L} \mathbf{U}_L \right) \end{aligned}$$

Boundary conditions

- ▶ Aim: isothermal and adiabatic wall
 - ▶ Velocity: Dirichlet boundary condition
 - ▶ Temperature: Neumann (adiabatic) or Dirichlet (isothermal)
- ▶ Advection term \approx nearly as slipping wall
- ▶ Diffusion terms:
 - ▶ Neumann is directly replaced by the imposed flux,
 - ▶ Dirichlet: compute **jumps** based on imposed values
- ▶ The system is expressed in **conservative variables** $(\rho, \rho \mathbf{u}, \rho E)$
 - ▶ Fourier contribution

$$\nabla T = \frac{1}{\rho C_v} \left(\left(\frac{|\mathbf{u}|^2}{2} - \varepsilon + \frac{\ell}{\rho} \right) \nabla \rho - \sum u_i \nabla (\rho u_i) + \nabla \rho E \right)$$

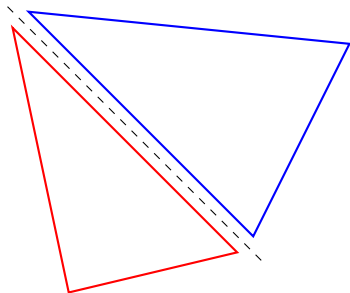
- ▶ How to define ρ and ρE on the wall?
 - ▶ locally switch back to primitive variables (nonlinearity within the lifting operator)

Implementation

- ▶ Discontinuous Galerkin methods are linear methods for linear problems
- ▶ Three steps:
 - ▶ Interpolate on quadrature points (values, gradient, lifting gradient)
 - ▶ Compute (numerical) flux
 - ▶ Project on degrees of freedom
- ▶ Three loops
 - ▶ Cells
 - ▶ Interior sides
 - ▶ Boundary sides
- ▶ One nonlinear step nested in two linear steps

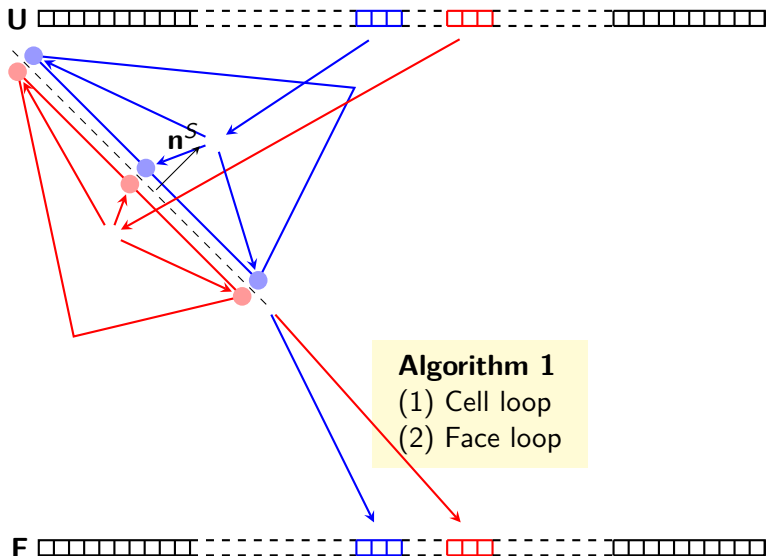
Implementation

U 

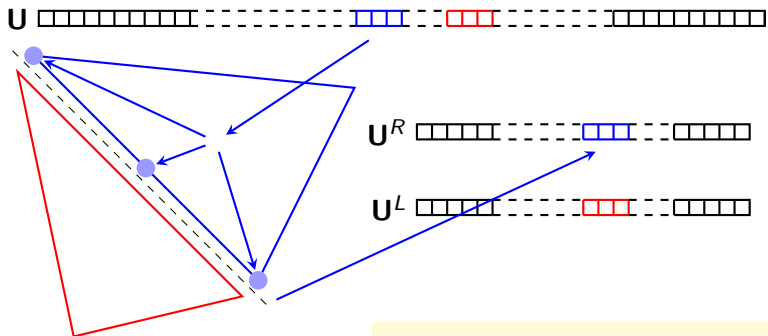


F 

Implementation



Implementation

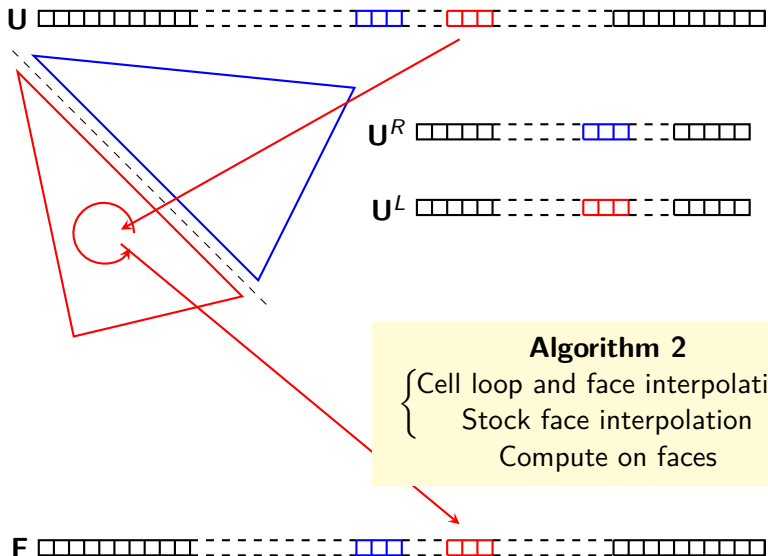


Algorithm 2

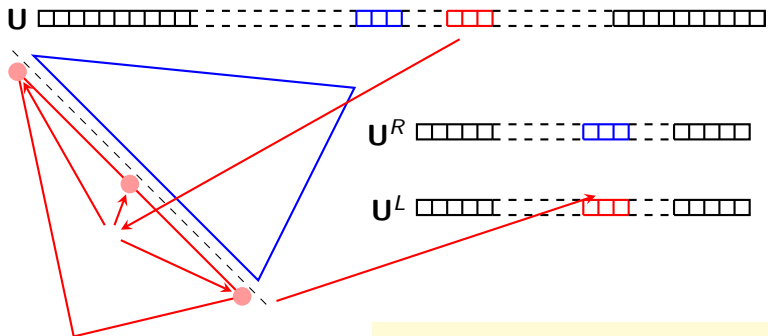
- { Cell loop and face interpolation
- Stock face interpolation
- Compute on faces



Implementation



Implementation

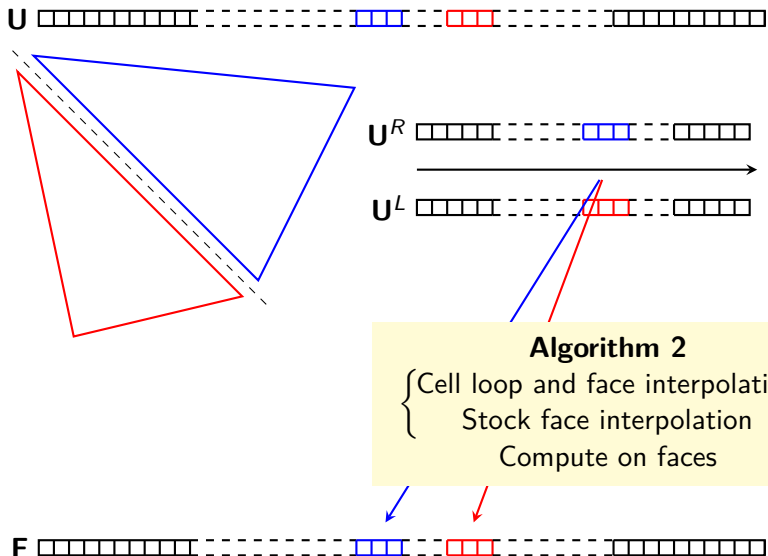


Algorithm 2

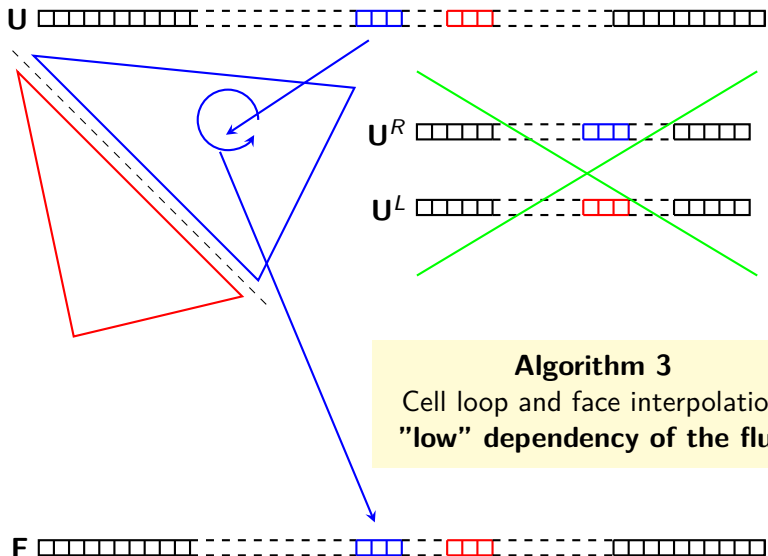
{ Cell loop and face interpolation
 Stock face interpolation
 Compute on faces



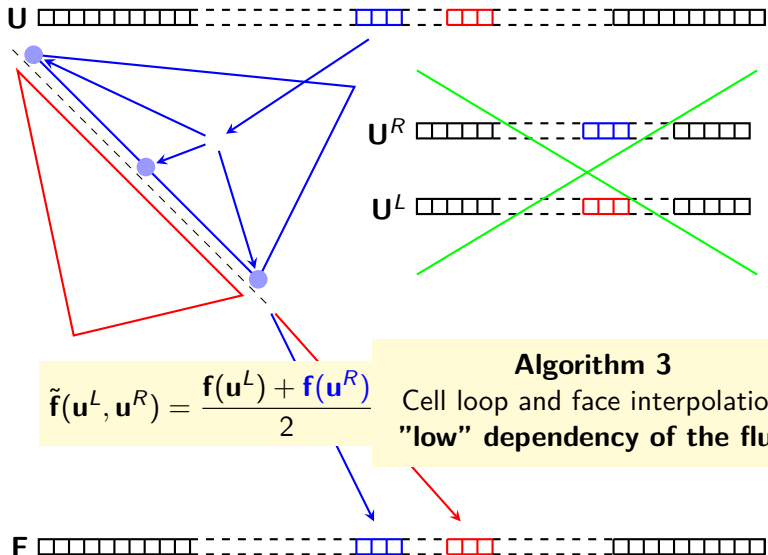
Implementation



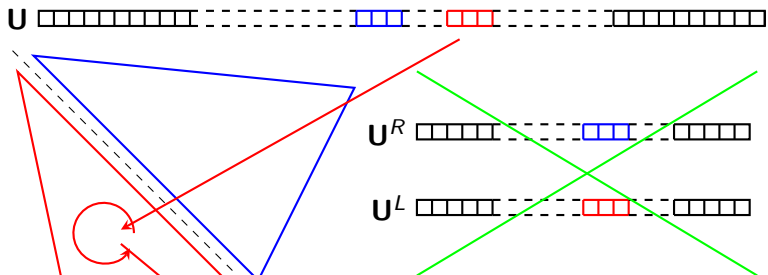
Implementation



Implementation



Implementation

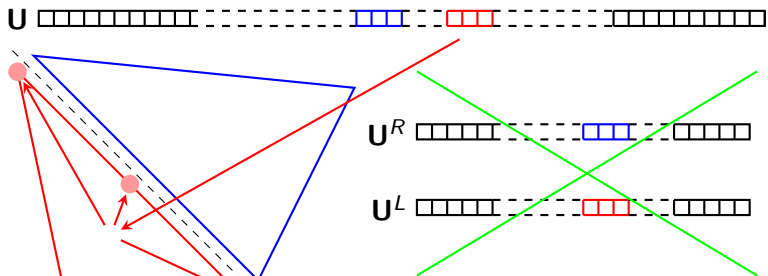


$$\tilde{f}(u^L, u^R) = \frac{f(u^L) + f(u^R)}{2}$$

Algorithm 3
Cell loop and face interpolation
"low" dependency of the flux



Implementation



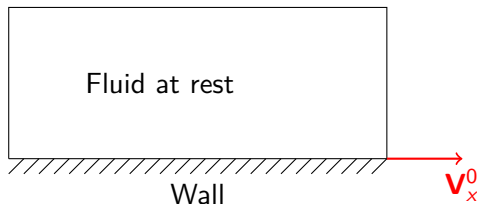
$$\tilde{f}(u^L, u^R) = \frac{f(u^L) + f(u^R)}{2}$$

Algorithm 3
Cell loop and face interpolation
"low" dependency of the flux



Validation test

Second Stokes problem



$$\mathbf{v}_x^0 = \sin(\omega t)$$

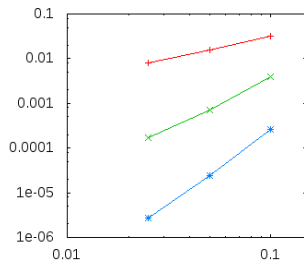
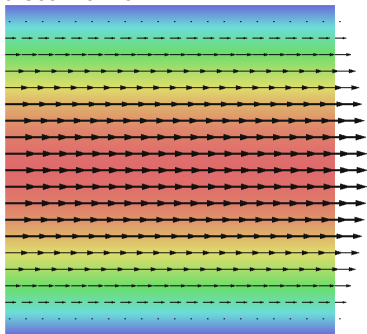
▶ Movie

$$\begin{aligned}
 & - \sum_{T \in \mathcal{T}_h} \int_T \nabla \varphi \cdot A \nabla \mathbf{U} \\
 & + \sum_{S \in \mathcal{S}_i} \int_{S_i} [\{ \{ A^T \nabla \varphi \} \} \cdot [\mathbf{U}] + \{ \{ A \nabla \mathbf{U} \} \} \cdot [\varphi]] \\
 & + \sum_{S \in \mathcal{S}_i} \int_{S_i} \eta \{ \{ A R^{S_i}([\mathbf{U}]) \} \} [\varphi] = 0
 \end{aligned}$$

Validation test

Poiseuille flows

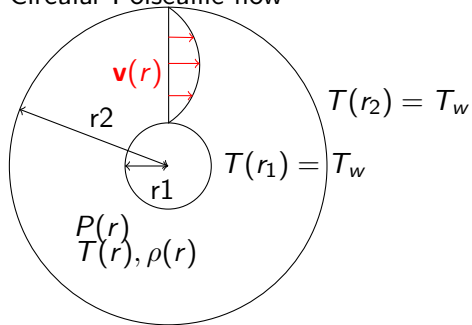
► Poiseuille flow



Validation test

Poiseuille flows

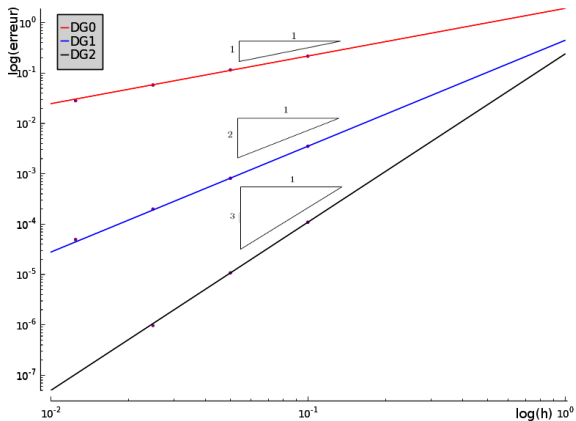
► Circular Poiseuille flow



Validation test

Poiseuille flows

► Circular Poiseuille flow



Validation test

Taylor-Green Vortex

- ▶ Three dimensional test
- ▶ Cube with periodic boundary conditions
- ▶ Low Mach flow with z -anisotropy
- ▶ No mechanism for maintaining turbulence

▶ [Movie](#)

Outline

Numerical scheme for compressible Navier-Stokes equations

Discontinuous Galerkin methods for low (but not zero) Mach flow

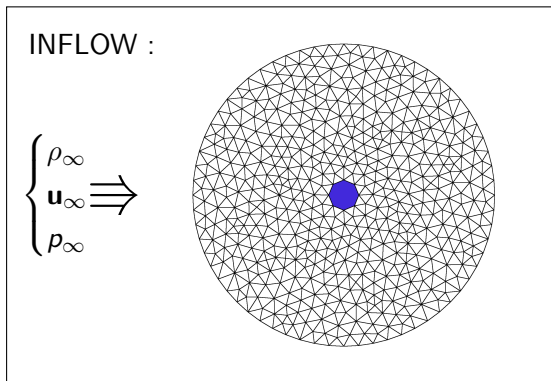
- Review of the steady case

- Problem in the unsteady case

- A new scheme stable for both steady and unsteady flow

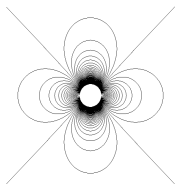
Application

A steady test case

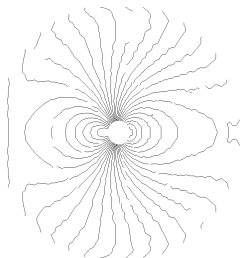


- ▶ Discontinuous Galerkin.
- ▶ High order discretisation.
- ▶ Unstructured Mesh.
- ▶ Roe Riemann Solver.

A steady test case



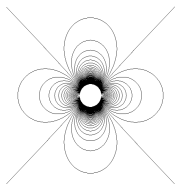
Incompressible exact



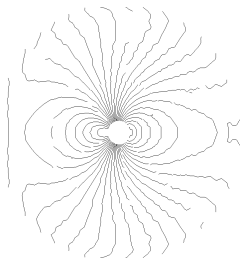
Roe, Quad

- ▶ The **compressible discrete** solution does not converge toward the **incompressible** one as the Mach number tends to zero on quadrangular meshes. (Here at $M = 10^{-3}$)

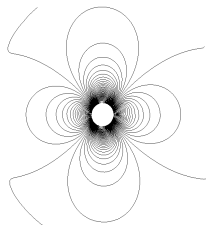
A steady test case



Incompressible exact



Roe, Quad



Roe, Tri

- ▶ The **compressible discrete** solution does not converge toward the **incompressible** one as the Mach number tends to zero on quadrangular meshes. (Here at $M = 10^{-3}$)
- ▶ H. Guillard, [On the behavior of upwind schemes in the low Mach number limit. IV: \$P_0\$ approximation on triangular and tetrahedral cells](#), *Computers & Fluids*, 2009, 38 (10).

Euler equations

Non-dimensional Euler equations

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{u}) = 0$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{M^2} \nabla p = 0$$

$$\frac{\partial \rho e}{\partial t} + \operatorname{div}(\rho e \mathbf{u} + p \mathbf{u}) = 0$$

$$p = (\gamma - 1) \left(\rho e - \frac{M^2}{2} \rho \|\mathbf{u}\|^2 \right)$$

Where the dimensionless variables are :

- ▶ ρ density.
- ▶ \mathbf{u} velocity vector.
- ▶ e total energy.
- ▶ p the pressure.
- ▶ $M = \frac{u_\infty}{a_\infty}$ Mach number.

One scale asymptotic expansion

Let's consider the system :

$$\partial_t \mathbf{u} + A(\mathbf{u}) \nabla \mathbf{u} + \frac{B(\mathbf{u})}{M^2} \nabla \mathbf{u} = 0$$

And expand the variables using a one scale **asymptotic development** in power of the Mach number :

$$\mathbf{u}(x, t; M) = \sum_{n=0}^N M^n \mathbf{u}^{(n)}(x, t) + O(M^N)$$

We want to compare the behaviour of the **continuous** and **discrete** system.

- ▶ B. Müller (1999). **Low Mach number asymptotics of the Navier-Stokes equations and numerical implications.**
- ▶ H. Guillard, & C. Viozat (1999). **On the behaviour of upwind schemes in the low Mach number limit.** Computers & Fluids

Comparison between continuous and discrete cases

- Continuous :

Order M^{-2} :

$$\nabla p^{(0)} = 0$$

Order M^{-1} :

$$\nabla p^{(1)} = 0$$

Order M^0 :

$$\nabla \cdot (\rho^{(0)} u^{(0)}) = 0$$

$$\nabla \cdot (\rho^{(0)} u^{(0)} u^{(0)}) + \nabla p^{(2)} = 0$$

$$\nabla \cdot (\rho^{(0)} H^{(0)} u^{(0)}) = 0$$

$$p^{(0)} = (\gamma - 1) \rho^{(0)} e^{(0)}$$

- Discrete using Roe scheme :

Order M^{-2} :

$$\sum p^{(0)} \mathbf{n} = 0$$

Order M^{-1} :

$$\frac{1}{2} \sum \frac{\Delta \bar{p}^{(0)}}{\bar{c}^{(0)}} = 0$$

$$\frac{1}{2} \sum \bar{p}^{(0)} \bar{c}^{(0)} \mathbf{n} \Delta \bar{U}^{(0)} + \sum p^{(1)} \mathbf{n} = 0$$

Order M^0 :

$$d_t \rho^{(0)} + \frac{1}{2} \sum \frac{\Delta p^{(1)}}{\bar{a}^{(0)}} = 0$$

Comparison between continuous and discrete cases

- Continuous :

Order M^{-2} :

$$\nabla p^{(0)} = 0$$

Order M^{-1} :

$$\nabla p^{(1)} = 0$$

Order M^0 :

$$\nabla \cdot (\rho^{(0)} u^{(0)}) = 0$$

$$\nabla \cdot (\rho^{(0)} u^{(0)} u^{(0)}) + \nabla p^{(2)} = 0$$

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$$\frac{1}{2} \sum \bar{p}^{(0)} \bar{c}^{(0)} \mathbf{n} \Delta \bar{U}^{(0)} + \sum p^{(1)} \mathbf{n} = 0$$

Order M^0 :

$$d_t \rho^{(0)} + \frac{1}{2} \sum \frac{\Delta p^{(1)}}{\bar{a}^{(0)}} = 0$$

Comparison between continuous and discrete cases

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$$\nabla \cdot (\rho^{(0)} u^{(0)}) = 0$$

$$\nabla \cdot (\rho^{(0)} u^{(0)} u^{(0)}) + \nabla p^{(2)} = 0$$

$$\nabla \cdot (\rho^{(0)} H^{(0)} u^{(0)}) = 0$$

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- Discrete using Roe scheme :

Order M^{-2} :

$$\sum p^{(0)} \mathbf{n} = 0$$

Order M^{-1} :

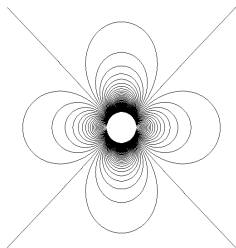
$$\frac{1}{2} \sum \frac{\Delta \bar{p}^{(0)}}{\bar{c}^{(0)}} = 0$$

$$\frac{1}{2} \sum \bar{p}^{(0)} \bar{c}^{(0)} \mathbf{n} \Delta \bar{U}^{(0)} + \sum p^{(1)} \mathbf{n} = 0$$

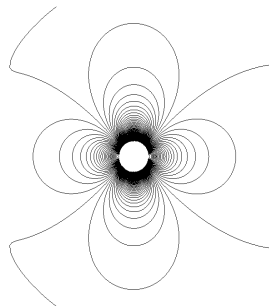
Order M^0 :

$$d_t \rho^{(0)} + \frac{1}{2} \sum \frac{\Delta p^{(1)}}{\bar{a}^{(0)}} = 0$$

Preconditioning methods



Incompressible exact



Compressible LM-Roe solver

Quad Mesh, $M = 10^{-3}$

- ▶ H. Guillard, & C. Viozat, *Computers & Fluids*. (1999)
- ▶ S. Dellacherie, *Journal of Computational Physics*. (2010)
- ▶ F. Rieper, *Journal of Computational Physics*. (2011)

Results

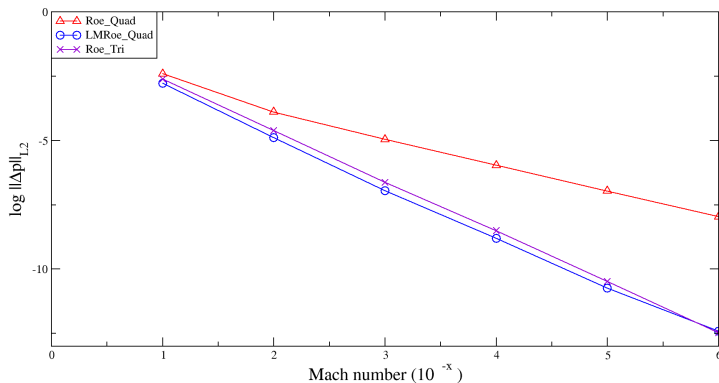
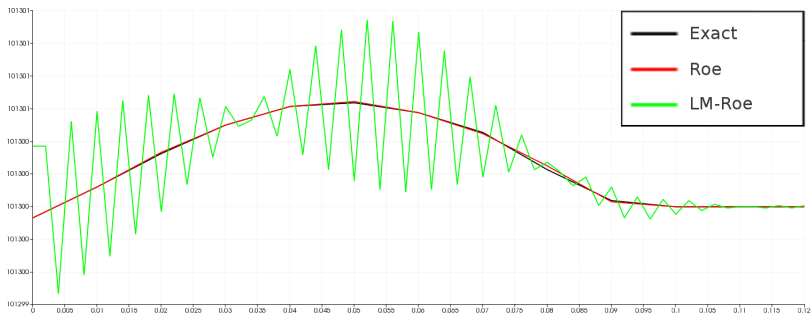


Figure: L2 Error for the pressure in terms of Mach number

What about higher order?

- ▶ Any of the higher order schemes work well with the cylinder test.
- ▶ Problems occur with e.g. flow around a NACA on quads
 - ▶ F. Bassi, C. De Bartolo, R. Hartmann and A. Nigro, [A discontinuous Galerkin method for inviscid low Mach number flows](#), Journal of Computational Physics, 2009.
 - ▶ A. Nigro, S. Renda, C. De Bartolo, R. Hartmann and F. Bassi [A high-order accurate discontinuous Galerkin finite element method for laminar low Mach number flows](#) International Journal for Numerical Methods in Fluids, 2013.

A unsteady test case



Propagating wave with second order spatial discretisation

Moguen, Y. *et al.* (2013). [Pressure-velocity coupling for unsteady low Mach number flow simulations: An improvement of the AUSM+ scheme](#) *Journal of Computational and Applied Mathematics*

Two time scales asymptotic development

Let consider a second time scale, the **acoustic time scale** :

$$\tau = t/M.$$

Introducing this scale in the development gives :

$$\mathbf{u}(x, t, \tau; M) = \sum_{n=0}^N M^n \mathbf{u}^{(n)}(x, t, \tau) + O(M^N)$$

The time derivative at constant x and M yields :

$$\frac{\partial}{\partial \tilde{t}} = \frac{1}{M} \frac{\partial}{\partial \tau} + \frac{\partial}{\partial t}$$

Continuous two time scales asymptotic development

Order M^{-1} momentum and order M^0 energy equations

$$\begin{cases} \partial_\tau \rho^{(0)} \mathbf{u}^{(0)} + \nabla p^{(1)} = 0 \\ \partial_\tau p^{(1)} + a^{(0)2} \operatorname{div}(\rho^{(0)} \mathbf{u}^{(0)}) = -d_t p^{(0)} \end{cases}$$

We will note $\rho^{(0)} \mathbf{u}^{(0)} = \mathbf{u}$, $p^{(1)} = p$ and $a^{(0)} = a$.

First order wave equation

$$\begin{cases} \partial_\tau \mathbf{u} + \nabla p = 0 \\ \partial_\tau p + a^2 \operatorname{div}(\mathbf{u}) = -d_t p^{(0)} \end{cases}$$

Discrete two time scales asymptotic development

Roe first order discrete wave equation

$$\partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + \frac{a}{2} \sum \Delta_{il} \mathbf{u} = 0$$

$$\partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 = 0$$

Diffusion given by classical upwind flux for the wave system.
Diffusion is a SPD matrix.

- ▶ E. Burman, Alexandre Ern, Miguel Angel Fernandez. [Explicit Runge–Kutta schemes and finite elements with symmetric stabilization for first-order linear PDE systems](#), SIAM Journal on Numerical Analysis, 2010, **48** (6),

Discrete two time scales asymptotic development

Roe first order discrete wave equation

$$\begin{aligned} \partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + \frac{a}{2} \sum \Delta_{il} \mathbf{u} &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 &= 0 \end{aligned}$$

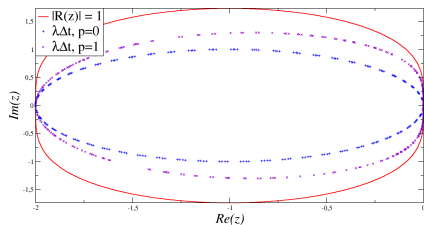
Modified Roe first order discrete wave equation

$$\begin{aligned} \partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + 0 &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 &= 0 \end{aligned}$$

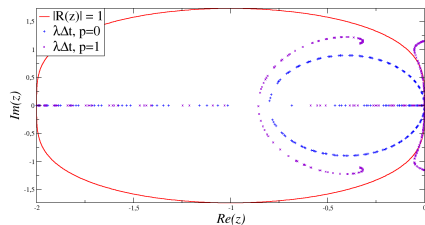
Von-Neumann stability analysis for the wave equation

$$d_{\tau} \mathbf{U} + A(\mathbf{U}) = 0, \quad \mathbf{U}_{n+1} = R(A\Delta\tau)\mathbf{U}_n$$

$$z = \lambda_{\max}\Delta\tau : |R(z)| \leq 1$$



Roe scheme Eigenvalues

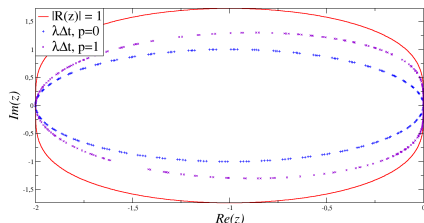


LMRoe scheme Eigenvalues

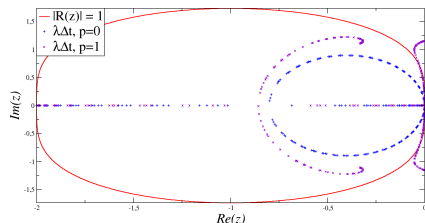
Von-Neumann stability analysis for the wave equation

$$d_{\tau} \mathbf{U} + A(\mathbf{U}) = 0, \quad \mathbf{U}_{n+1} = R(A\Delta\tau)\mathbf{U}_n$$

$$z = \lambda_{\max}\Delta\tau : |R(z)| \leq 1$$



Roe scheme Eigenvalues



LMRoe scheme Eigenvalues

The LM-Roe scheme is stable for a **CFL condition** of order 10^{-3} .

Modifying dissipation

Roe : not accurate in steady case

$$\begin{aligned} \partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + \frac{a}{2} \sum \Delta_{il} \mathbf{u} &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 &= 0 \end{aligned}$$

Modifying dissipation

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Modified Roe : not stable in unsteady case

$$\begin{aligned} \partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + 0 &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 &= 0 \end{aligned}$$

Modifying dissipation

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Modified Roe : not stable in unsteady case

$$\begin{aligned}\partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + 0 + 0 &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + 0 &= 0\end{aligned}$$

A new set of dissipative terms

$$\begin{aligned}\partial_\tau \mathbf{u} + \frac{1}{2} \sum p_l \mathbf{n} + \frac{1}{2} \sum \Delta_{il} p + 0 &= 0 \\ \partial_\tau p + \frac{a^2}{2} \sum \mathbf{u}_l \cdot \mathbf{n} + \frac{a}{2} \sum \Delta_{il} p + \frac{a^2}{2} \sum \Delta_{il} \mathbf{u} &= 0\end{aligned}$$

Stability analysis of our new scheme

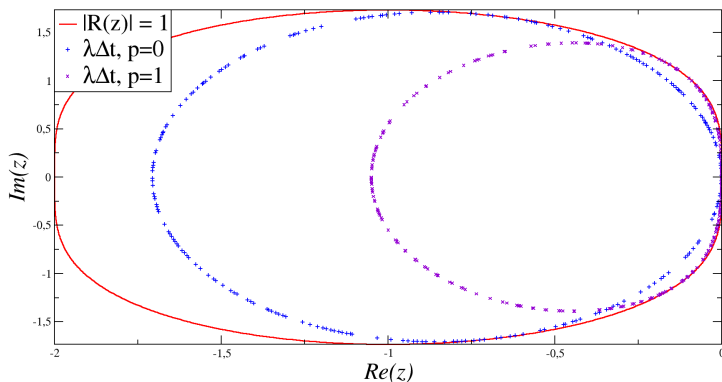


Figure: Stability of the new scheme applied to the first order wave equation

Convergence for the wave equation

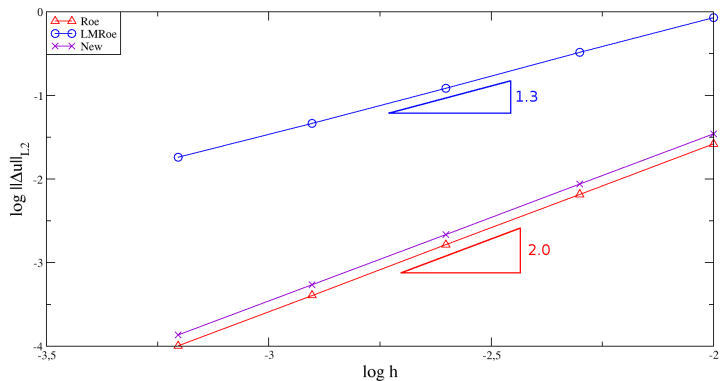


Figure: Convergence for second order spatial discretisation

Back to the Euler system

- Momentum :

$$\frac{1}{2M^2} \sum \rho \mathbf{n} +$$

$$\frac{1}{2} \sum \left(\rho \mathbf{u} \cdot \mathbf{n} + \frac{(\bar{U} \mathbf{n} + \bar{\mathbf{u}})}{\bar{a}} \Delta p + \bar{\rho} \bar{a} \Delta U \mathbf{n} \right) +$$

$$\frac{M}{2} \sum \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{\mathbf{u}} \Delta U = 0$$

- Energy :

$$\frac{1}{2M} \sum \frac{\bar{h}}{\bar{a}} \Delta P +$$

$$\frac{1}{2} \sum ((\rho e + p) \mathbf{u} \cdot \mathbf{n}) +$$

$$\frac{M}{2} \sum \bar{\rho} \bar{a} \bar{U} \Delta U + \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{h} \Delta U = 0$$

Back to the Euler system

- Momentum :

$$\begin{aligned} & \frac{1}{2M^2} \sum \rho \mathbf{n} + \\ & \frac{1}{2} \sum \left(\rho \mathbf{u} \mathbf{u} \cdot \mathbf{n} + \frac{(\bar{U} \mathbf{n} + \bar{\mathbf{u}})}{\bar{a}} \Delta p + \bar{\rho} \bar{a} \Delta U \mathbf{n} \right) + \\ & \frac{M}{2} \sum \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{\mathbf{u}} \Delta U = 0 \end{aligned}$$

- Energy :

$$\begin{aligned} & \frac{1}{2M} \sum \frac{\bar{h}}{\bar{a}} \Delta P + \\ & \frac{1}{2} \sum ((\rho e + p) \mathbf{u} \cdot \mathbf{n}) + \\ & \frac{M}{2} \sum \bar{\rho} \bar{a} \bar{U} \Delta U + \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{h} \Delta U = 0 \end{aligned}$$

Back to the Euler system

- Momentum :

$$\begin{aligned} & \frac{1}{2M^2} \sum (\rho \mathbf{n} + \Delta P \mathbf{n}) + \\ & \frac{1}{2} \sum \left(\rho \mathbf{u} \mathbf{u} \cdot \mathbf{n} + \frac{(\bar{U} \mathbf{n} + \bar{\mathbf{u}})}{\bar{a}} \Delta p + \bar{\rho} \bar{a} \Delta U \mathbf{n} \right) + \\ & \frac{M}{2} \sum \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{\mathbf{u}} \Delta U = 0 \end{aligned}$$

- Energy :

$$\begin{aligned} & \frac{1}{2M} \sum \frac{\bar{h}}{\bar{a}} \Delta P + \\ & \frac{1}{2} \sum ((\rho e + p) \mathbf{u} \cdot \mathbf{n} - \bar{a}^2 \bar{\rho} \Delta U) + \\ & \frac{M}{2} \sum \bar{\rho} \bar{a} \bar{U} \Delta U + \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{h} \Delta U = 0 \end{aligned}$$

Steady test case

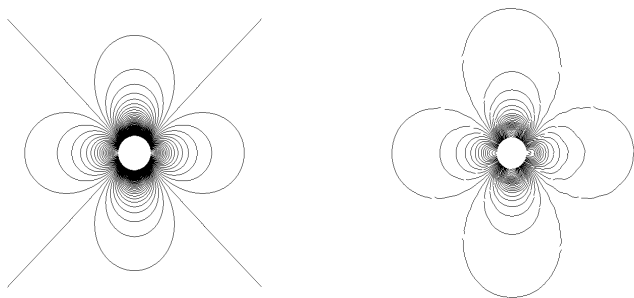


Figure: **Incompressible** solution and **Compressible** new scheme
($M = 10^{-3}$)

Convergence

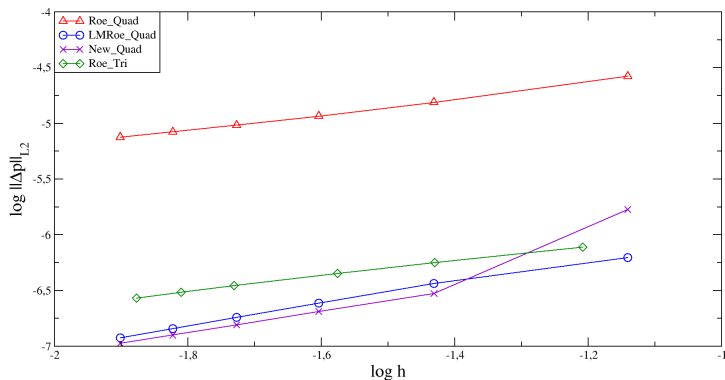


Figure: Convergence for first order spatial discretisation at Mach = 10^{-3}

Unsteady test case

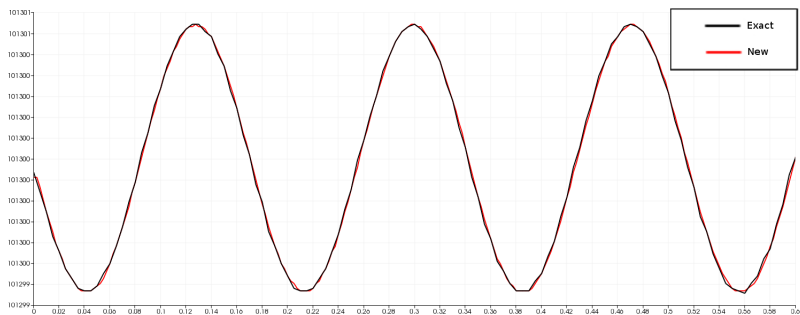


Figure: Propagating wave with second order spatial discretisation

Convergence

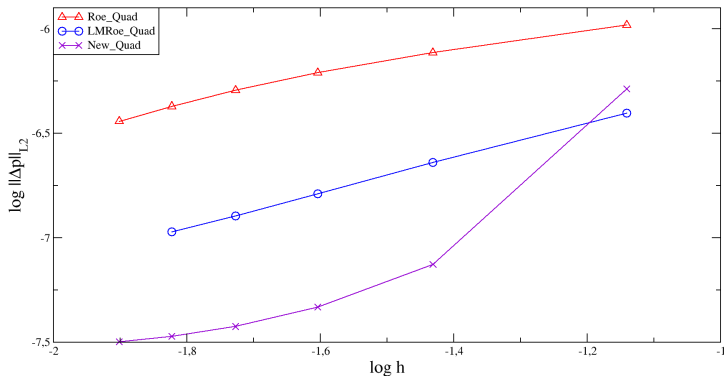


Figure: Convergence for spatial discretisation of order 2 at Mach = 10^{-3}

Remark on the wall boundary condition

$$U_l = \begin{pmatrix} \rho \\ \rho \mathbf{u}_l \\ \rho E \end{pmatrix} \quad U_r = \begin{pmatrix} \rho \\ \rho \mathbf{u}_r \\ \rho E \end{pmatrix}$$

$$\mathbf{u}_r = \mathbf{u}_l - 2(\mathbf{u}_l \cdot \mathbf{n})\mathbf{n} \quad \Delta \rho = \Delta P = 0$$

With classical schemes

$$F_{wall}(U_l, U_r) = \begin{pmatrix} 0 \\ p^* \mathbf{n} \\ 0 \end{pmatrix} \quad p^* = p_l - 2 \frac{(\mathbf{u}_l \cdot \mathbf{n})}{\lambda}$$

Remark on the wall boundary condition

$$U_l = \begin{pmatrix} \rho \\ \rho \mathbf{u}_l \\ \rho E \end{pmatrix} \quad U_r = \begin{pmatrix} \rho \\ \rho \mathbf{u}_r \\ \rho E \end{pmatrix}$$

$$\mathbf{u}_r = \mathbf{u}_l - 2(\mathbf{u}_l \cdot \mathbf{n})\mathbf{n} \quad \Delta \rho = \Delta P = 0$$

With the new solver: energy equation :

$$\frac{1}{2M^2} \sum p \mathbf{n} + \frac{1}{2} \sum \rho \mathbf{u} \mathbf{u} \cdot \mathbf{n} + \frac{M}{2} \sum \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{\mathbf{u}} \Delta U = 0$$

$$\frac{1}{2} \sum (\rho e + p) \mathbf{u} \cdot \mathbf{n} - \bar{a}^2 \bar{\rho} \Delta U + \frac{M}{2} \sum \bar{\rho} \bar{a} \bar{U} \Delta U + \bar{\rho} \frac{\bar{U}}{\bar{a}} \bar{h} \Delta U = 0$$

$$F_{wall}(U_l, U_r) = \begin{pmatrix} 0 \\ p^* \mathbf{n} \\ X \end{pmatrix} \Rightarrow \begin{pmatrix} 0 \\ p^* \mathbf{n} \\ 0 \end{pmatrix}$$

Conclusion on low Mach number flows

- ▶ Classical low Mach solver **are not** stable for high order acoustic calculation.
- ▶ A stable and accurate low Mach scheme for **both steady and unsteady** flow computation.
 - ▶ Stabilization of the incompressible system is **not achieved by centering the pressure**
 - ▶ Stabilization of the wave system is **not symmetric** .
- ▶ Higher order: ?
 - ▶ E. Burman, A. Ern, I.Mozolevski and B. Stamm. **The symmetric discontinuous Galerkin method does not need stabilization in 1D for polynomial orders $p \geq 2$** . Comptes Rendus Mathematique, 2007.

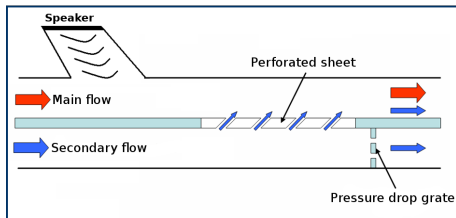
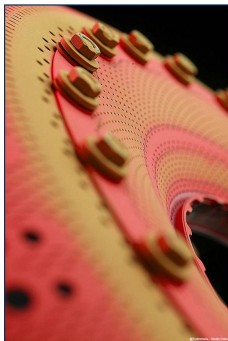
Outline

Numerical scheme for compressible Navier-Stokes equations

Discontinuous Galerkin methods for low (but not zero) Mach flow

Application

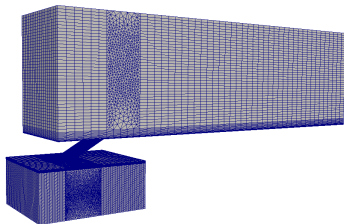
Context



Low (**NOT zero**) Mach flow, with acoustic

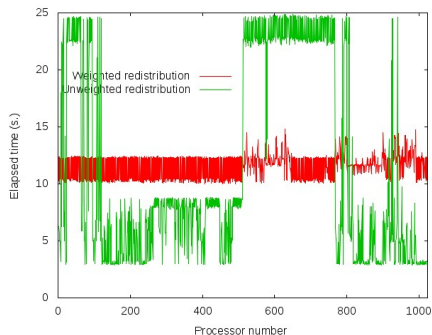
Numerical result

- ▶ Around 500 000 degrees of freedom
- ▶ Hybrid mesh



▶ [Movie](#)

A remark on weighted redistribution on hybrid meshes



| | | | |
|--------------------|----|-------------------|----|
| <i>Tetrahedron</i> | 3 | <i>Pyramid</i> | 9 |
| <i>Prism</i> | 10 | <i>Hexahedron</i> | 29 |

Why I will keep on on discontinuous Galerkin

- ▶ A rich topic of numerical analysis
 - ▶ Derive stable schemes in different asymptotics
- ▶ MARSU: Multigrid AggRegated on unStrUctured meshes
 - ▶ Fully matrix-free implementation
 - ▶ Derive aggregation strategies depending on the Re or Ma .
- ▶ HONHA: High Order Numerical methods on Heterogeneous Architectures
 - ▶ Strong memory locality

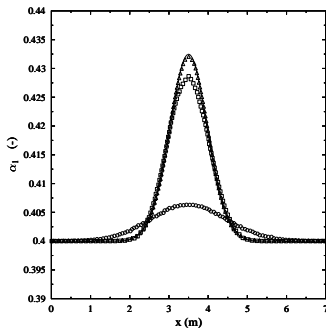
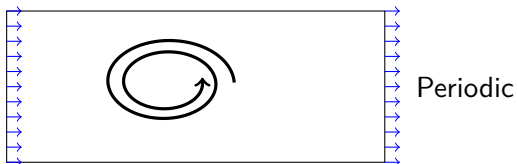
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 - ▶ E. Burman, A. Ern, I. Mozolevski and B. Stamm. [The symmetric discontinuous Galerkin method does not need stabilization in 1D for polynomial orders \$p \geq 2\$.](#)
- ▶ MARSU: [Multigrid Aggregated on unstructured meshes](#)
 - ▶ Fully matrix-free implementation
 - ▶ F. Bassi, L. Botti, A. Colombo, D. A. Di Pietro, and P. Tesini, [On the flexibility of agglomeration based physical space discontinuous Galerkin discretizations](#)
 - ▶ Derive aggregation strategies depending on the Re or Ma .
 - ▶ J.J.W. van der Vegt and S. Rhebergen, [h-p-multigrid as smoother algorithm for higher order discontinuous Galerkin discretizations of advection dominated flows. Part I. Multilevel Analysis](#)
- ▶ HONHA: [High Order Numerical methods on Heterogeneous Architectures](#)
 - ▶ Strong memory locality
 - ▶ Klöckner, A., Warburton, T., Bridge, J., Hesthaven, J. S. [Nodal discontinuous Galerkin methods on graphics processors.](#)

Thanks to

- ▶ S. Delmas, R. Manceau, P. Bruel
- ▶ H. Belkhayat (**looking for a PhD position**)
- ▶ E. Martin, F. Renac from ONERA, the french aerospace lab.

Advection of a vortex



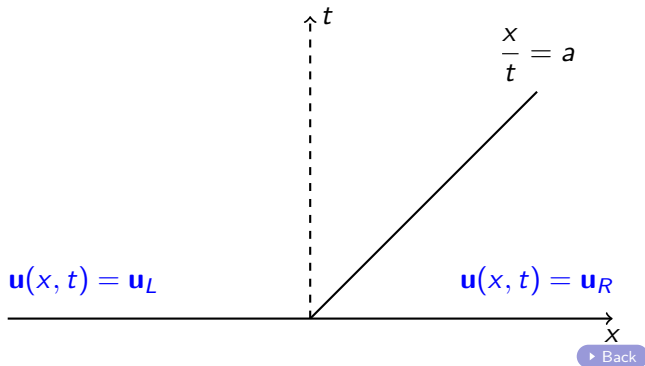
▶ Movie

▶ Back

Riemann problem

$$\partial_t \mathbf{u} + a \partial_x \mathbf{u} = 0$$

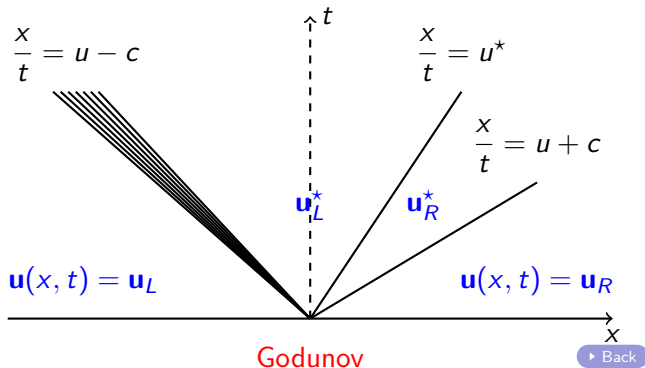
$$\mathbf{u}(x, 0) = \begin{cases} u_L & \text{if } x < 0 \\ u_R & \text{if } x > 0 \end{cases}$$



Riemann problem

$$\partial_t \mathbf{u} + \partial_x \mathbf{F}(\mathbf{u}) = 0$$

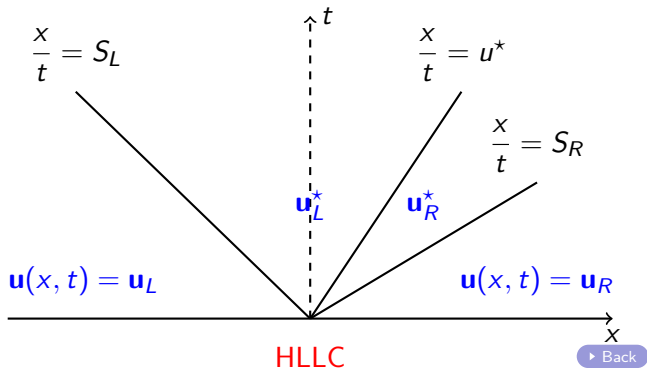
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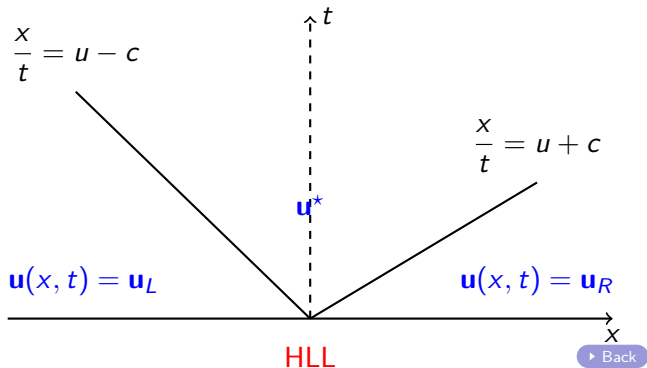
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